Natural Hazards
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Sciences

Discussions

Interactive comment on "Brief communication: 3D reconstruction of a collapsed rock pillar from web-retrieved images and terrestrial LiDAR data – The 2005 event of the West face of the Drus (Mont-Blanc massif)" *by* Antoine Guerin et al.

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Response letter to the Anonymous Referee #2 of the NHESS journal – Guerin et al.: "3D reconstruction of a collapsed rock pillar from web-retrieved images and terrestrial LiDAR data – The 2005 event of the West face of the Drus (Mont-Blanc massif)"

The authors took into account all the general comments and required corrections by both reviewers in the new version of this Brief communication which has been well developed. We first try to quantify more precisely the different sources of errors that influence the estimation of the final volume and to relate them to each step of the method

(number of photos taken into account, SfM method itself, scaling/alignment procedure and mesh smoothing procedure). The authors have also developed the section 2 "Material and methods" in order to clarify the different stages of data processing. Then, on the basis of the Fig. 3C, several illustrations have been added (Fig. 3E and 3F, Fig. 6) in order to better characterize the deviations resulting from the point-to-mesh comparison, particularly in stable areas. Furthermore, as proposed by the reviewer #1, a point density map was added (Fig. 3D) as well Fig. 4 and Fig. 5, so as to better illustrate the methods of rockfall extraction and volume calculation. Finally, the four references suggested by the reviewer #2 have been incorporated into the manuscript. In italics below, you will find the answers to the questions you have asked.

Reviewer #2's questions

Page 1 line 29/30: Please, be more specific about the approach to estimate rock thickness from historical images without doing 3D reconstruction. How reliable is it? This is also relevant because you will compare your own results to this study. Indeed, it was not very clear... For clarity, we replaced "The assessment of this volume by Ravanel and Deline (2008) was performed in two steps: (a) determination of the rock-avalanche scar dimensions (height and width) by making measurements on terrestrial LiDAR data acquired just after the event (October 2005); and (b) estimation of the thickness of the fallen blocks from historical photographs taken from different viewpoints" by "The assessment of this volume by Ravanel and Deline (2008) was performed in two steps: (a) identification on photos of different rock elements (slabs, dihedrons, overhangs) whose dimensions (height, width, depth) can be compared with compartments now collapsed; and (b) measurements of these dimensions on terrestrial LiDAR scans acquired just after the event in October 2005. Historical photographs of the West face taken from different viewpoints facilitate the estimation of the thickness of the missing elements, which remains the most difficult dimension to determine. Under this method, the assessment of rock thickness (8 meters on average) represents the greatest source of uncertainty since the height and width of the rock-avalanche scar could be very accu-

rately measured on the October 2005 LiDAR data." (page 4, line 27 to page 5, line 3)

Page 2 line 14 -21: Maybe, also refer to Eltner et al. (2016) because the authors give a review on SfM used in geosciences and furthermore summarise accuracies achieved at different scales. As well, Smith et al. (2015) could be cited as they review applications and explain the workflow. Eltner et al. (2016) as well as Smith et al. (2016) have been cited in the introduction (page 5, line 19 and page 5, line 24-25). Smith et al. was then quoted for the SfM workflow at the beginning of section 2.4 (page 7, line 28).

Page 3 line 27: If you merge scans from 2005 to 2010 to achieve a detailed 3D model of the upper face, how certain are you that no changes occurred between 2005 and 2010 to allow for a reliable model? Actually, we did not merge the scans from 2005 to 2010. We just used and merged the point clouds of October 2005 and November 2011 after deleting the points belonging to the collapses of September and October 2011, which include the small rockfalls detected by Ravanel (2010) between October 2005 and September 2008. For more information, please refer to section 2.3 (page 7, line 17-26).

Page 4 line 2: Could you geo-reference with ICP because the source cloud for alignment was already geo-located? Yes, "in the absence of a fairly accurate DEM (the resolution of the IGN's DEM is only 30 m in this sector), both datasets were georeferenced using the scanner position measured by dGPS, then aligned with respect to the vertical axis using the coordinates of several points distributed in the cliff and measured with a total station." (page 7, line 15-17)

Page 4 line 3: What do you mean by accurate GPS? Do you refer to dGPS? Furthermore, what did you measure with GPS? The scan position or marker positions? Please refer to the answer to the previous comment.

Page 4 line 6: subtracted. This modification was taken into account in page 7 (line 24).

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Page 4 line 14/15: Did you identify stable areas and subsequently use these to perform ICP? If not, how did you account for potential errors in this regard (e.g. see Wujanz et al., 2016). All alignments performed using the ICP algorithms have been applied to the stable areas, whether to align both LiDAR point clouds with each other or to align by parts the SfM model on the 2005/2011 merged and cleaned LiDAR point cloud. This information has been added in sections 2.3/2.4 and Wujanz et al. (2016) has been cited in section 2.4 (page 8, line 5).

Page 4 line 22-26: I am afraid, I did not understand the procedure. Is the point extraction performed with the point cloud containing the cloud-to-mesh information? Thus, does it account on point cloud distances or solely the topographic information of a single cloud? Sections 2.5 (SfM/LiDAR comparison and rockfall extraction) and 2.6 (Volume calculation) have been substantially modified and Fig. 4, 5 and 6 (pages 19, 20 and 21) have been added to improve the understanding of the methods used in these two paragraphs. I hope it's clearer now. . .

Page 4 line 24: How did you define the LoD (what is your accuracy measure)? Chapter 2.4: What is the average deviation between SfM and Lidar in the stable areas? This could be helpful information to better assess the performance of SfM. Furthermore, the accuracy would be interesting because many images seem to be taken from similar perspectives leading to an unfavourable base-height-ratio potentially resulting in lower accuracies. The LoD ($\pm$ 1.2 m in our case) has been defined "in agreement with the average deviation observed in the stable areas" (page 8, line 21-22) which "reaches $\pm$ 1.17 m" (page 8, line 10). This value was determined from the result of the point-to-mesh comparison and refers to the area framed in Fig. 3A, whose the zoom is visible in Fig. 3E (page 18). Furthermore, in order to better appreciate the reconstruction of the depth in the SfM model, a top view has been added in Fig. 2 (page 17).

Page 5 line 12/13: Why do you choose this as average volume? Furthermore, the random selection of image number (84% and 67%) does not seem to be sufficient to allow for the statement of a relative error. This also accounts to page 6 line 5-7, when

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the Ravanel & Deline (2008) value is chosen as reference. Indeed, choose 311'970 m3 as average volume was not very judicious... Instead, "we consider the volume of 292'680 m3 as the most reliable estimation" (page 9, line 31-32) to define our relative error range. However, in the other error calculation you mentioned, we kept the Ravanel and Deline (2008) value as reference "because of its lower uncertainty range: $\pm$ 3.8 %)". (page 10, line 33)

Please also note the supplement to this comment:
http://www.nat-hazards-earth-syst-sci-discuss.net/nhess-2016-316/nhess-2016-316-AC2-supplement.pdf

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