A dense MEMS-based seismic network in populated areas: rapid es timation of exposure maps in Trentino (NE Italy)

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13 Abstract

14 The MEMS-based seismic network of Trentino (NE Italy) consists of 73 low-cost accelerometers installed close to inhabited 15 areas. These sensors have a suitable sensitivity to detect moderate-to-strong earthquakes but are able to record even weaker seismicity. The densely distributed peak ground acceleration values recorded by MEMS and other types of stations are 16 17 integrated within the existing seismic monitoring procedure in order to automatically obtain a complete set of strong motion 18 parameters a few minutes after the origin time. The exposure for resident population and critical buildings is estimated by 19 quantifying the different levels of shaking, which is expressed according to the Mercalli-Cancani-Sieberg intensity scale. 20 These types of results, summarized in synthetic PDF (Portable Document Format) documents, can be useful for civil 21 protection purposes to timely evaluate the state of emergency after a strong earthquake and to choose how and where 22 activate first aid measures and targeted structural monitoring.

24 1 Introduction

25 During the last decades seismic monitoring has been greatly improved in order to give precise and increasingly detailed 26 information for emergency and environmental purposes. Besides permanent seismic networks, a primary role in capturing 27 the increased amount of instrumental data is given by low-cost micro-electromechanical system (MEMS) instrumentation 28 (D'Alessandro et al., 2019). Nowadays, MEMS accelerometers are widely used on different spatial scales to replace or 29 densify permanent networks, in order to improve seismic detection and evaluate with greater resolution the effects of 30 earthquakes (Cochran et al., 2009: Boaga et al., 2018: Patanè et al., 2022: Vitale et al., 2022). Earthquake early warning systems have also been benefitting greatly from MEMS technology, because targeted timely actions can be automatically 31 taken in case of strong earthquakes (Satriano et al., 2011; Cochran, 2018). For this reason, large earthquake datasets need to 32 be efficiently and rapidly managed (Spallarossa et al., 2021) and related outcomes (e.g., earthquake location and magnitude, 33 34 strong motion data and maps) shared in real-time with different end users, such as scientists, technicians, politicians, civil 35 protection, decision makers, and citizens.

36 The Trentino region (NE Italy) is currently monitored by a permanent seismic network, which has been managed by the 37 Autonomous Province of Trento (PAT) since 1981 (Geological Survey-Provincia Autonoma di Trento, 1981; Viganò et al., 38 2021; Fig. 1). According to the Italian building code (Ministero delle Infrastrutture e dei Trasporti, 2018) this area is 39 characterized by peak ground acceleration (PGA) values lower than 0.18 g (for a return period of 475 years), with highest 40 seismic hazard in southern Trentino (upper Lake Garda and lower Adige Valley) and eastern Trentino (lower Valsugana, 41 Tesino and Primiero) where fault systems are mostly active (Viganò et al., 2015) (Fig. 2). The resident population on 1st January 2022 is 540,958 (ISTAT, 2012) and is mostly concentrated in the city of Trento and along the main valleys where 42 43 principal road networks and infrastructures are located.

Here, we present a local network based on MEMS accelerometers in Trentino, aimed at real-time monitoring and automatic generation of exposure maps. Co-seismic recordings are automatically processed and integrated with those from other stations (e.g., belonging to other permanent networks), allowing for a dense distribution of ground motion measurements.

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48 2 Method

49 Maps displaying seismic shaking are widely used during emergency due to their ability to summarize earthquake effects and 50 their potential impact on local targets (Michelini et al., 2020). In order to lead effective emergency actions, it is essential that 51 these maps, named "exposure maps" hereafter, are available in a few minutes after a seismic event. In fact, they provide a 52 first-level overview of the expected damage over the monitored area.

The exposure maps of the Trentino civil protection are automatically generated by using all the available seismic data (i.e., ground motion measurements), with the aim of estimating the asset exposed to an earthquake (Fig. 3). In particular, MEMS recordings are integrated with those from other stations and used to obtain a complete set of strong motion data, in order to quantify the numbers of resident population and buildings subjected to different levels of shaking. A step-by-step description of the method used to generate the exposure maps is given in the next sections.

59 2.1 MEMS accelerometer design and installation

60 The low-cost MEMS sensor adopted in the presented network is the ADXL355 of the Analog Device, AD, EL s.r.l., an 61 Italian based telecommunication company, developed the board for housing and operating the MEMS accelerometer, named 62 "ASX1000v2" (D600158 AD.EL code; Fig. 4a). The ASX1000v2 is a capacitive triaxial accelerometer, conceived to be a 63 platform for data acquisition and recording for long-term measurements. It is equipped with a high-performance 64 MicroController Unit (MCU: STM32H743 model by STMicroelectronics) and communication channels for remote control 65 and data transmission: a serial channel RS-422 or RS485, a LAN Ethernet 10/100 Mbit/s, an USB 2.0, and a 4G LTE modem (Fig. 4b). This sensor operates in high sensitivity mode for an acceleration range of ± 2 g (it supports also the ± 4 g full scale 66 67 configuration), with a 250 Hz sampling rate. Time synchronization is obtained using the Network Time Protocol (NTP). 68 Data streams from each single station are collected by a dedicated server; here, data are formatted, stored and made available 69 for the automatic processing by using a standard SeedLink server.

The noise analysis relative to each component reveals a Power Spectral Density with a general downward trend between -80 and -65 dB in the 0.03-10 Hz frequency range (Fig. 5). As shown in Figure 5, the detectability threshold of seismic events corresponds to a moment magnitude of about 3.5. Therefore, this sensor has a suitable sensitivity to detect moderate-tostrong events, those that are of primary interest to public administration for emergency management.

The MEMS sensors are installed inside telecommunication infrastructures. Each sensor is firmly coupled with the ground with screws and plugs, at the base of the local server room; the azimuth is carefully measured during installation. Each sensor is plugged into a wall outlet for power. A complete station costs only a few hundred euros, making possible the deployment of dense arrays of accelerometers.

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79 2.2 Data integration and seismic processing

80 Seismic data processing is here performed by using the software CASP - Complete Automatic Seismic Processor (Scafidi et 81 al., 2016; 2018; 2019). By taking advantage of the features of its iterative procedure, this software can effectively manage 82 (during phase picking and location) data provided by different seismic stations with variable signal quality. Contrary to 83 stations of permanent monitoring networks, which are usually installed in remote and quiet areas to ensure seismic signals 84 with low noise levels, signals from seismic stations deployed in urban areas, such as those from our MEMS network, can be 85 significantly affected by high level noise (producing spikes and impulsive signals) due to anthropogenic activities. This may 86 lead to an uncontrolled proliferation of false (i.e., non-seismic triggers). Therefore, their use in automatic phase picking 87 procedures may affect the reliability of the final earthquake location and, in some cases, lead to false events. Hence, noisy 88 stations are often neglected in automatic earthquake monitoring. CASP processes signals by using an iterative procedure 89 within which the phase picking is driven by earthquake location (Spallarossa et al., 2014). On the one hand, this allows 90 identification of false triggers. On the other hand, arrival times are improved at each iteration, leading to an optimization of 91 the earthquake location.

92 With reference to the present application, which integrates data from permanent monitoring networks and data from the 93 MEMS stations, CASP is set not to use MEMS data in the first iteration of the location procedure, thus assuming that they 94 are affected by significant background noise. In this step, the definition of arrival times is not yet driven by location but it is 95 based on an envelope function on signals (Spallarossa et al., 2014). This precaution may not be necessary for local strong 96 earthquakes, for which the seismic signal clearly dominates the background noise, but it is useful when managing signals 97 from weak earthquakes. From the second iteration on, signals from all stations are used and P- and S-wave arrivals are 98 computed by applying the Akaike Information Criterion – AIC (Akaike, 1974) on signal windows centred, for each station, 99 around the expected arrival times obtained by the location code. In fact, these picks are determined (at each iteration) by the 100 location algorithm working in conjunction with CASP, the NonLinLoc software (Lomax et al., 2000). This allows to reliably 101 discriminate between seismic phase arrivals and signal disturbances also in the case of weak-to-moderate earthquakes 102 recorded by different stations, regardless of the type of sensor used.

In addition to the computation of hypocentral parameters, for each station with at least one phase picked, CASP returns the
 values of a number of ground motion parameters (e.g., PGA, peak ground velocity PGV, spectral acceleration).

In the case of the Trentino region, a fully automated earthquake monitoring has been already operating based on CASP (Viganò et al., 2021). Thus, the great amount of data provided by the 73 installed MEMS stations (starting date July 2022; Fig. 1) has been easily integrated within the seismic monitoring procedure as the only requirements for CASP are real-time data transmission in standard SeedLink format and station response metadata in seismological standard format (i.e., Dataless, StationXML, Poles and Zeroes – PAZ file). About data transmission between the MEMS stations and the central processing system, the typical average latency is in the order of about 15 s, while the data stream of all the MEMS stations is continuous and complete at about 99.5 %.

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113 2.3 Exposure maps

114 Exposure maps are automatically created using the GMT software (Wessel and Smith, 1998) and the PHP open-source 115 scripting language. At first, shaking data recorded by each station (i.e., peak ground accelerations) are converted to intensity 116 values (Mercalli-Cancani-Sieberg scale, MCS) using empirical relationships for Italy (Faenza and Michelini, 2010 for PGA 117 <1 cm s⁻²; Oliveti et al., 2022 for PGA ≥ 1 cm s⁻²). Intensity, which is considered more informative than peak ground 118 acceleration for civil protection purposes as it is directly based on earthquake damage and perception, is colour coded 119 according to the ShakeMap palette (Michelini et al., 2020). These densely distributed data are then gridded using adjustable 120 tension continuous curvature splines ("surface" routine command in GMT, with tension set to 0.5), with no pre-processing 121 (e.g., blockmean) or interpolation. This is possible because of the dense distribution of MEMS stations, which are mainly 122 located in the vicinity of inhabited areas. At this stage, a maximum intensity value is assigned to each municipality in 123 Trentino, for which the cumulative number of resident population is known (Fig. 6). Then, the intensity map is compared to 124 the distribution and density of resident population in Trentino (last national census; ISTAT, 2012), where territorial localities 125 are classified as (i) urban area, (ii) small inhabited areas, (iii) productive areas or (iv) wide spread houses. For each locality the procedure automatically calculates the maximum intensity and combines it with the population density. The cumulative population for each intensity level is then computed. In a similar way, the system automatically processes (as polygonal features) the distribution of buildings of interest for the Autonomous Province of Trento (Fig. 6), and the cumulative number of buildings for each intensity class is obtained. Finally, peak ground acceleration is measured at 16 instrumented dams located in Trentino (Fig. 6). As the strong motion parameters from all the other stations, also these ones are converted to intensity values and used to create the Trentino exposure maps.

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133 3 Results

134 The estimation of exposure maps in Trentino is usually carried out within 10 minutes from an earthquake. A local magnitude 135 $(M_{\rm L})$ threshold for their automatic generation is set to $M_{\rm L}$ 4.0. The procedure has been activated since July 2022, using a 136 standard workstation equipped with an Intel Core i5 CPU. Even if no strong earthquakes occurred until now (October 2023) 137 in the monitored area. MEMS stations have been used for standard locations (i.e., available additional phase arrivals from 138 MEMS stations are used by the location procedure) and to record the ground motions of low-to-medium energy seismic 139 events. We note that a seismic signal recorded by a MEMS station is commonly clearly detectable for events with M_1 greater 140 than about 2.5, considering hypocentral distances of a few tens of kilometres (compare also with results by Cascone et al., 141 2021). In fact, even if the MEMS application presented in this study is principally aimed to perform quasi real-time exposure 142 maps in the urbanized areas of Trentino, in Appendix A the low magnitude earthquakes which were recorded by at least one 143 MEMS station during the period July 2022–October 2023 is listed. In some cases, some stations recorded a readable signal, related both to seismic events inside or outside the Trentino area. As an example, we can consider the automatically detected 144 145 P- and S-phase arrival times (red and blue vertical lines in Fig. 7, respectively) for the M₁ 2.7 earthquake occurred on November 10th 2022 in the Fassa Vallev (NE Trentino). GAGG is a standard seismic station of the permanent PAT network, 146 147 while station 003B belongs to the MEMS network (see Fig. 1). Both stations are located in the same area (2 km apart from 148 each other) at about 65 km from the earthquake hypocentre. Even if the P-phase onset for station 003B is masked by the 149 background noise, which is clearly higher than the noise affecting the GAGG recordings, the CASP procedure is able to 150 detect the S-phase arrival time. Thus, both GAGG and 003B can be used to calculate the strong motion parameters for that 151 event (Fig. 8). Few minutes (maximum 5) after the origin time, CASP returns event location, magnitude, and the strong 152 motion table (for all the analysed stations), which includes: PGA, PGV, Peak Ground Displacement (PGD), Spectral 153 Acceleration (SA) for different response periods (T), response spectrum intensity (also known as Housner Intensity, IH) for 154 different period ranges (0.1–0.5 s, IH 0; 0.1–1.0 s, IH 1; 0.1–1.5 s, IH 2), and Instrumental Intensity (I_{MCS}; Mercalli-Cancani-155 Sieberg scale). Compared to station GAGG, station 003B shows stronger shaking values that can be attributed to the effect 156 of different subsoils (Fig. 8). As with all stations belonging to the PAT permanent network, GAGG is deployed on bedrock, 157 while 003B is located in the middle of an alluvial valley near the town of Vezzano. Here, alluvial deposits are reasonably 158 assumed to be responsible of the observed shaking amplification. The higher ground motion values of station 003B are used 159 for a site-specific exposure map, which can take into account local seismic effects near towns and populated areas.

160 The exposure maps and all the relevant seismic results provided by CASP are reported in an automatically generated 161 document in standard PDF (Portable Document Format) format, which also contains links to the high resolutions maps 162 stored online. This summary file represents an easy and user-friendly mean of communications that can be easily 163 disseminated through emails and messaging platforms (e.g., Telegram), read online, or printed. Figure 9 shows the PDF of 164 the exposure map generated for an M₁ 2.1 earthquake occurred on July 11th 2023 in Western Trentino. After a synthetic 165 textual and graphical summary of event location (magnitude, area, origin time and hypocentral data), tables and maps 166 relative to the seismic shaking and exposure are displayed. The first table contains a quantification of the population and the 167 number of buildings of interest (A and B levels according to the administrative classification) possibly stricken by the 168 earthquake for each intensity level. The maximum recorded intensity is VI MCS at about 5 km from the earthquake 169 hypocentre (which is only 4.8 km deep). Of note, without the information provided by the MEMS network, we would have 170 significantly underestimated the maximum intensity induced by the earthquake, which would not have exceeded III MCS. 171 The PDF also shows two intensity maps that can be helpful for a rapid inspection of the damaged area. The first one shows 172 interpolated values while the second one displays the values actually observed at each analysed station. Besides the maps, 173 two tables provide further details about the measured shaking levels for both potentially involved population (first 20 174 municipalities sorted according to decreasing intensity) and available instrumented dams (listed according to both decreasing 175 intensity and PGA values).

176 In order to test the procedure considering a realistic emergency scenario for a moderate event, we have simulated an M_L 5.8 177 earthquake in Southern Trentino (45.834 °N latitude, 11.066 °E longitude, 9.0 km depth). This event has been selected to 178 roughly simulate the so-called "Middle Adige Valley" earthquake, which represents a reference for the seismic potential of 179 the Trentino region, as also evidenced by recent studies (e.g., Ivy-Ochs et al. 2017 and references therein). This earthquake 180 dated to 1046 AD, with estimated epicentral intensity IX MCS and co-seismic shaking responsible for great damage and 181 catastrophic induced events. The performed calculation represents a simplified simulation, obtained by assigning the selected 182 event magnitude and then calculating PGA at each seismic station of the network (MEMS and permanent stations). PGA is 183 computed using the regional attenuation law developed within the framework of the INGV-DPC Project S4 (Michelini et al., 184 2008). In particular, the regionalized attenuation relation adopted for the Eastern Alps is used. The summary PDF document 185 relative to this earthquake is shown in Figure 10. According to this scenario (possibly even worse than presented, because of 186 the simplified approach used), about 60 thousand people and 262 buildings of interest are involved in the area with 187 maximum intensity (VIII MCS): the four municipalities with maximum intensity count a total population of about 52,000 188 people. Concerning dams, two of them reach PGA values greater than 0.3 g; this is important in order to define specific 189 structural monitoring when predetermined PGA thresholds are overcome.

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191 4 Summary and conclusions

We have presented an upgrade of the seismic monitoring procedure of the Trentino region through the integration of dataprovided by 73 low-cost MEMS accelerometers installed in urban areas. This dense MEMS-based network has a suitable

194 sensitivity to detect moderate-to-strong seismic events; weaker earthquakes with local magnitude lower than 3.0 can be even 195 recorded and analysed. The additional data in conjunction with the automatic monitoring procedure currently in use allows 196 us to obtain a densely distributed set of strong motion measurements and, consequently, high-definition shaking maps that 197 relies only on actual recorded data. Integrating these dense MEMS data, though noisy, allows avoiding the use of ground 198 motion prediction equations, thus leading to a more reliable picture of the actual ground shaking (hence, of the expected 199 damage). This is of paramount importance for post-earthquake emergency planning in densely populated, urbanized areas 200 characterized by high seismic risk. The use of the CASP code is crucial to properly manage such noisy data with the aim of 201 getting reliable results in quasi real-time.

In addition to shaking data, the procedure presented here provide automatically generated exposure maps that quantify the resident population and the number of critical buildings in Trentino, subjected to different levels of shaking during an earthquake. Exposure maps are reported in synthetic PDF documents, which are very useful for civil protection in order to rapidly evaluate the local state of emergency after a strong earthquake and to choose how and where activate first aid measures, both for population and buildings of interests like dams.

208 Code availability

- 209 The Complete Automatic Seismic Processor (CASP) is a commercial software.
- 210

211 Author contributions

- 212 DS, AV, JB and MC conceptualized the project; JB, VC, MC and GDM developed the MEMS sensor; DS, AV, JB and MC
- 213 followed MEMS installation; DS, AV, MC and GDM performed data integration; DS and GF made the earthquake
- simulation; DS, AV, JB, GF and SB wrote the manuscript draft; DS, AV, JB, GF, SB and DSp edited the manuscript; DS,
- 215 AV, VC and GDM revised the manuscript.
- 216

217 Competing interests

- 218 The authors declare that they have no conflict of interest.
- 219

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tion of MEMS stations. Maps were made using Generic Mapping Tools v.4.5 (Wessel and Smith, 1998).

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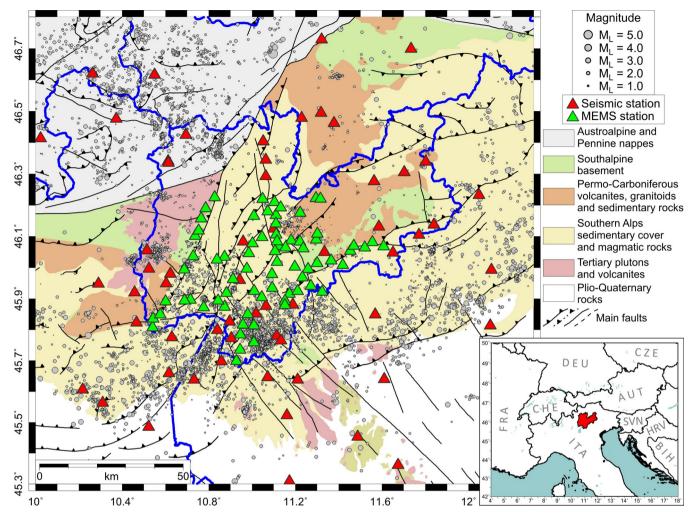
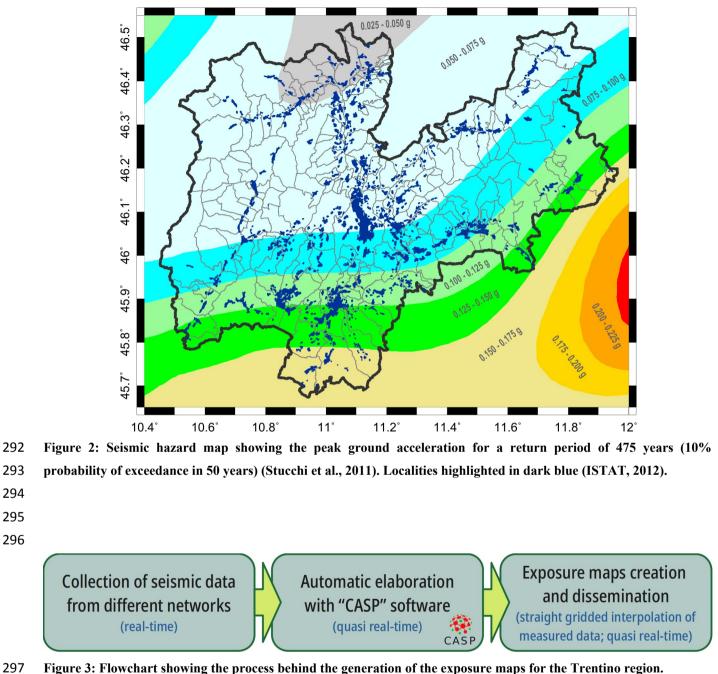
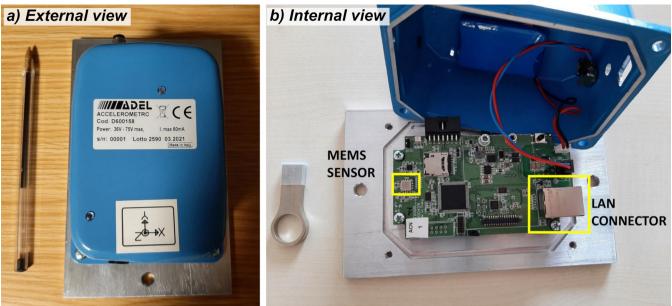


Figure 1: Simplified geological map of the Trentino region with epicentral distribution of earthquakes in the period
1981-2021 and local seismic networks. Green triangles represent the MEMS-based network (73 stations at October
2023).





300 Figure 4: (a) The ASX1000v2 MEMS sensor prototype; (b) internal circuit batch.

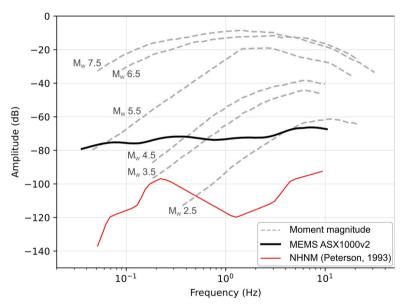


Figure 5: Noise floor of the ASX1000v2 MEMS (black line) compared to typical ground motion amplitudes of
 earthquakes measured at 10 km from the epicentre for different moment magnitudes (dashed lines). The new high
 noise model (NHNM – red line) from Peterson (1993) is also shown for reference.

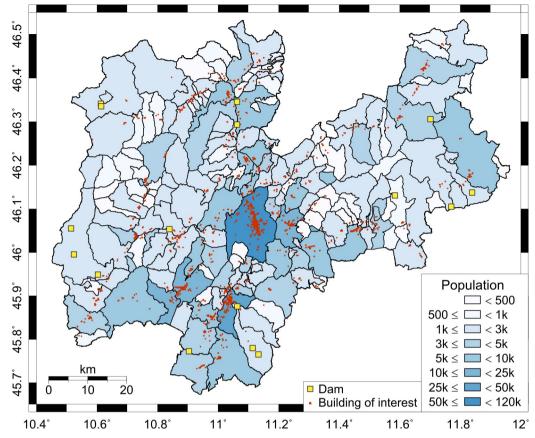
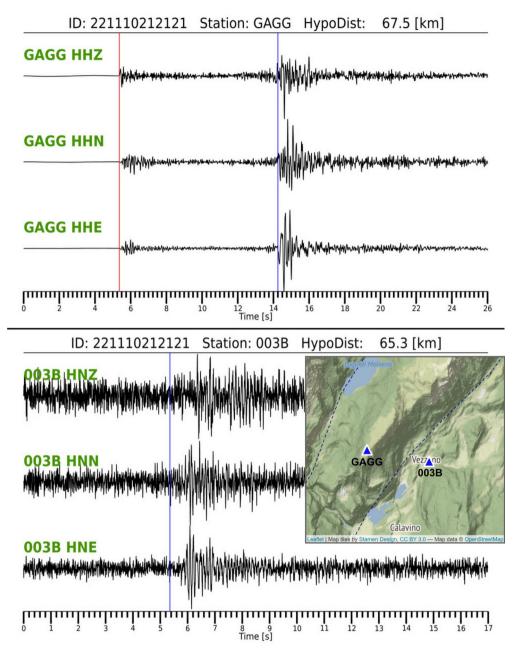


Figure 6: Trentino municipalities coloured according to the resident population density (ISTAT, 2012), with buildings
of interest (red dots) and main dams (yellow boxes) highlighted.



311 Figure 7: Unfiltered three-component seismic traces from standard (GAGG) and MEMS sensors (003B) (see their 312 geographic location in the inset) associated with automatically detected P- and S-phase arrival times (red and blue 313 lines, respectively).

Station	<u>Net</u>	Chan.	PGA (g)	PGV (m/s)	PGD (m)	IH 0* (m)	IH 1* (m)	IH 2* (m)	Sa(T=0.10) (g)	Sa(T=0.30) (g)	Sa(T=1.00) (g)	Sa(T=3.00) (g)	Dist. (km)	Azim. (°)	IMCS
GAGG	ST	HNZ	1.1544e-4	2.2126e-5	6.2110e-7	1.0179e-5	1.9381e-5	2.8232e-5	2.1453e-4	3.5065e-5	2.1356e-6	4.2307e-7	67.4	234	-
GAGG	ST	HNN	2.9669e-4	6.0573e-5	2.2308e-6	4.2506e-5	6.9291e-5	6.9291e-5	5.6295e-4	1.3750e-4	8.1487e-6	1.3107e-6	67.4	234	-
GAGG	ST	HNE	1.6050e-4	3.0075e-5	9.4923e-7	2.0460e-5	3.6440e-5	5.1543e-5	3.2503e-4	7.9317e-5	4.1464e-6	7.4897e-7	67.4	234	-
GAGG	ST	HHZ	6.2145e-5	1.2363e-5	3.1840e-7	5.5445e-6	1.0630e-5	1.5508e-5	1.1933e-4	1.8409e-5	1.1905e-6	2.3914e-7	67.4	234	-
GAGG	ST	HHN	1.8374e-4	3.3499e-5	1.0534e-6	2.2252e-5	3.9742e-5	3.9742e-5	3.6630e-4	8.2173e-5	4.3522e-6	8.3149e-7	67.4	234	-
GAGG	ST	HHE	3.4416e-4	6.5648e-5	2.4004e-6	4.6288e-5	7.5544e-5	1.0331e-4	6.5411e-4	1.4711e-4	8.9149e-6	1.4392e-6	67.4	234	-
003B	ΤN	HNZ	7.3837e-4	1.7043e-4	1.5931e-5	1.1293e-4	2.6258e-4	3.6550e-4	2.9278e-3	4.2887e-4	1.2247e-4	8.3564e-6	65.2	232	1.3
003B	ΤN	HNN	6.3724e-4	9.0012e-5	9.0852e-6	6.8410e-5	1.4765e-4	1.4765e-4	2.3232e-3	2.9415e-4	6.2978e-5	7.1631e-6	65.2	232	1.2
003B	ΤN	HNE	9.8603e-4	1.6420e-4	7.6455e-6	1.0939e-4	2.0714e-4	2.9276e-4	4.5366e-3	2.8501e-4	1.1568e-4	7.3048e-6	65.2	232	1.6

- 316 Figure 8: Screenshot of the automatically created summary table with strong motion data from standard (GAGG)
- 317 and MEMS sensors (003B). Net, network; Chan., recording channel; Dist., hypocentral distance; Azim., azimuth; see
- 318 text (section 3) for the other parameter abbreviations and meaning.
- 319







MAGNITUDE (ML): 2.1 Area: Trentino_SW_Lago_di_Garda_e_Lessini Origin Time: 2023/07/11 14:20:00 (GMT +0) Epicentre: 46.027 (°N); 10.738 (°E) Depth: 4.8 (km)



Seismic shaking exposure

Intensity (I _{MCS}):	≤ III	IV	v	VI	VII	VIII	IX	Х	≥ XI	
Perceived Shaking:	Very light	Light	Moderate	Quite strong	Strong	Very strong	Severe	Very severe	Extreme	
Population(1):	-	1.8K	3.7K	0	0	0	0	0	0	Total: 5.6
Buildings of interest A ⁽²⁾ :	-	9	14	0	0	0	0	0	0	Total: 23
Buildings of interest B ⁽²⁾ :	-	2	21	0	0	0	0	0	0	Total: 23

Ime

III (3.0)

III (3.0)

III (3.0)

III (3.0)

III (3.0)

< 111 (2.8)

< 111 (2.7)

< 111 (2.4)

(1)ISTAT 2011 census estimation; ⁽²⁾PAT 2022 census estimation.



V (5.4)	TIONE DI TRENTO	3.665
IV (4.8)	BORGO LARES	707
IV (4.7)	TRE VILLE	1.404
IV (4.2)	SELLA GIUDICARIE	2.894
III (3.9)	PORTE DI RENDENA	1.752
III (3.5)	BLEGGIO SUPERIORE	1.516
III (3.2)	LEDRO	5.248
III (3.1)	PIEVE DI BONO-PREZZO	1.430
III (3.1)	FIAVÈ	1.055
III (3.1)	PELUGO	390

COMANO TERME

DRO

SPIAZZO

TENNO

VALDAONE

RIVA DEL GARDA

STENICO

ARCO

2.895

5.057

1.244

1.992

1.141

17.646

1.178

17.798

MUNICIPALITIES EXPOSURE (first 20)

			< 111 (2.4)	BOCENAG	D 396
			< 111 (2.4)	STREMBO	609
	i la fillionna da tra di anna si si sa				
	SHAKING INTENSITY (actual	values)			
		5-2		DAMS (decreasing	exposure)
5			Imcs	Accel. max (g)	Dams
~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	×	~~~~	< 111 (1.6)	0.0009	Malga Boazzo
×	× - 15	, · · · · · · · · · · · · · · · · · · ·	< 111 (1.3)	0.0007	Ponte Pià
{	× < ,10		< 111 (1.2)	0.0006	Murandin
\$	e	2	< 111 (0.0)	0.0002	Malga Giumela
		2	< 111 (0.0)	0.0001	Pian Palù
	3	XXX	< III (0.0)	0.0001	Mollaro
		Construction of the second sec	< 111 (0.0)	0.0000	Santa Giustina
+	· ×	دي	< 111 (0.0)	0.0000	San Colombano
<b>^</b>	_	$\frown$	< 111 (0.0)	0.0000	Busa
×	<u>د</u> ک	~~~	< 111 (0.0)	0.0000	Pra da Stua
		Measurement station	< 111 (0.0)	0.0000	Costabrunella
	<u></u> <u></u> ∠	Measurement station (dam)	< 111 (0.0)	0.0000	Val Noana
J	7 _ {	km	< 111 (0.0)	0.0000	Speccheri
			< 111 (0.0)	0.0000	Val Schener
	h.m.	0 10 20			
	20 3	Event-ID: 230711141921			

Figure 9: Exposure map PDF for a weak earthquake occurred in Western Trentino. See text (section 3) for 321 322 description.







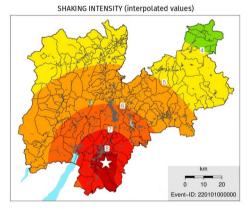
MAGNITUDE (ML): 5.8 Area: Trentino_SW_Lago_di_Garda_e_Lessini Origin Time: 0000/00/00 00:00:00 (GMT +0) Epicentre: 45.834 (°N) ; 11.066 (°E) Depth: 9.0 (km)



#### Seismic shaking exposure

Intensity (I _{MCS} ):	≤	IV	v	VI	VII	VIII	IX	х	≥ XI	
Perceived Shaking:	Very light	Light	Moderate	Quite strong	Strong	Very strong	Severe	Very severe	Extreme	
Population ⁽¹⁾ :	-	70.7K	107.3K	187.4K	72.5K	71K	0	0	0	Total: 509.1K
Buildings of interest A ⁽²⁾ :	-	198	375	231	89	161	0	0	0	Total: 1.054
Buildings of interest B ⁽²⁾ :	-	270	390	618	235	201	0	0	0	Total: 1.714

(7)ISTAT 2011 census estimation; (2)PAT 2022 census estimation



I _{MCS}	Municipality	Population		
VIII (8.5)	ALA	8.792		
VIII (8.5)	ROVERETO	39.954		
VIII (8.5)	TRAMBILENO	1.468		
VIII (8.5)	VALLARSA	1.364		
VIII (8.4)	MORI	9.974		
VIII (8.3)	BRENTONICO	4.021		
VIII (8.2)	ISERA	2.754		
VIII (8.2)	TERRAGNOLO	696		
VIII (8.0)	NOGAREDO	2.075		
VIII (8.0)	VOLANO	3.020		
VII (7.9)	VILLA LAGARINA	3.825		
VII (7.9)	CALLIANO	1.996		
VII (7.9)	FOLGARIA	3.150		
VII (7.9)	POMAROLO	2.418		
VII (7.9)	RONZO-CHIENIS	987		
VII (7.8)	AVIO	4.072		
VII (7.8)	NOMI	1.312		
VII (7.7)	BESENELLO	2.746		
VII (7.5)	ALDENO	3.187		
VII (7.5)	ARCO	17.798		

MUNICIPALITIES EXPOSURE (first 20)

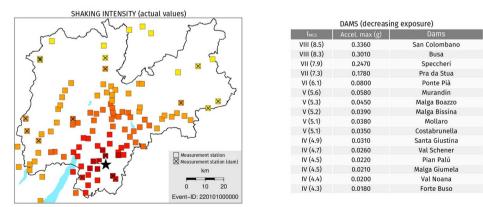


Figure 10: Exposure map PDF for a strong earthquake simulated in Southern Trentino. See text (section 3) for description.

# 326 Appendix A

327

328 List of low magnitude earthquakes recorded by at least one MEMS station, in the period July 2022-October 2023. The

329	event-MEMS distance is calculated considering the cl	losest station to the hypocentre.
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ID	Date	UTC time	ML	Epicentral area	Recording MEMS	Event-MEMS distance
	(yyyy-mm-dd)	(hh:mm:ss)		(-)	(#)	(km)
1	2022-10-21	07:15:37	1.7	Trentino	2	14.0
2	2022-11-10	21:22:12	2.7	Trentino	2	46.7
3	2023-02-07	08:37:24	1.8	Trentino	1	16.3
4	2023-03-29	11:05:14	0.9	Trentino	1	18.0
5	2023-04-04	04:08:42	1.3	Trentino	1	10.7
6	2023-05-22	13:04:19	2.1	Trentino	1	44.4
7	2023-07-06	11:10:36	0.8	Trentino	1	4.7
8	2023-07-11	14:20:17	2.1	Trentino	4	5.0
9	2023-07-23	07:05:50	0.8	Trentino	1	3.1
10	2023-08-06	21:57:41	1.8	Trentino	2	10.6
11	2023-09-13	20:10:41	2.3	Trentino	6	5.2
12	2023-10-13	07:25:19	3.4	Outside Trentino	1	133.9
13	2023-10-25	13:45:37	4.2	Outside Trentino	13	79.7
14	2023-10-28	15:29:23	4.2	Outside Trentino	6	84.2