1	Analysis of three-dimensional slope stability combined with rainfall
2	and earthquake
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8	Abstract

9 In the current context of global climate change, geohazards such as earthquakes and 10 extreme rainfall pose a serious threat to regional stability. We investigate a three-11 dimensional(3D) slope dynamic model under earthquake action, derive the calculation 12 of seepage force and the normal stress expression of slip surface under seepage and 13 earthquake, and propose a rigorous overall analysis method to solve the safety factor of 14 slopes subjected to combined with rainfall and earthquake. The accuracy and reliability 15 of the method is verified by two classical examples. Finally, the effects of soil permeability coefficient, porosity and saturation on slope stability under rainfall in a 16 17 project located in the Three Gorges Reservoir Area are analyzed. The safety evolution 18 of the slope combined with both rainfall and earthquake is also studied. The results 19 indicate that porosity has a greater impact on the safety factor under rainfall conditions, 20 while the influence of permeability coefficient and saturation is relatively small. With 21 the increase of horizontal seismic coefficient, the safety factor of the slope decreases

significantly. The influence of earthquake on slope stability is significantly greater than
that of rainfall. The corresponding safety factor when the vertical seismic action is
vertically downward is smaller than that when it is vertically upward. When considering
both horizontal and vertical seismic effects, slope stability is lower.

26 Keywords

27 Three-dimensional slopes; Rainfall; Earthquake; Stability analysis

1 Introduction

29 Rainfall-induced landslides are caused by the infiltration of precipitation into the 30 ground surface, leading to an increase in pore water pressure, hence reducing the 31 effective stress and shear strength of the soil. Sustained rainfall or heavy rainfall events 32 can significantly increase the risk of slope instability, especially in those areas with 33 loose, poorly drained soils. Several landslides in the Three Gorges reservoir area have 34 been triggered by rainfall (Yin et al., 2012; Sun et al., 2016b). Earthquakes, as another 35 key factor, impose additional dynamic loads on slopes through ground shaking, which 36 may lead to instability of otherwise stable slopes. In addition, earthquake-induced 37 landslides tend to be more destructive because they often occur without warning. Due 38 to completely different destabilization mechanisms, studies of landslides induced by these two factors are often carried out separately. In some cases, rainfall and 39 40 earthquakes may act together on slopes. And earthquake-induced landslides may occur 41 more frequently during the rainy season, when the soil is saturated with water and its 42 resistance to earthquakes is reduced. Further research is necessary to investigate the 43 stability of slopes under the combined influence of rainfall and earthquake (David, 2000;
44 Iverson, 2000; Sassa et al., 2010).

45 At present, the main research methods for slope stability include the limit equilibrium method (Bishop, 1955; Morgenstern and Price, 1965; Spencer, 1967), limit 46 47 analysis (Farzaneh et al., 2008; Michalowski, 1995; Qin and Chian, 2018; Zhou et al., 48 2017), Finite Element Method (Griffiths and Lane, 1999; Ishii et al., 2012) et al. There 49 have been numerous studies and findings regarding the stability assessment of 3D 50 slopes. However, most of these methods are based on extended 3D equilibrium analysis 51 techniques (Hungr, 1987; Zhang, 1988; Chen, 2001; Cheng and Yip, 2007), which 52 rarely strictly adhere to the six equilibrium conditions. Additionally, these approaches 53 often introduce a significant number of assumptions that limit their practical 54 engineering applications. The strict 3D limit equilibrium method proposed by Zheng 55 (2007) is an overall analysis approach based on the natural form of slip surface stress 56 distribution and approximation through shard interpolation. Sun et al. (2016a, 2017) 57 combined Morgenstern-Price and Bell global analysis method to analyze the stability 58 of reservoir bank slope, applying this method to the Three Gorges reservoir area. 59 Rahardjo et al. (2010) studied the effect of groundwater table position, rainfall intensities, and soil properties in affecting slope stability using the numerical analyses. 60 Some of the defects inherent in the two-dimensional(2D) limit equilibrium method 61 62 remain unresolved, and some of them are even amplified in the complex 3D analysis, which has a certain impact on the accuracy of the 3D slope stability evaluation. For the 63

64	limit analysis method, it is still difficult to establish the velocity field of the motion
65	permit in 3D space. And numerical methods often suffer from two problems: the
66	determination criteria of the critical state of the slope and the determination of the
67	location of the critical sliding surface. Compared with a single traditional analysis
68	method, the mutual integration of several method theories has also been gradually
69	developed, so as to give full play to the advantages of their respective methods and
70	better used in slope stability analysis, such as the finite element limit analysis method
71	(Ali et al., 2016; Lim et al., 2017; Zhou and Qin, 2022).
72	As a common geological hazard in seismic zones, earthquake-triggered landslides
73	have been extensively investigated by numerous scholars (Sepúlveda et al., 2005;
74	Chang et al., 2012; Jibson and Harp, 2016; Marc et al., 2017; Salinas-Jasso et al., 2019).
75	At present, the stability analysis method of 3D slope is not mature, and the research on
76	the dynamic stability of 3D slope is even more scarce. The quasi-static method (Liu et
77	al., 2001) introduces coefficients (k_v and k_h) that reflect dynamic action, thereby
78	transforming a dynamic problem into a static one for easier resolution. This approach
79	avoids the complexities associated with dynamic analysis and has become widely used
80	in engineering. Horizontal seismic effects are often a significant consideration in slope
81	stability analysis, however, some research (Chopra, 1966; Lew, 1991; Ling et al., 1999;
82	Shukha and Baker, 2008) confirms that the vertical component of seismic forces should
83	also be given great attention. Wang and Xu (2005) employed the dynamic finite element
84	method to investigate the seismic response characteristics of various components in a

85 3D high slope yet failed to determine the safety factor. Guo et al. (2011) obtained the time history curve of slope safety factor during earthquake using vector sum method in 86 87 2D situations. Cao et al. (2019) studied the seismic response and dynamic failure mode 88 of the slope subjected to earthquake and rainfall by two model tests. In summary, 89 although previous research have provided significant insights into landslides triggered 90 by earthquakes, there remain inadequacies in fully considering the vertical effects of seismic activity, extending analysis from 2D to 3D, and comprehensively integrating 91 92 the effects of both earthquakes and rainfall. 93 Most studies only consider the role of a single factor in seepage or earthquake, neglecting the slope stability analysis under combined working conditions. Therefore, 94 95 analyzing the change law of safety factors for slopes during seepage and seismic action 96 is of great practical value in guiding slope support design and evaluating slope stability. 97 In this paper, a 3D rigorous slice-free method considering seepage and seismic forces 98 to solve the safety factor of bank slopes is proposed. The proposed method strictly

100 other redundant assumptions.

99

101 **2** Rise of phreatic surface and calculation of seepage force with rainfall

satisfies the force balance and moment balance in three directions, without introducing

102 infiltration in the soil column

103 The phreatic surface is the interface between the saturated and unsaturated zones 104 within the slope. Physical and mechanical parameters of the sliding below the phreatic 105 surface adopt saturated, while above the phreatic surface adopt naturally. A differential

soil slice is taken from the slip surface to the slope surface in the landslide body is 106 107 shown in Fig. 1. z(t) is the rise of phreatic surface after rainfall infiltration, which 108 refers to Conte and Troncone (2017), the height of the soil slice below the phreatic line on *BE* and *CF* side are respectively z_1 and z_2 . It is assumed that rainfall is consistent 109 110 with groundwater movement and that the slope surface is well drained and free of 111 standing water. Regardless of rainfall intensity, runoff will form if it is greater than the 112 infiltration capacity. The height of rise of the phreatic surface within the slope after the 113 rainfall is

114
$$z(t) = \frac{z_r}{n(1-S_r)} \exp\left[-\frac{k}{ds\cos\alpha}i\cos\delta(t-t_0)\right]$$
(1)

where z_r is the volume of water (per unit area) that infiltrates the slope due to a 115 116 rainfall event with a specified duration, n is porosity, k is permeability coefficient, S_r is saturation, i is the hydraulic gradient ($i = \sin \beta$), δ is the angle between the slope 117 surface and the horizontal plane, α is the angle between the sliding surface BC of the 118 119 differential soil slice and the horizontal plane, β is the angle between the phreatic line and the horizontal plane, ds is the length of the sliding surface BC of the differential 120 121 soil slice, t is time, and t_0 is the initial moment. As a further simplification, it is 122 assumed that both n and S_r are constant.





Fig. 1 Relationship between rainfall and groundwater level





126

Fig. 2 Calculation sketch of forces acting on the differential soil slice



127

Fig. 3 Calculation sketch of hydraulic head

The load on the soil slice is shown in Fig. 2. dW_1 and dW_2 are the gravity of the differential soil slice above and below the phreatic line. The resultant hydrostatic force of the boundary *AB*, *CD*, and *BC* are F_1 , F_2 , and F_3 respectively. *N* is the contact pressure (effective pressure) between the soil particles, and *T* is the sliding resistance force. h_u and h_w are the height of the soil slice above and below the phreatic line respectively.

According to the flow properties of the phreatic line perpendicular to the equipotential line, the surrounding hydrostatic pressures F_1 , F_2 , and F_3 on the boundary *CF*, *BE*, and *BC* can be determined. As shown in Fig. 3, *BB*₁ and *CC*₁ are perpendicular to the phreatic line, then make B_1B_2 perpendicular to *AB*, and C_1C_2 perpendicular to *CD*. According to the geometric relationship, the hydrostatic pressure resultant forces at the boundary *CF* and *BE* are

141
$$F_{1} = \frac{1}{2} \gamma_{w} z_{1}^{2} \cos^{2} \beta, F_{2} = \frac{1}{2} \gamma_{w} z_{2}^{2} \cos^{2} \beta$$
(2)

142 γ_w is the unit weight of the water. Let $h_w = \frac{1}{2}(z_1 + z_2)$, the hydrostatic pressure

resultant force on the slip surface *BC* is

144
$$F_3 = \frac{1}{2} \gamma_w (z_1 + z_2) ds \cos^2 \beta = \gamma_w h_w ds \cos^2 \beta$$
(3)

145 The components of F_3 in the horizontal and vertical directions are

146
$$U_x = \gamma_w h_w ds \cos^2 \beta \cos \alpha, \quad U_y = \gamma_w h_w ds \cos^2 \beta \sin \alpha \tag{4}$$

147 The gravity of water in differential soil slice is

148
$$dW_{2w} = \gamma_w h_w ds \cos \alpha \tag{5}$$

The permeability pressure is a pair of balancing forces with the water weight in a differential soil slice and the hydrostatic pressure around it (Zheng et al., 2004). Therefore, the weight of water in the differential soil slice and the surrounding hydrostatic pressure can be replaced by a seepage force. The force diagram in Fig. 2 can be replaced by Fig. 4. dW'_2 represents the effective unit weight of the soil below the phreatic line and dW_D is the seepage force.





Fig. 4 Simplified force diagram on a differential soil slice

157 The horizontal and vertical component of the seepage force
$$dW_3$$
 are
158 $dW_{Dx} = F_1 - F_2 + U_x = \gamma_w h_w cos^2 \beta(z_1 - z_2 + dssin\alpha)$ (6)
159 $dW_{Dy} = dW_{2w} - U_y = \gamma_w h_w dscos\alpha sin^2 \beta$ (7)
160 According to geometric relation
161 $z_1 - z_2 + dssin\alpha = dscos\alpha \tan \beta$ (8)
162 Therefore, the seepage force is
163 $dW_D = \gamma_w h_w dscos\alpha \sin \beta$ (9)
164 The direction of seepage force is consistent with groundwater flow. The direction
165 of groundwater flow within the sliding soil mass is determined by the inclination of the
166 phreatic surface in each differential soil slice. As shown in Fig. 4, the flow direction of
167 groundwater is oriented at an angle β relative to the horizontal plane.
168 **3 A global analysis method for slope stability under seepage and**

169 earthquake

3.1 Overall system of equilibrium equations

- 171 As shown in Fig. 5, taking the whole sliding body Ω as the research object, and
- S is a potential slip surface.



Fig. 5 A 2D schematic plot for force system in/on the sliding body

175 dS is a differential element on the sliding surface S. The normal force on a 176 differential element dS at point r is $\sigma n dS$, the resultant shear force is $\tau s dS$, n is 177 the unit normal vector at position vector r on S and pointing to the inside of the sliding 178 body Ω ; s is the unit tangent vector at position vector r on S and opposed to the 179 sliding direction of the sliding body Ω , so the reaction on dS is:

$$df = (\sigma n + \tau s) dS \tag{10}$$

$$d\boldsymbol{m}_{A} = \Delta \boldsymbol{r}_{A} \times d\boldsymbol{f} \tag{11}$$

182 Here, $\Delta \mathbf{r}_A = \mathbf{r} - \mathbf{r}_A$, \mathbf{r} is the position vector of dS, \mathbf{r}_A is the position vector for any 183 given reference point A, "×" represents vector multiplication.

184 f_{ext} is the resultant external force vector, including external loads such as gravity, 185 seepage force, seismic force, et al.; m_{ext} denotes the moment f_{ext} concerning r_A . To 186 integrate over the entire sliding surface dS:

187
$$\iint_{s} df + f_{ext} = \mathbf{0}$$
(12)

188
$$\iint_{s} d\boldsymbol{m}_{A} + \boldsymbol{m}_{ext} = \boldsymbol{0}$$
(13)

189 According to Mohr-Coulomb criterion,

190
$$\tau = \frac{1}{F_s} \left[c' + f'(\sigma - u) \right] = \frac{1}{F_s} \left(c_w + f'\sigma \right)$$
(14)

Here, F_s is the safety factor, c' and f' are the effective stress shear strength parameters, c' is cohesion, f' corresponds to the tangent of the friction angle, u is the pore pressure; c_w is defined as

$$c_w \equiv c' - f'u \tag{15}$$

195 Order,

196
$$\mathbf{n}' = \begin{pmatrix} \mathbf{n} \\ \Delta \mathbf{r}_A \times \mathbf{n} \end{pmatrix}, \quad \mathbf{s}' = \begin{pmatrix} \mathbf{s} \\ \Delta \mathbf{r}_A \times \mathbf{s} \end{pmatrix}, \quad \mathbf{f}_m = \begin{pmatrix} \mathbf{f}_{ext} \\ \mathbf{m}_{ext} \end{pmatrix}$$
 (16)

197 Substituting equations (10), (11), and (14) into equations (12) and (13), and 198 merging into a more compact form:

199
$$F_{s}\left(\iint_{s} \mathbf{n} \, \sigma dS + \mathbf{f}_{m}\right) + \iint_{s} \left(c_{w} + f \, \sigma\right) \mathbf{s} \, dS = 0 \tag{17}$$

200 **3.2 Normal stress expression of slip surface under seepage force and seismic force**

As shown with the dash line in Fig. 5, a vertical differential cylinder is now taken from the homogeneous sliding body from the slip surface to the slope surface. The load on the differential cylinder is shown in Fig. 6. $-\mathbf{k}dw_1$ is the weight of the soil above phreatic surface, and $-\mathbf{k}dw_2'$ refer to the floating weight of the soil below the phreatic surface. $\mathbf{p}dw_3$ and $\mathbf{e}dw_4$ denote the seepage force and seismic force. $d\mathbf{h}$ refers to the action force of the soil around the differential cylinder.



207

210

Fig. 6 Sketch of force acting on a vertical differential cylinder in a sliding body Here, k = unit vector of z-axis; p = unit vector pointing to the direction of the

seepage force; e = unit vector pointing to the direction of the seismic force; $\theta =$ angle

211 between dS and the horizontal plane; $\xi =$ angle between the phreatic surface dS^w and

the horizontal plane in the differential cylinder.

213 The force equilibrium condition for a differential cylinder is

214
$$\sigma \mathbf{n} dS + \tau \mathbf{s} dS - \mathbf{k} dw_1 - \mathbf{k} dw_2 + \mathbf{p} dw_3 + \mathbf{e} dw_4 + d\mathbf{h} = \mathbf{0}$$
(18)

Both sides of the Eq. (18) are simultaneously multiplied by n to obtain

216
$$\sigma = n_3 \left(\frac{dw_1}{dS} + \frac{dw_1'}{dS} \right) - n_p \frac{dw_3}{dS} - n_e \frac{dw_4}{dS} - \frac{\mathbf{n} \cdot d\mathbf{h}}{dS}$$
(19)

217 Here, n_3 = component of n in the positive direction of z-axis, n_p = projection of 218 p in n direction, n_e = projection of e in n direction.

219 Known,

220

$$\begin{cases}
dw_{1} = \gamma H_{u} dS \cos \theta \\
dw_{2} = \overline{\gamma'} H_{w} dS \cos \theta \\
dw_{3} = \gamma_{w} H_{w} dS \cos \theta \sin \xi \\
dw_{4} = k_{c} \left(\overline{\gamma} H_{u} + \overline{\gamma}_{sat} H_{w}\right) dS \cos \theta \\
n_{p} = \mathbf{n} \cdot \mathbf{p} \\
n_{e} = \mathbf{n} \cdot \mathbf{e}
\end{cases}$$
(20)

221 where, $\overline{\gamma}$ = average value of the unit weight of the soil above the phreatic surface; γ' 222 = average value for the unit floating weight of the soil below the phreatic surface; $\overline{\gamma}_{sat}$ 223 = average value of the unit saturated weight of below the phreatic surface; γ_w = unit 224 weight of water; H_u = height of soil above the phreatic surface; H_w = height of the soil 225 below the phreatic surface; k_c = seismic force coefficient.

226 Substitute Eq. (20) into Eq. (19) and sort it out

227
$$\sigma = (\gamma H_u + \gamma' H_w) \cos^2 \theta - n_p \gamma_w H_w \cos \theta \sin \xi - n_e k_c \left(\gamma H_u + \gamma_{sat} H_w \right) \cos \theta - \frac{\boldsymbol{n} \cdot d\boldsymbol{h}}{dS}$$
(21)

228 Order

229

$$\sigma_{0} = (\gamma H_{u} + \gamma' H_{w}) \cos^{2} \theta - n_{p} \gamma_{w} H_{w} \cos \theta \sin \xi - n_{e} k_{c} (\gamma H_{u} + \gamma_{sat} H_{w}) \cos \theta,$$

$$h_{n} = -\frac{\mathbf{n} \cdot d\mathbf{h}}{dS}$$
(22)

230 Therefore

231

237

$$\sigma = \sigma_0 + h_n \tag{23}$$

232

Here,
$$\sigma_0$$
 = contribution of volume force to the normal stress. h_n = contribution

233 of the force of surrounding soil to the normal stress of sliding surface.

The normal stress distribution of the slip surface can be approximated in the following (Zheng, 2009):

236 $\sigma = \sigma_0 + f(x, y; \boldsymbol{a}) \tag{24}$

where f(x, y; a) = function in the horizontal coordinates (x, y) with a parametric

238 vector **a** consisting of five unknowns. f(x, y; a) is constructed by piecewise triangular

239 linear interpolation:

$$f(x, y; \boldsymbol{a}) = \boldsymbol{l}\boldsymbol{a}$$
(25)

241 where l is the interpolation function, $l = (l_1, l_2, ..., l_5)$, and it satisfies $\sum_{i=1}^{5} l_i = 1$.



242

243 Fig. 7 A triangular mesh for interpolation of normal stress on slip surface

As shown in Fig. 7, Ω_{xy} is the projection of the sliding body on the *xoy* plane, the

area characterized by the dashed line. T_m is a triangular network containing 5 nodes.

246 $l_i(x, y)(i=1, 2, ..., 5)$ is the interpolation function for these 5 nodes, which can be

formed as in finite elements with the help of the area coordinates of the 4 triangles on T_m .

Substitute Eq. (24) into Eq. (17), a system of nonlinear equations with F_s and a as unknowns is obtained:

$$F_s \boldsymbol{B} \boldsymbol{a} + \boldsymbol{D} \boldsymbol{a} + F_s \boldsymbol{b} + \boldsymbol{d} = 0 \tag{26}$$

252 Where *B* and *D* are both matrices of order 6×5 , and *b* and *d* are both vectors of 253 order six, whose expressions are respectively.

254
$$\begin{cases} \boldsymbol{B} = \iint_{s} \boldsymbol{n}' \boldsymbol{l} dS \\ \boldsymbol{D} = \iint_{s} \boldsymbol{f}' \boldsymbol{s}' \boldsymbol{l} dS \\ \boldsymbol{b} = \boldsymbol{f}_{m} + \iint_{s} \boldsymbol{\sigma}_{0} \boldsymbol{n}' dS \\ \boldsymbol{d} = \iint_{s} (\boldsymbol{c}_{w} + \boldsymbol{f}' \boldsymbol{\sigma}_{0}) \boldsymbol{s}' dS \end{cases}$$
(27)

255 We can solve Eq. (26) by either Newton's method or eigenvalue method.

In Eq. (26), all terms except the resultant external force (moment) f_m are area integrals. The volume integrals on the sliding body involved in the problem are transformed into boundary integrals that can skip the column partitions. Hence, it is not required to divide the sliding body into columns anymore, only the surface of the sliding body needs to be partitioned, as detailed in Zheng (2007).

261 **4 Verification examples**

In order to verify the accuracy of the proposed method, two examples are analyzed in this section. Different working conditions were set up for Example 2 and the results are compared with those calculated by the software.

265 **4.1 Example 1: translational sliding**

Wedge stability in rock mechanics is a typical 3D limit equilibrium analysis 266 problem. Examples of wedge include two cases of geometric symmetry and asymmetry. 267 268 Example 1 is an asymmetric wedge. Fig. 8 shows the three-dimensional model and 269 geometric parameters of the wedge plane sliding. The sliding surface is composed of 270 two structural planes, ABC and OAB, and the coordinates of the vertices have been listed in Fig. 8. The sliding direction of the wedge sliding body is assumed to be parallel 271 272 to the intersection line AB. The sliding surface of the wedge adopt the same shear strength: c' = 50kPa and $\varphi' = 30^{\circ}$. The unit weight of the wedge is 26 kN/m³. For 273 274 simple wedges, the 3D limit equilibrium method has analytical solutions, but these 275 methods all include an assumption that the shear force on the bottom slip plane is 276 parallel to the intersecting prism. If the sliding direction of the wedge sliding body is 277 assumed to be parallel to the intersection line AB of the two structural planes, the wedge 278 sliding body is statically determinate, and the safety factor has an exact value of 1.640 279 (Hoek and Bray, 1977) for this example. The safety factor calculated based on the 280 method in this paper is 1.652. This discrepancy may stem from the triangulation of the 281 sliding surface. In our method, the sliding surface is approximated using a series of 282 small triangular elements, which might introduce a slight inaccuracy, leading to a minor 283 deviation in the calculated safety factor. However, we observed a slight difference between exact value and the result obtained by the method proposed in our study, it 284 demonstrates that the proposed method can reasonably evaluate the stability of rocky 285

286 slopes containing different structural surfaces.





288

Fig. 8 Model and geometric parameters of the wedge

4.2 Example 2: ellipsoidal sliding

290 In order to verify the feasibility of the proposed method for calculating the slope 291 stability under seepage and earthquake, a classical ellipsoid example is selected for the 292 stability analysis, as shown in Fig.9, which is derived from the study of Zhang (1988). 293 Zhang's (1988) paper in 1988 provides a three-dimensional slope ellipsoid slip surface 294 example, and the simplified three-dimensional limit equilibrium method (only three 295 force equilibrium and one moment equilibrium are satisfied) is used for the stability 296 analysis. Zhang's (1988) solution for the 3D limit equilibrium of a symmetric ellipsoid 297 can be regarded as a rigorous solution since the ellipsoid has a symmetric sliding 298 surface and the other two moment equilibrium conditions are automatically satisfied by 299 the symmetric bar-column method. Zhang's (1988) solution has also been used by many 300 scholars to check the correctness of their own procedures (Hungr et al., 1989; Huang 301 and Tsai, 2000; Zheng, 2009). The example is a homogeneous slope, the potential 302 sliding surface is a part of a simple ellipsoid, the sliding surface is symmetric about the

303 *xoz* plane, and the equation of the sliding surface is



The ellipsoid model is shown in Fig. 9. The external load of the slope is only considered the effect of gravity, the unit gravity is 19.2kN/m3, and the effective shear strength parameter: c' = 29.3kPa and $\varphi' = 20^{\circ}$. We extended the analysis to include complex conditions such as groundwater presence and seismic activity. Four working conditions are considered in this section, case-1: no groundwater is considered as in the computational model of Zhang (1988); case-2: groundwater is set up as shown in Fig. 10, the mechanical parameters are listed in Table 1; case-3: earthquake action in the

316	horizontal direction is considered; case-4: both groundwater and horizontal earthquake
317	action are considered. Reference to the peak ground acceleration at the location of the
318	real slope in the Three Gorges reservoir area in Section 5, the earthquake acceleration
319	is taken 0.05g and the horizontal earthquake direction along the x-axis positive direction
320	The results from other methods and our proposed method are listed in Table 2.

321

 Table 1 Mechanical parameters of the slope

Unit weight	, γ (KN/m ³)	Shear strength, $c'(kPa)$		Friction angle, $\varphi'(\circ)$	
Saturated condition	Unsaturated condition	Saturated condition	Unsaturated condition	Saturated condition	Unsaturated condition
21	19.2	15.8	29.3	13.5	20

. .

- - - -

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322	Case-1: The safety factor calculated using our proposed method is 2.054, whereas
323	Zhang (1988) obtained a result of 2.122 using the limit equilibrium method.
324	Additionally, we perform a 2D stability analysis of the intermediate cross-section of the
325	model using Rocscience's Slide software and obtain a safety factor of 2.084. Comparing
326	the results mentioned above, it becomes evident that our proposed method for slope
327	stability analysis is feasible, and its calculation results are consistent with the results
328	obtained by using the traditional limit equilibrium method and two-dimensional
329	stability analysis.

Case-2: Only the effect of groundwater seepage is considered. Mechanical parameters of the slope below the water surface adopt saturated, while above the water surface adopt unsaturated. The groundwater not only induces hydrodynamic effects, but also increases the saturation of geotechnical materials, leading to a reduction in soil shear strength. In this working condition, the calculated safety factor is 1.183, which isclose to 1.057 calculated by Rocscience's Slide.

Case-3: We only consider the effect of horizontal earthquake on slope stability. In order to compare the results with the 2D stability calculations, we choose the horizontal seismic action direction to be in the *xoz* plane. The results calculated by the 3D procedure and the 2D software are 1.855 and 1.861, respectively. Compared with the case-2, the effect of seepage on the slope stability is greater than that of seismic action. Case-4: We considered both seepage and horizontal seismic effects. In this case, the results calculated by 3D program and 2D software are 1.047 and 0.934 respectively.

343

 Table 2 Safety factor of Example 2

Method	Zhang (1988)	Slide(2D)	The proposed method
Case-1	2.122	2.084	2.054
Case-2	-	1.057	1.183
Case-3	-	1.861	1.855
Case-4	-	0.934	1.047

Based on the above calculation results, the comparison revealed minimal differences across all four conditions (natural, with groundwater, with seismic loading, and combined), indicating that the proposed method is also effective in assessing slope stability under seepage and seismic actions.

348 **5 A True 3D Slope**

349 This section investigates slope stability evolution under the influence of rainfall350 and earthquake by taking an actual slope in the Three Gorges reservoir as a case study.



Fig. 11 Geographical location map of Woshaxi slope (© Google Maps)



Fig. 12 Contour map of Woshaxi slope





Fig. 13 Geological section map of Woshaxi slope



358 12 shows a topographic map of Woshaxi slope with contour lines and the cross-section (I-I') of the landslide is illustrated in Fig. 13. This landslide is located on the right bank 359 of the Qinggan River, a Yangtze River tributary, and lies about 1.5km away from the 360 361 Qianjiangping landslide situated on the river's opposite bank. The composition of the 362 Woshaxi landslide primarily consists of rubble and soil, underlain by Jurassic-era 363 sandstone and mudstone layers that are interstratified. The orientation of these rock layers is $100^{\circ} \angle 25^{\circ}$. The landslide has experienced significant impact due to water level 364 365 fluctuations in the range of 145-175m, resulting in submersion of its frontal part by 366 about 20-50m. This geological structure displays a descending gradient from the southwest to the northeast, with a general gradient of 20°. The highest point at the rear 367 reaching an elevation of 405m, and the front edge descending below 140m. The 368 369 landslide encompasses an average thickness of around 15m and a total volume estimated at 4.2×10^6 m³. Its main sliding direction of the landslide body is toward 40° 370 371 east of north.

According to the Seismic Ground Motion Parameter Zonation Map of China, the peak ground motion acceleration in this region is 0.05g. To investigate slope stability evolution under seismic conditions, peak accelerations are calculated and analyzed at various levels. The most dangerous case is considered in the following calculations, where the direction of the horizontal seismic action coincides with the primary sliding direction. The precipitation pattern in this region is characterized by relatively concentrated temporal and spatial distribution. Most of the rainfall occurs between April and October. To investigate the stability of three-dimensional slopes under the combined influence of rainfall and earthquake, this study considers the effects of three geotechnical parameters: permeability coefficient, porosity, and saturation. The proposed method is applied to calculate changes in slope stability resulting from average monthly rainfall and earthquake occurring between 2007-2009.



384 385

Fig. 14 Average monthly rainfall from 2007 to 2009

Fig. 14 shows the average monthly rainfall from 2007 to 2009. Table 3 lists the physical and mechanical parameters of the landslide body. It is assumed that the reservoir water level remains unchanged. To assess the effects of different geotechnical parameters and seismic action on the safety factor, four cases are considered: (i) rainfall only, (ii) rainfall and horizontal earthquake, (iii) rainfall and vertical earthquake, and (iv) rainfall and earthquake in both horizontal and vertical directions.



 Table 3 Mechanical parameters of Woshaxi slope

Unit weight, γ (KN/m ³)		Shear strength, $c'(kPa)$		Friction angle, $\varphi'(^{\circ})$	
Saturated condition	Natural condition	Saturated condition	Natural condition	Saturated condition	Natural condition

22.4 20.8 18 22 15 20	18 22 15	2.4 20.8	22.4
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393 (i) Rainfall only

394 The three parameters, infiltration coefficient, porosity, and saturation, have 395 different effects on the safety factor of slopes. The safety factor varies with the monthly 396 rainfall. The analysis indicates that an increase in rainfall does not invariably lead to a 397 decrease in the safety factor of the slope. This phenomenon can be attributed to the fact 398 that increased rainfall raises the phreatic surface within the slope, affecting two key 399 aspects: firstly, it enhances the hydrodynamic forces, and secondly, it increases the 400 pressure at the base of the slope. When the increase in pressure at the slope's base has 401 a more pronounced impact on stability than the hydrodynamic forces, the safety factor 402 of the slope will subsequently increase. Conversely, if the hydrodynamic forces 403 dominate, the stability of the slope will diminish. As shown in Fig. 15(a), the 404 permeability coefficient k is 0.01, 0.1 and 1m/d, respectively. With other parameters 405 unchanged, the trend of safety factor variation for Woshaxi landslide is consistent. The 406 higher the permeability coefficient, the greater the soil's ability to allow water to pass 407 through above the phreatic surface, the smaller the rise of the phreatic surface within 408 the slope. This results in a smaller increase in pressure at the foot of the slope and a 409 lower safety factor.

As shown in Fig. 15(b), the porosity *n* is 0.1, 0.3 and 0.5, respectively, and the safety coefficient of the Woshaxi landslide is consistent under the condition that other parameters remain unchanged. The higher the porosity, the greater the soil permeability above the phreatic surface, the smaller the rise of the phreatic surface within the slope, 414 resulting in a smaller increase of pressure at the slope's foot and thus a lower safety415 factor.

416 As shown in Fig. 15(c), the saturation S_r of the soil above the phreatic surface of 417 the landslide is 0.4, 0.6 and 0.8, respectively, and the safety factor of the Woshaxi landslide is consistent under other parameters remained unchanged. The higher the 418 419 saturation, the lower the permeability of soil above the phreatic surface, resulting in a greater rise of phreatic surface within the slope and an increased pressure at its foot, 420 421 thereby leading to a higher safety factor. Overall, under rainfall conditions, soil porosity 422 on the phreatic surface has a greater impact on safety factor than permeability 423 coefficient and saturation.



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438 stability of the landslide is obviously decreased. Fig. 17 shows the evolution of the stability of the Woshaxi landslide with rainfall and different horizontal earthquake 439 440 coefficients. With other parameters unchanged, the values of the horizontal earthquake 441 coefficients are 0.05, 0.1 and 0.15 respectively. In this research, we employed three 442 different horizontal earthquake coefficients: 0.05, 0.1, and 0.15. The coefficient of 0.05 443 is based on the seismic zoning map of China, corresponding to the seismic characteristics and expected level of seismic activity in the study area. As for the other 444 two coefficients, 0.1 and 0.15, they are not directly associated with any specific 445 446 earthquake magnitude or return period. These values were set based on engineering requirements and safety considerations, aiming to assess the variation in slope stability 447 448 under stronger seismic actions. This approach allows us to understand the response of 449 the slope under different seismic intensities and provides a safety margin for seismic 450 activities that may exceed expectations. Our study has revealed that within the specific 451 context of the examined landslide, as the horizontal earthquake coefficient increases, 452 there is a notable decrease in the safety factor. It is also observed that in this particular 453 case, the impact of seismic activity on slope stability appears to be considerably more pronounced than that of rainfall. However, these findings are derived from a singular 454 455 case study, focusing on a specific landslide morphology and set of soil properties. 456 Consequently, they may not necessarily be universally applicable across different 457 landslide types and varying geological conditions.







467 Fig. 17 Safety factors of the Woshaxi landslide under rainfall and horizontal
468 earthquake (different horizontal seismic coefficient)

469 (iii) Rainfall and vertical earthquake

Fig. 18 shows the evolution of the stability of the Woshaxi landslide with rainfall and different vertical earthquake coefficients. With other parameters unchanged, the vertical earthquake coefficient k_v takes on values of 0.025, 0, and -0.025 respectively, and the negative sign indicates that the direction of vertical earthquake is vertically downward. It is obvious from Fig. 18 that the corresponding safety factor when the earthquake acts vertically downward is smaller than the corresponding safety factor when it is vertically upward.



477

478 Fig. 18 Safety factors of the Woshaxi landslide under rainfall and vertical earthquake

479 (iv) Rainfall and earthquake in both horizontal and vertical directions

Fig. 19 shows the evolution of the stability of the Woshaxi landslide with rainfall 480 481 and different earthquake coefficients. Horizontal earthquake coefficient k_h is taken as 482 0.05, and the values of vertical earthquake coefficient are 0.025, 0, -0.025 respectively, 483 and the negative sign indicates that the direction of vertical earthquake action is 484 vertically downward. Under the condition that other parameters remain unchanged, the slope stability is lower when considering both horizontal and vertical upward 485 486 earthquake compared to considering only horizontal earthquake. Therefore, it is essential to properly account for the effect of vertical earthquake in order to ensure 487 488 maximum safety.



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490 Fig. 19 Safety factors of the Woshaxi landslide under rainfall and earthquake (in both

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horizontal and vertical directions)

492 **6 Conclusions**

In this paper, the calculation of the seepage force is studied, the normal stressexpression on the sliding surface of a slope under seepage force and seismic force are

495 also derived. Furthermore, a global analysis method that considers both seepage and seismic forces is proposed to determine the safety factor of slopes subjected to the 496 497 combined effect of rainfall and earthquake. The reliability of the proposed method is 498 also verified with two examples combining software calculations and previous results. 499 Taking a slope in the Three Gorges reservoir area as an example, this study 500 investigates the influence of soil permeability coefficient, porosity and saturation on 501 slope stability, and analyzes the safety evolution of this slope under combined effects 502 of rainfall and earthquake. The results indicate that, under rainfall conditions, the 503 porosity of the soil above the phreatic surface exerts a greater influence on safety factor 504 than permeability coefficient and saturation. With an increase in the horizontal earthquake coefficient, the safety factor of the landslide is significantly reduced, and 505 506 the impact of earthquake on slope stability surpasses that of rainfall. The safety factor 507 corresponding to vertical downward earthquake action is smaller than that of vertical 508 upward, and the stability of slope is lower when considering horizontal and vertical 509 upward earthquake actions. Therefore, in order to ensure maximum safety, proper 510 consideration should be given to vertical earthquake actions.

When considering rainfall alone, the slope safety factor is 1.04-1.09, positioning the slope in a state that between unstable and basically stable. However, upon accounting for horizontal seismic activity, the slope safety factor decreases to about 0.9 and is transformed into an unstable state. When the vertical earthquake is considered, the slope safety factor is 1.035-1.075. This represents a slight reduction but still in the

516	unstable and basically stable state. This suggests that horizontal seismic influences
517	exert a more pronounced impact on slope stability compared to vertical. When rainfall
518	and earthquake act simultaneously, the safety factor calculated using the proposed
519	method falls below 1.0, indicating an unstable condition where landslide disasters are
520	likely to occur on the slope. The research results provide scientific basis for slope
521	stability analysis and prevention. Further, the proposed method can identify potential
522	risk areas for landslide hazards, and planners in the Three Gorges Reservoir area can
523	better consider these risks and take measures to increase the seismic and flood resilience
524	of reservoir infrastructure.
525	Data availability
526	The data used in this study are available from the first author upon request.
527	Author contribution
528	JW analyzed the data, conceived the paper, and wrote the paper; ZW conceived
529	and co-wrote the paper; HL reviewed and improved the analysis and paper; and GS
530	provided the data of the actual slope in the Three Gorges reservoir.
531	Competing interests
532	The contact author has declared that none of the authors has any competing
533	interests.
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