1	Assimilation of Himawari-8 Imager Radiance Data with the WRF-3DVAR
2	system for the prediction of Typhoon Soulder
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19 Abstract

Himawari-8 is a new generation geostationary meteorological satellite launched 20 by Japan Meteorological Agency (JMA). It carries the Advanced Himawari Imager 21 (AHI) onboard, which can continuously monitor high-impact weather events with 22 high frequency space and time. The assimilation of AHI radiance data was 23 implemented with the three-dimensional variational data assimilation system of 24 Weather Research and Forecasting model (WRF-3DVAR) for the analysis and 25 prediction of Typhoon Soudelor (2015) in the Pacific Typhoon season. The effective 26 27 assimilation of AHI radiance data in improving the forecast of the tropical cyclone during its rapid intensification has been realized. The results show that after 28 assimilating the AHI radiance data under clear sky conditions, the typhoon position in 29 30 the background field of the model is effectively corrected compared with the control experiment without AHI radiance data assimilation. It is found that the assimilation of 31 AHI radiance data is able to improve the analyses of the water vapor and wind in 32 typhoon inner-core region. The analyses and forecasts of the minimum sea level 33 pressure, the maximum surface wind, and the track of the typhoon are further 34 improved. 35

Key words: Weather Research and Forecasting model; Three-Dimensional
Variational Data Assimilation; AHI Radiance Data; Typhoon

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1. Introduction

In recent years, although researchers have made great progress in the field of 40 numerical weather prediction (NWP), the huge challenges are encountered in the 41 accurate forecasts of tropical cyclones (TCs) with rapid intensifications (DeMaria et 42 al., 2014). The predictability of these TCs is limited because it entails complex 43 multi-scale dynamic interactions (Minamide and Zhang 2018). These interactions 44 environmental airflows, TC vortex interactions, 45 include atmosphere-ocean interactions, and the effects of mesoscale and micro-convective scale, together with 46 47 the microphysics and atmospheric radiation. In order to attain a better initial condition and improve the accuracy of the forecast, data assimilation seeks to fully utilize the 48 observations. The life span of most TCs is over the ocean where conventional 49 50 observations are relatively insufficient compared to the land. Therefore, by analyzing observed data from satellites and planes over the ocean, it is crucial to adopt effective 51 data assimilation (DA) methods to improve the analysis and forecast of TCs. 52

With the rapid development of atmospheric radiative transfer model, many numerical weather prediction centers have adopted variational DA method to assimilate a variety of radiance data from different satellite observation instruments (Bauer et al., 2011; Buehner et al., 2016; Derber et al., 1998; Hilton et al., 2009; Kazumori et al., 2014; McNally et al., 2006; Prunet et al., 2000; Pennie, 2010). These data can take up 90% of all data used in global DA system and can improve the accuracy of the numerical model results strikingly (Bauer et al., 2010). Some researches demonstrated that in global model, satellite radiance DA makes more
contribution to improving the accuracy of the numerical model results than
conventional observation DA does (Zapotocny et al., 2007).

Generally speaking, radiance data are derived from microwave and infrared 63 detecting instruments, which are from polar-orbit satellites and geostationary satellites, 64 respectively. Polar-orbit satellites cover the sphere of all the earth, thereby suitable for 65 global NWP models (Jung et al., 2008). Besides, they have finer resolutions compared 66 to geostationary satellites (Li et al., 2017; Shen et al., 2015; Xu et al., 2013). However, 67 68 it is highlighted that they are not able to perform continuous monitoring over a fixed area, thus leaving out some rapidly intensified TCs or storms. On the contrary, 69 because geostationary satellites have a fixed location related to the earth's surface, 70 although their resolutions are lower than that of polar-orbit satellites, they can capture 71 the formation and development of mesoscale convective systems by continuous 72 monitoring (Montmerle et al., 2007; Stengel et al., 2009; Zou et al., 2011). 73

Geostationary satellites are able to continuously detect a region at a higher frequency, thus observing TCs over the vast ocean effectively. In fact, they can capture convective spiral cloud systems relating to TCs. As the first new generational geostationary satellite, Himawari-8 plays a pioneering role for the geosynchronous imagers to be launched in US, China, Korea and Europe. It has an advanced imager called Advanced Himawari Imager (AHI) with 16 visible and infrared bands, including 3 moisture channels, which can conduct a full-disk scan every 10 minutes. Meanwhile, it can also acquire regional scanning images and that is to say it can scan the Japan and the target areas every 2.5 minutes. Compared to the early geosynchronous imagers, AHI has more spectrum bands and this can monitor the state of atmosphere with a higher frequency.

In recent years, some experts and scholars have carried out some studies on the 85 data assimilation of geostationary satellite observations. Firstly utilizing GSI 86 (Gridpoint Statistical Interpolation) from NCEP (National Centers for Environmental 87 Prediction), Zou, et al (2011) conducted direct assimilation on imagers' data from 88 89 GOES-11 and GOES-12 to estimate their potential influences on QPF (quantitative precipitation forecasts) of coastal regions in the eastern part of American. They found 90 that assimilating radiance data from GOES's imager has a remarkable improvement 91 on 6 to 12 hour's QPF near northern Mexico Gulf coast. Their work was continued by 92 Qin, et al (2013), which put thinned radiance data into GSI system to make a 93 comprehensive investigation on the issue on combined assimilation of GOES Imager 94 95 data together with AMSU-A (Advance Microwave Sounding Unit-A), AMSU-B (Advance Microwave Sounding Unit-B), AIRS (Atmospheric Infrared Sounder), 96 97 MHS (Microwave Humidity Sounder), HIRS (High Resolution Infrared Radiation Sounder), GSN (GOES Sounder). The results showed the effect of single assimilation 98 of AHI radiance data are better than combined assimilation in term of precipitation 99 forecast. Zou, et al (2015) adopted the GSI system to assimilate radiance data from 100 101 four infrared channels on GOES-13/15 and set up two experiments for comparison. A

symmetric vortex was used for initialization in the first experiment and an asymmetric 102 counterpart for the other experiment. Results showed that direct assimilation of 103 GOES-13/15's radiance data could yield positive effects on the track and intensity 104 forecasts of hurricane "Debbie". As the new instrument of himawari-8, there are few 105 studies on the DA of himawari-8 data. Ma, et al (2017) used 4DEnVar 106 (four-dimensional ensemble variational) DA in NCEP's GSI system to assimilate 107 radiance of three moisture channels of AHI radiance data under clear-sky condition 108 and then NCEP GFS (Global Forecast System) was utilized to estimate the impacts of 109 110 AHI radiance data assimilation on whether forecast. They found it had a positive impact on the forecast of global vapor at high level of troposphere. Wang, et al (2018) 111 investigated the impact of assimilating three water vapor channels under clear sky on 112 113 the analysis and forecast of a rainstorm in Northern China with the 3DVAR method. It pointed out that the assimilation of AHI radiance data could improve the wind and 114 vapor fields and the accuracy of rainfall forecast in the first 6 hours lead time. 115

Although previous researches have made several achievements in satellite data assimilation and application, it is still a challenge to make more effective use of the new generational geostationary satellite imager data with high spatial and temporal resolution. In most of the previous studies, researches usually use a 6 hour's or even longer time interval with a coarse spatial resolution. Therefore, the rapid updating assimilation techniques of the geostationary satellite radiance data have not been well carried out at convective scale. This study intends to build a data assimilation system

aiming at AHI radiance data based on the new generational mesoscale Weather 123 Research and Forecasting (WRF) model. A case of Typhoon Soudelor is studied by 124 performing numerical simulation to address the impacts of convective DA on the 125 improvement of the initial conditions of TC and the enhancement of track and 126 127 intensity forecasts. Our study focuses mainly on assimilating the three water vapor channels (6.2, 6.9, and 7.3µm) since they are very sensitive to the humidity in the 128 middle and upper troposphere and have a certain effect on the lower troposphere. 129 Thus, a large amount of effective atmospheric information can be provided for AHI 130 131 radiance data assimilation in the troposphere. The weighting functions for the three channels are provided in Fig. 1. 132

Section 2 describes the observations and the data assimilation system. Introductions to the typhoon case and the experimental setup are provided in section 3. The detailed results in terms of the analyses and the forecasts are illustrated in section 4 before conclusions are summarized in section 5.

137 **2. Observational data and DA system**

138 2.1 An introduction to Himawari-8 AHI radiance data

Himawari-8 satellite was launched by JMA to a geosynchronous orbit on 17 October 2014 and has begun its operational use since 7 July 2015 (Bessho et al., 2016). It is located between the equator and 140.7°E, thus the earth is observed between 60°N and 60°S meridionally and between 80°E and 160°W zonally. Compared to its previous generation Himawari-7, its detective ability can get

significantly improved since the instrument AHI on Himawari-8. Besides, its device is 144 comparable to imagers on American GOES-R satellite (Goodman et al., 2012; Schmit 145 et al., 2005; Schmit et al., 2008; Schmit et al., 2017). AHI is able to provide a full-disk 146 image every 10 minutes and complete a scan over Japan every 2.5 minutes. AHI 147 conducts continuous scan and detection on a moving targeted typhoon. It has 16 148 channels covering visible, near-infrared, and infrared spectral bands with a resolution 149 of 0.5 km or 1 km, and 2 km respectively. Channel 8 to 10 (6.2, 6.9, and 7.3 µm) are 150 water vapor bands that are sensitive to the humidity in the middle and upper 151 152 troposphere (Di et al., 2016). Other channels (channel 11, 12, 16: 8.6 µm, 9.6 µm, and $13.3\mu m$) are either monitoring other fields such as the thin ice clouds, volcanic SO₂ 153 gas, the ozone or CO₂, or the atmospheric window channels (13-15: 10.4, 11.2, and 154 155 12.4 µm) function as monitors for ice crystal/water, low water vapor, volcanic ash, sea surface temperature and other phenomena (Bessho et al., 2016). 156

157 2.2 WRFDA system and AHI radiance data

WRFDA system is designed by National Center for Atmospheric Research (NCAR) and it contains 3DVAR, 4DVAR, Hybrid parts. This research is based on the 3DVAR method. An interface that is suitable for AHI DA is built in WRFDA system. Currently, WRFDA is able to assimilate many conventional and unconventional observations. In terms of satellite radiance data, this system is compatible with RTTOV (the Radiative Transfer model of the Television and Infrared Observational Satellite Operational Vertical sounder) and CRTM (Community Radiative Transfer

Model, Liu and Weng, 2006) as observation operators. In this study, CRTM is utilized 165 as the observation operator to simulate and compute AHI radiance data. Estimating 166 the systematic bias and random error of the observations caused by the errors of 167 numerical models and instruments are the key factors to directly assimilate the 168 satellite radiance data. Apart from eliminating cloud pixels, other procedures for 169 quality control are as follows. (1) when reading the data, remove the observed outliers 170 with values below 50 K or above 550 K; (2) only the marine observations are applied 171 by removing the observations on the land and the observations over complex surfaces; 172 173 (3) remove observations when the observation minus the background is larger than 3 times of the observation error; (4) the pixels are removed when the cloud liquid water 174 path calculated by the background field of the numerical model is greater than or 175 176 equal to 0.2 kg/m2; (5) eliminate the data when the observation minus background is greater than 5 K. 177

By using 3DVAR algorithm, the assumption is that there is no bias between observation and background (Dee et al., 2009; Liu et al., 2012; Zhu et al., 2014). A bias correction scheme for observation is essential before DA. Usually, radiance bias can be obtained by a linear combination of a set of forward operators.

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$$\tilde{H}(x,\beta) = H(x) + \beta_0 + \sum_{i=1}^{N_p} \beta_i p_i$$
 (1)

Here, H(x) represents the initial observation operator (before the bias correction), x represents the mode state vector, β_0 represents a constant component of the total bias (constant part), P_i and β_i represent the i-th predictor and its coefficient respectively. In this study, four potentially state-dependent predictors (1000–300 hPa and 200–50 hPa layer thicknesses, surface skin temperature, and total column water vapor) are applied. The variational bias correction (VarBC) scheme is utilized to update the bias correction coefficient variationally with the new observation operator considered in the cost function of 3DVAR.

191 **3. Introduction to the typhoon and experimental design**

192 *3.1 Typhoon Soudelor*

From the record of the China Meteorological Administration (CMA), Typhoon 193 Soudelor was the 13th typhoon in 2015 as the second strongest tropical cyclone in that 194 year. At 1200 UTC 30 July 2015, it formed at northwest Pacific Ocean as a tropical 195 storm at 13.6° N, 159.2° E, then moved north-westwards. It upgraded to a strong 196 tropical storm at 2100 UTC 1 August 2015. Afterwards, it went through a process of 197 rapid intensification. It became a typhoon at 0900 UTC 2 August 2015, a strong 198 typhoon at 2100 UTC 2 August 2015, a super typhoon at 0900 UTC 3 August 2015. 199 200 Then it weakened to a strong typhoon in the morning on 5 August 2015. However, it intensified to a super typhoon again at 1200 UTC 7 August 2015 with a maximum 201 surface wind of 52 m s⁻¹, moving west by north, and its intensity raised to its second 202 peak. It was reduced to a strong typhoon again at 1800 UTC 7 August 2015. It 203 decreased to a typhoon, entering to Taiwan Strait. It landed again as a typhoon at 1410 204 UTC on the coast of Fujian Province, China. Owing to continuous orographic friction, 205

it decreased to a tropical depression. Fig. 2 shows the track of Soudelor and different 206 color lines represent typhoon's maximum surface wind. It is displayed that after the 207 208 formation of typhoon, its track is relatively stable. After July 30, the tropical depression moved west by north at a speed of about 20 km/h. Its moving tendency 209 210 changed slightly within 10 days of its generation. However, its intensity went through a rapid intensification, a weakening, a second intensification, then a continuous 211 weakening till disappearing gradually after landing on the China. Fig. 3 demonstrates 212 the variation of typhoon's intensity from 31 July 2015 to 5 August 2015. It is shown 213 214 that typhoon's maximum surface wind increased fast, while its minimum sea level pressure decreased sharply. This was the stage of typhoon's rapid intensification. The 215 date from 1 August 2015 to 3 August 2015 during its rapid intensification are selected 216 217 as a research object.

218 *3.2 Experimental design*

Two experiments are designed to investigate the effects of AHI radiance data 219 220 direct assimilation on the analysis and forecast of Typhoon Soudelor starting from 1800 UTC 1 August 2015 to 0000 UTC 3 August 2015. WRF 3.9.1 is employed as the 221 222 forecast model in this experiment. Arakawa C grid is used in the horizon with a 5 km grid distance. As is known, Arakawa A grid is "unstaggered" by evaluating all 223 quantities at the same point on each grid cell. The "staggered" Arakawa B-grid 224 separates the evaluation of the velocities at the grid center and masses at grid corners. 225 Arakawa C grid further separates evaluation of vector quantities compared to the 226

Arakawa B-grid. Vertically, it has 41 eta levels using 10 hPa as its top with coarser 227 vertical spacing for the higher levels. Model center is (17.5 °N, 140 °E) (Fig. 4). The 228 initial condition and lateral boundary are provided by 0.5°×0.5° Global Forecasting 229 System (GFS) reanalysis data. The following parameterization schemes are used: The 230 231 following parameterization schemes are used: WDM6 microphysics scheme (Lim et al., 2010), Grell Devenyi cumulus parameterization scheme (Grell et al., 2002), 232 RRTM (Rapid Radiative Transfer Model) longwave radiation scheme (Mlawer et al., 233 1997), shortwave radiation scheme (Dudhia et al., 1989), and YSU boundary layer 234 235 scheme (Hong et al., 2006).

The experimental procedures are illustrated by Fig. 5. Firstly, a 6 hour's spin-up 236 conducted initialized from 1800 UTC 1 August 2015 to prepare the background field 237 for the data assimilation at 0000 UTC 2 August 2015. The first experiment is 238 assimilating GTS (Global Telecommunications System) conventional data (including 239 aircraft report, ship report, sounding report, satellite cloud wind data, ground station 240 241 data) only, which is called control experiment (CTNL). Another experiment is configured with AHI radiance data assimilation (AHI DA). AHI radiance data is 242 243 assimilated hourly further from 0000 UTC to 0600 UTC on 2 August 2015. Afterwards, an 48 hours forecast is launched as the deterministic forecast. The 244 climatological background error (BE) statistics are estimated using the National 245 Meteorological Center (NMC) method. There are 5 control variables applied in this 246 study including U component, V component, full temperature, full surface pressure, 247

and pseudo-relative humidity. The observation error for each channel is estimated
based on the observed brightness temperature minus background brightness
temperature (OMB) from 0000 UTC on 1 August 2015 to 0000 UTC on 3 August
2015 every 6 hours.

Fig. 4 also shows the distribution of GTS observation data at the simulated 252 domain at 0000 UTC 2 August 2015. It is proved that raw radiance observations 253 thinned to a grid with 2-6 times of the model grid resolution are able to remove the 254 potential error correlations between adjacent observations 255 (Schwartz et 256 al., 2012; Xu et al., 2015; Choi et al., 2017). Hence, 20 km is chosen to make thinning of AHI radiance data. Also, sensitivity experiments with 25 km, and 30 km 257 thinning mesh are also conducted with similar results. The length scale and the 258 variance scale are set to be 0.5 and 1 respectively after several sensitivity experiments 259 conducted on tuning the background error. Similar conclusions are also found in Shen 260 and Min (2015) with the scale factors related to the static background error 261 covariance. 262

263 **4. Results**

264 *4.1 Minimization iterations*

Fig. 6 shows the cost function and gradient with the iteration times. There is an obvious exponential decrease curve in Fig. 6a, while Fig. 6b shows gradient decreases with the increase of iteration times. Taking Fig. 6a as an example, cost function decreases remarkably in the first 10 iterations. However, after 30 times of iteration,

the cost function curve becomes smooth gradually. The differences between 269 background field and observation are largest. With continuous iterations, background 270 271 field goes through continued adjustments. Finally, the cost function tends to reach a stable minimum that represents the point when cost function has its optimal solution. 272 Besides, the gradient in Fig. 6b decreases stably with increasing iterations. The 273 exponential decrease of the cost function and the change trend of its gradient indicate 274 that the effectiveness of AHI radiance DA. The final iterated analytical field is close 275 276 to the observation.

4.2 Analytical results of the brightness temperature

Fig. 7a, c, e show the distribution of OMB, while the observed brightness 278 temperature minus analytical brightness temperature (OMA) after the bias correction 279 of AHI radiance data are presented in Fig. 7b, d, f from channel 8, 9, and 10 at 0000 280 UTC 2 August 2015. It should be pointed that even only parts of the AHI radiance 281 data are applied after quality control in the data assimilation, the radiative transfer 282 283 model is able to simulate the brightness temperature for all the pixels with the background and the analysis respectively for the verification purpose. The similar 284 285 verification method is also applied in Yang et al., (2016). In the Fig. 7a, part of typhoon's spiral cloud belt is clearly visible. The brightness temperature in typhoon's 286 inner-core area is low, while the brightness temperature in other areas is high. The 287 mean of observed OMB was -4.65 K, indicating that the background brightness 288 temperature is higher than the observation. It is found in Fig. 7b that the OMA values 289

of most pixels are below 0.02 K, indicating that the analytical field fitting the 290 observation after analyzing. It can be inferred from Fig. 7a, c, and e that the 291 292 magnitude in OMB of channel 10 is generally larger than that of channel 9, while that of the OMB in channel 8 is the smallest. This is because the detection height of 293 channel 10 is lower than that of channel 8 and 9 seen from the weighting function (Fig. 294 1), indicating channel 10 is largely affected by the clouds. Conversely, the weighting 295 peak of the channel 8 is the highest, being least affected by the clouds. In general, the 296 analytical brightness temperature match well with the observed brightness 297 temperature of all the three water vapor channels after the assimilation of AHI 298 radiance data. 299

Fig. 8 shows the effect of the bias correction for AHI radiance data at 0000 UTC 300 2 August 2015. Fig. 8a, d, g show the scatter plots of the observed brightness 301 temperature and the brightness temperature from the background before the bias 302 correction. Fig. 8b, e, h show results after bias correction. Fig. 8c, f, i show the scatter 303 plots of observed brightness temperature and analytical brightness temperature after 304 bias correction. From Fig. 8a, before the bias correction, the values from the 305 306 observation and the background are comparable, but most of the scatter points are below the diagonal line. This suggests that the observed brightness temperature is 307 higher than the background simulated brightness temperature. From Fig. 8b, after the 308 bias correction, observed warm bias is corrected to some extent. From Fig. 8a, b, after 309 the bias correction, the root mean square error (RMSE) of OMB decreases from 1.864 310

K to 1.627 K, with the average decreasing from 0.956 K to 0.358 K, proving the 311 validity and rationality of the variational bias correction. Compared to the result of 312 Fig. 8b, the scatters in Fig. 8c are more symmetrical, fitting closely to the diagonal 313 line. The mean and RMSE were also significantly reduced, suggesting that the 314 analytical field is more similar to observation than background field. Channel 9, 10 315 have a similar result, but with a significantly reduced mean and RMSE, indicating that 316 the background field and analytical field of channel 9, 10 match better with the 317 observation than channel 8 does. Among them the RMSE of channel 10 is smallest as 318 319 0.234 K in Fig. 8i, which is likely related to strict cloud detection scheme for channel 10 with rather lower detecting peak (Wang et al., 2018). 320

Fig. 9 shows the observation numbers, the mean, and the standard deviation of 321 OMB and OMA of channel 8, 9, and 10 before and after the bias correction. It can be 322 seen that after the quality control, 24057, 24181, 21785 observations are adopted in 323 the DA system for channel 8, 9, and 10, respectively. From the mean value of OMB 324 325 before the bias correction, the value of the three channels is relatively small, indicating that the simulated brightness temperature of the three channels is close to 326 327 the observed brightness temperature. The lowest mean of 0.3 K is found in channel 10, indicating that the simulated brightness temperature of channel 10 is closest to the 328 observed brightness temperature. Bias correction effectively corrects the systematic 329 bias and reduces the mean value of observation residuals. After the bias correction, 330 the OMB mean value of the three channels significantly decreases to nearly 0 K. With 331

the bias correction, the simulated brightness temperature is almost the same as the observed brightness temperature. The analysis of the standard deviation of OMB shows that the results are comparable before and after the bias correction. The standard deviation of OMA decreases by about 80% compared to OMB, indicating that the analyses fit better with the observations after the data assimilation. Differences between the standard deviations of the OMB and OMA were statistically significant at the 95% level using zero difference for the null hypothesis.

The RMSEs of the simulated brightness temperature by the NWP model before 339 340 and after the assimilation are also calculated against the AHI radiance observations. Fig. 10 shows the RMSEs during the DA cycles for channels 8, 9, 10. As can be seen 341 from Fig. 10, RMSE decreases after each analysis in AHI DA. The most significant 342 improvement is from the first analysis cycle of channel 8, where RMSE of the 343 brightness temperature after assimilation significantly decreases from 1.64 K to 0.46 344 K, possibly due to the largest adjustment on the background for the first analysis time. 345 346 The background before the assimilation is the short-term forecast from the previous analysis. The increase of the RMSE in the fluctuation arise from the model error in 347 the 1 hour short-term forecast. Overall, the effect of the analysis from the channel 10 348 is most significant. 349

350 *4.3 Analysis of the typhoon structure*

Fig. 11 shows the wind field at sea level and the distribution of water vapor at 850 hPa at 0000 UTC 2 August 2015. The obvious cyclonic eddy circulation

structures in the core area of the typhoon are found in both fields, while the 353 anti-cyclonic circulation exists in the northwest quadrant of the typhoon. The mixing 354 355 ratio of water vapor in the region where the typhoon located is very high and the wind field is cyclonic, indicating that the typhoon has a continuous water vapor advection. 356 This contributes to the enhancement of typhoon (Kamineni, et al., 2003). From the 357 flow field of the control experiment in Fig. 11a, the water vapor convergence in the 358 center of the typhoon region is weak with the low intensity and smaller coverage. As 359 can be seen from Fig. 11b, after the assimilation of AHI radiance data, the streamlines 360 361 in the typhoon region become denser, indicating that the cyclonic circulation is strengthened. Conversely, the intensity and distribution of the water vapor after the 362 assimilation of AHI radiance data tend to contribute to the developing typhoon. This 363 364 suggests that the assimilation of AHI radiance data are able to significantly improve the large-scale environmental field in the simulation region of Typhoon Soudelor. It 365 should be pointed out that the model status in the cloudy area are modified due to the 366 spatial correlation in the background error covariance. The similar findings for 367 small-scale information in the cloudy area can also be referred in Wang et al., (2018). 368

369 *4.4 Track forecast*

In order to further evaluate the effect of AHI radiance data assimilation, a 48-hour deterministic forecast is launched with the analyses initialized from 0000 UTC 2 August 2015 and 0600 UTC 2 August 2015 respectively. The best track data are provided by the CMA (Yu et al., 2007; Song et al., 2010). As can be seen in Fig. 12a,

at the beginning of the forecast, the initial location of the typhoon from the CTNL 374 experiment has large south bias and east bias at 0000 UTC and 0600 UTC 375 376 respectively. Conversely, the location of the typhoon in AHI DA is relatively closer to the observation at the beginning. During the following few hours of forecasts, the 377 typhoon track predicted by the CTNL continues to show a south-west bias with the 378 environmental wind, while the track predicted by AHI DA match better with the best 379 track. Fig. 12c shows the averaged typhoon track error over the two forecasts 380 predicted by the two experiments. At the initial time of the forecast, the track errors of 381 382 CTNL and AHI DA are significantly different, with the magnitude of 55.6 km and 13.4 km, respectively. During the subsequent 48-hour forecast, the track error of the 383 CTNL gradually increases with the forecast time reaching 167.1 km at the end of the 384 385 forecast. In contrast, the track error of AHI DA is consistently less than 122.5 km during the 48-hour forecast period. In general, the average track error of the CTNL is 386 168.57 km, and the average track error of AHI_DA experiment is only 67.0 km, 387 388 indicating a significant improvement in the track prediction.

Fig. 13 provides the time series of the typhoon intensity from the two experiments in terms of the averaged maximum surface wind and minimum sea level pressure error over the two forecasts initialized from 0000 UTC 2 August 2015 and 0600 UTC 2 August 2015 respectively. It can be seen that the maximum surface wind error predicted by the AHI_DA is much lower than that by the CTNL, due to the overall under estimation for the strength of Typhoon Soudelor simulated in the

background field. The maximum surface wind predicted by AHI DA fit closer to the 395 best track data with the maximum difference about 2.6 m s⁻¹ after 12 hours forecast . 396 397 In Fig. 13b, the results of the minimum sea level pressure are consistent with Fig. 13a. 5. Conclusion 398 An interface for AHI radiance data assimilation on the WRFDA system based on 399 the 3DVAR assimilation method was built. Based on the Typhoon Soudelor in 2015, 400 two experiments for comparison was designed to examine the impact of AHI water 401 vapor channel radiance data assimilation on the analysis and prediction of the rapid 402 development stage of Typhoon Soudelor under clear sky condition. Following 403 conclusions are obtained: 404

(1) The AHI radiance data on the new generation of geostationary meteorological satellite is able to reflect the structure of Typhoon Soudelor very clearly. After a series of pre-procedures such as the quality control, the bias correction, cloudy pixels are able to effectively be eliminated, ensuring the validity and rationality of the Ahi radiance data. The biases are also eliminated from the VarBC statistical method, which is able to provide a positive impact on the data assimilation procedure for the typhoon numerical simulation.

(2) Compared with the control experiment with only GTS data, the 3DVAR
assimilation including AHI radiance data is able to improve the structure of typhoon's
core and outer rain band. Also, the position and intensity of typhoon in the
background field are able to be corrected.

(3) It is found that the track, maximum surface wind, and minimum sea level pressure
from the AHI radiance data assimilation experiment match better with the best track
than the control experiment does for the subsequent 18-hour forecast.

In this study, the AHI water radiance data assimilation is conducted under the 419 clear sky condition. The results of the experiments indicate that AHI radiance data 420 assimilation has a positive effect on the analysis and prediction of rapidly intensifying 421 TC. Considering the complex influence of underlying surface, only the rapid 422 development stage of typhoon at sea were studied, while the whole generation, 423 424 development and disappearance stage of typhoon can also be studied in the future. In addition, based on the AHI radiance data of the water vapor channels under the 425 condition of clear sky, only 3DVAR method was adopted. Further improvements 426 under the condition of all sky and hybrid DA can be obtained in the future. 427

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579 Fig.1 Weighting functions of Himawari-8 Advanced Himawari Imager three water

580	vapor	channels	for C	hannel	8,9), and	10.
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Fig.2 The best track of Soudelor from the China Meteorological Administration
(CMA) from 0000 UTC 30 July to 0600 UTC 12 August 2015. Different colors





Fig. 3 The time series of the minimum sea level pressure (solid line, unit: hPa) and the
maximum surface wind (dash line, unit: m s-1) of typhoon Soudelor from the CMA
best-track data.



Fig. 4 Distribution of GTS observations in the simulated area at 0000 UTC 2 August
2015. On the right side of the map is the name of observation data and the number of
observations.







Fig. 7 (a, c, and e) OMB (unit: K) after bias correction for channel 8, 9, and 10, respectively; (b, d, and f) OMA (unit: K) after bias correction for channel 8, 9, and 10,

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respectively at 0000 UTC 2 August 2015.
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Fig. 8 Scatter plots of (a, d and g) the observed and background brightness temperature before the bias correction of channel 8, 9 and 10. Scatter plots of (b, e and h) the observed and background brightness temperature after the bias correction of channel 8, 9 and 10. Scatter plots of (c, f and i) the observed and analyzed brightness temperature after the bias correction of channel 8, 9 and 10.



Fig. 9 Number of (a) observations, (b) mean (unit: K), and (c) standard deviations
(unit: K) of OMB and OMA before and after the bias correction for water vapor
channels 8-10 (OMB_nb: OMB without bias correction; OMB_wb: OMB with bias
correction).



Fig.10 Time series of the RMSE for the brightness temperature (unit: K) withassimilation times before and after the data assimilation.



Fig. 11 The surface wind speed (vectors, unit: m s⁻¹) and water vapor (colored, unit:

675 g/kg) for (a) CTNL; (b) AHI_DA at 850 hPa at 0000 UTC 2 August 2015.



Fig. 12 The 48-hour predicted tracks (a) from 0000 UTC 2 August to 0000 UTC 4
August, (b) from 0600 UTC 2 August to 0600 UTC 4 August 2015, (c) averaged track
errors (unit: m s⁻¹) for the two forecasts.



Fig.13 The 48-hour (a) maximum surface wind (unit: m s⁻¹), (b) minimum sea level
pressure (unit: hPa) of Soulder averaged from two forecasts.