



**The European
lightning location
system EUCLID –
Part 2**

D. R. Poelman et al.

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The European lightning location system EUCLID – Part 2: Observations

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Abstract

Cloud-to-ground (CG) lightning data from the European Cooperation for Lightning Detection (EUCLID) network over the period 2006–2014 are explored. Mean CG flash densities vary over the European continent, with the highest density of about 6 km⁻² yr⁻¹ found at the triple point between Austria, Italy and Slovenia. The majority of lightning activity takes place between May and September, accounting for 85% of the total observed CG activity. Furthermore, the thunderstorm season reaches its highest activity in July, while the diurnal cycle peaks around 15:00 UTC. A difference between CG flashes over land and sea becomes apparent when looking at the peak current estimates. It is found that flashes with higher peak currents occur in greater numbers over sea than over land.

1 Introduction

Numerous ground-based lightning location systems (LLS) exist to date employing different types of sensors and detection techniques, enabling the user to detect cloud-to-ground (CG) and/or intra- and intercloud electrical activity. As such, it is possible to retrieve not only the geographical and frequency distribution of lightning on a global scale (Jacobson et al., 2006; Keogh et al., 2006; Said et al., 2010, 2011), but detailed information at the level of individual strokes or flashes as well by means of three dimensional reconstruction of the development of the lightning channel as observed by present-day Lightning Mapping Arrays (LMAs) (Krehbiel et al., 1999; Rison et al., 1999, 2000; van der Velde et al., 2011; Defer et al., 2015). Nevertheless, each LLS has its pros and cons. Whereas networks operating at the very-low frequencies (VLF) are able to detect lightning over large distances with relative low amount of sensors, these systems are limited in location accuracy (LA) and detection efficiency (DE) when compared to the LMA performance. On the other hand, LMAs function at very-high frequencies (VHF), thereby restricting the range of observation to very local scales and do

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not detect the ground stroke very well. LLS operating at low frequencies (LF) combine the best of both worlds: with baselines of a few hundred of kilometers it is possible to cover countries as well as continents (e.g. Biagi et al., 2007; Nag et al., 2011, 2013; Schulz et al., 2005; Antonescu and Burcea, 2010; Enno, 2011; Mäkelä et al., 2014), while still retaining a satisfactory level of performance in terms of LA and DE.

While most LLS provide supplementary information such as polarity and peak current of the lightning discharge, it is the spatial flash incidence that remains the main objective. This continuous interest in the spatial distribution of the lightning flash density N_g is not surprising as it is not only of importance for climatological studies, but plays a vital role in the risk analysis for protecting structures and electronic systems against damage from lightning impacts to ground (see risk management in accordance with IEC 62305-2). Various studies exist already in Europe, assessing the lightning climatology at regional scales or within country borders. For instance, Finke and Hauf (1996) observed the lightning occurrence in southern Germany and retrieved a spatial flash density of $2.8 \text{ km}^{-2} \text{ yr}^{-1}$ based on a three-year data set. Schulz et al. (2005) found that over a 10-year observation period, mean flash densities vary between 0.5 and $4 \text{ flash km}^{-2} \text{ yr}^{-1}$ in Austria, whereas according to Antonescu and Burcea (2010) the mean annual CG lightning density in Romania ranges from $0.34 \text{ flashes km}^{-2} \text{ yr}^{-1}$ in the east to $3.06 \text{ flashes km}^{-2} \text{ yr}^{-1}$ on the south, averaged over three observational years. Poelman (2014) reported CG flash densities in Belgium varying between $0.3 \text{ flashes km}^{-2} \text{ yr}^{-1}$ in the west up to $2.4 \text{ km}^{-2} \text{ yr}^{-1}$ toward the east of Belgium, with an average flash density of $0.7 \text{ km}^{-2} \text{ yr}^{-1}$. The lowest values in Europe are found in the northern, Scandinavian countries with flash densities of about $1 \text{ km}^{-2} \text{ yr}^{-1}$ in the southwest of Sweden and Baltic countries, down to $0.01 \text{ km}^{-2} \text{ yr}^{-1}$ along the coast of Norway (Enno, 2011; Mäkelä et al., 2014). While it is clear that over the European continent flash densities vary from one region to another, it is not straightforward to combine latter studies into one coherent picture due to the different LLS, observational periods and grid resolutions used, as well as changes in the performance over time for a particular LLS. Another approach to investigate the European lightning density in a more

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coherent way is by making use of a long-range VLF lightning network. This has been done by Anderson and Klugmann (2014), presenting the observations made by the Met Office Arrival Time Difference Network (ATDnet) over Europe. However, ATDnet's observations contain, similar to other VLF networks, a certain fraction of cloud signals in addition to CG lightning (Jacobson et al., 2006; Poelman et al., 2013b), which has not been accounted for in their analysis. In addition, the spatial distribution of lightning, i.e. CG and cloud lightning, over Europe has been measured by the Optical Transient Detector (OTD) onboard the Orbview-1/Microlab satellite (Christian et al., 2003). Although OTD's measurements are useful in providing the overall spatial behavior over large areas, the absolute lightning density should be interpreted with caution as a result of the moving field of view.

In this paper we report on the cloud-to-ground lightning characteristics over most of Europe based on the observations of the European lightning location system EUCLID. Figure 1 displays the current sensor locations within the EUCLID network and the region of investigation for the following analyses. The performance of EUCLID has been frequently tested over the years in terms of its location accuracy (LA), detection efficiency (DE) and peak current estimation. For the latest in-depth analysis of the performance validation of EUCLID in Europe, the interesting reader is referred to Schulz et al. (2015). A description of the treatment of the data and methodology is provided in Sect. 2. Section 3 is reserved to display the temporal and spatial statistics along with an analysis of the multiplicity and peak current estimates. We conclude and summarize in Sect. 4.

2 Data and methodology

Since the start of EUCLID in 2001, its performance improved gradually over the years. This improvement is attributed to an increased number of sensors contributing to the network, but is also due to the upgrade of the older type of sensors into the newest LS700x sensor technology and by the implementation of advanced processing algo-

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rithms (Schulz et al., 2015). Nevertheless, for the purpose of this study it can be assumed that from 2006 onward the improvements to the network in terms of flash detection efficiency and location accuracy will have minor influence on the outcome presented in the remainder of this paper. This is true, since even though the stroke DE has improved, the flash DE remained rather stable since to detect a flash it is sufficient to identify successfully solely one stroke out of several in a multi-stroke flash. As such, we opt to use flash data from 2006 until 2014 in this study. In addition to CG detections, EUCLID is able to detect part of the strongest cloud-to-cloud (CC) discharges as well, using the capability of the LS700x sensors. The discrimination between CC and CG discharges is based on peak-to-zero threshold values. Note that in this work we consider each CC signal as an individual CC flash.

Initial CG stroke data has been grouped into CG flashes, with individual strokes belonging to a particular flash if $\Delta t < 1.5$ s and $\Delta r < 10$ km, with respect to the time and position of the first stroke in the flash. In addition, a temporal interstroke interval criterion, $\Delta t_{\text{interstroke}}$, of 0.5 s is used as well. These grouping criteria overlap well with those used in other studies (e.g. Cummins et al., 1998; Kuk et al., 2011), except for the more relaxed time criterion, compared to a Δt of 1 s what is traditionally used. Since occasionally flashes are observed with a duration exceeding 1 s (Poelman et al., 2013a), the time criterion used in this work is justified. The position and peak current of the first return stroke are chosen as the position and peak current of the CG flash, respectively. Note that positive discharges with peak currents smaller than 10 kA are likely to be misclassified as CG strokes when in fact those are more likely to be of intracloud nature (Cummins et al., 1998; Wacker and Orville, 1999a, b; Jerauld et al., 2005; Orville et al., 2002; Cummins et al., 2006; Biagi et al., 2007; Grant et al., 2012). Therefore, we opt to remove them from the dataset. About 5 % of all the flashes that are removed in this way are single stroke positives. In addition, after removing those particular positive strokes in a multiple-stroke flash, about 3 % of the flashes remain to be bipolar flashes. Because often positive cloud strokes are wrongly grouped to negative CG flashes, those bipolar flashes have been removed as well, such that the

final flash data set contains only flashes with strokes of the same sign belonging to a particular flash.

Geographical plots are presented with a spatial resolution of $20 \text{ km}^2 \times 20 \text{ km}^2$, or stated otherwise. Note that this adopted grid size is much larger than the assumed LA of EUCLID within Europe and is therefore appropriate for this study. Moreover, it can be demonstrated that an uncertainty in flash density of less than 20 % at 90 % confidence level is obtained, when the minimum requirements are satisfied by following equation:

$$N_g \times T_{\text{obs}} \times A_{\text{cell}} \geq 80, \quad (1)$$

with T_{obs} the observation period and A_{cell} the grid cell area expressed in years and km^2 , respectively (Diendorfer, 2008). Hence, with an observation period of 9 years and a grid cell area of 400 km^2 , regions with flash densities down to 0.02 flashes per km^2 per year are still accurately depicted in this way. Spatial distribution maps of, for example, the flash density or peak current are then obtained by summing the relevant parameter and dividing it by the amount of flashes observed per grid cell. Considering the excellent flash DE, no correction factor has been applied to the flash data in the course of this study.

3 Results and analysis

3.1 Temporal statistics

Figure 2a plots the temporal distribution of the CG stroke and flash count over the years, observed within the polygon displayed in Fig. 1. As expected, the CG activity experiences a natural annually variability, with an observed minimum of $\sim 31 \times 10^5$ flashes in 2012 and increasing up to $\sim 54 \times 10^5$ flashes in 2006. Annual variations are found as well in other parts of the globe and are attributed to the natural variability of the climate (Ghil, 2002). In addition, the CC/CG flash ratio is indicated as

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is 55 %, and increases up to 95 % for positive flashes. 85 % of all negative flashes have been observed with three strokes or less. We find a mean multiplicity of 2.1 and 1.1 for negative and positive flashes, respectively. This is an underestimation when compared to ground truth recordings. For instance, based on ground truth recordings in Belgium, Poelman et al. (2013a) found a mean multiplicity for negative flashes of 3.7, while similar multiplicities are found in comparable ground truth studies at different regions (Rakov and Huffines, 2003; Saraiva et al., 2010; Ballarotti et al., 2012). Likewise, the high percentage of single stroke negative flashes is an overestimation with respect to ground truth observations, reporting in general values in between 20 and 40 % (Fleenor et al., 2009; Biagi et al., 2007; Poelman et al., 2013a). This overestimation of the amount of single-stroke flashes is observed by many other ground-based networks as well (Rakov and Huffines, 2003; Schulz et al., 2005; Poelman et al., 2013a) and can be related to the fact that first strokes tend to be, in general, more easily detected by a lightning location system (LLS) because of its higher peak current compared to the subsequent strokes. Additionally, outliers and misclassified cloud pulses which are not in time and distance close to another stroke influence the percentage of single-stroke flashes. As such, the amount of observed single-stroke flashes by EUCLID is increased by a fraction of multi-stroke flashes from which only one stroke is detected.

Figure 5b plots the spatial distribution of the multiplicity of negative flashes. The minimum is found at the limits of EUCLID's boundary and is a consequence of a drop in detection efficiency where only the strongest strokes within a flash tend to be detected. The spatial variance in Fig. 5b can be attributed to orography, cloud altitude and latent heat of the surface, intrinsic to specific areas. Note that a negative CG flash with a maximum multiplicity of 49 has been recorded. The latter was a flash to a tall radio and TV tower in the south of Austria, at the border of Italy and Slovenia. The overall highest multiplicities are found over the southern part of the Bay of Biscay, the Adriatic Sea and the Mediterranean Sea.

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3.4 Lightning peak current

Peak current estimates by EUCLID have been compared against direct measurements, made possible by dedicated instruments installed on the Gaisberg tower in Austria (Diendorfer et al., 2009). One can deduce a median peak current estimation error of 4% compared to the measured peak currents at the Gaisberg tower (Schulz et al., 2015).

Mean/median peak current for negative and positive first strokes is $-18.6/-15.0$ kA and $+34.5/+22.2$ kA, respectively. In absolute terms, positive first strokes have higher peak currents compared to their negative counterparts. Subsequent negative strokes have mean/median peak currents of $-15.2/-14.0$ kA, and are hence lower compared to negative first strokes.

Figure 6a shows the cumulative statistical distribution of return stroke peak currents for negative first strokes, negative subsequent strokes, and positive strokes. It enables to view the percentage of peak currents exceeding a particular value on the horizontal logarithmic axis. The vertical axis is chosen in such a way so that a Gaussian (normal) cumulative distribution appears as a slanted straight line. The cumulative distribution for the negative first and subsequent strokes resembles almost a straight line, but is certainly not so for the positive strokes being non-linear around the low and high estimated peak currents. One deduces that about 50% of the negative first and subsequent strokes exhibit peak currents larger than 15 kA, whereas this increases to 22 kA for positive first strokes. In general one finds that negative first strokes have higher peak currents compared to the subsequent negative strokes, but is lower than the peak currents deduced for positive strokes. The respective 95, 50 and 5% values following the peak current distributions are summarized in Table 1.

Figure 6b plots the monthly distribution of the mean, median and 95th percentile peak current for negative and positive strokes. It is found that during the summer months the lowest values are found, with higher estimated peak currents observed toward the end/beginning of the year. Such a behavior has been demonstrated as well in the US

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(Brook, 1992), and is believed to be related to the observation that electric-field initiating lightning during winter is greater than during summer. Hence, discharges produced during the winter tend to exhibit more energetic discharges with higher peak currents (Brook, 1992).

5 Figure 7a and b display the spatial distribution of the geometric mean and 95th percentile of estimated peak current currents in negative flashes. Over large parts of mainland Europe, the mean values range in between -20 and -5 kA. However, a clear transition between land and sea alongside the Italian and Sardinian coast and the Adriatic Sea is noticed. This becomes more obvious when looking at the 95th percentile in
10 Fig. 7b. Figure 7c zooms in on a particular interesting region in the Mediterranean Sea, indicated by the white box in Fig. 7b. This region in particular is well covered by multiple EUCLID sensors positioned inland and along the coast of France and Italy. In addition, one sensor is located in the southwest of the island Corsica. Even though the observed change in the peak current behavior is in line with the findings along the coast of US by the global GLD360 and WWLLN networks (Said et al., 2013; Hutchins
15 et al., 2013), one can speculate that it is an artifact of the change in conductivity which is not accounted for by the central processor, or simply due to an instrumentation effect or resulting from sensor coverage issues over sea. However, apart from the findings along the US coast, Corsica is well covered by the lightning sensors and exhibits a decrease in peak current magnitude compared to the surrounding water mass. This
20 strengthens the hypothesis that the observed peak current behavior is real. The same behavior, although less pronounced, holds for the subsequent strokes, as evidenced in Fig. 7d. In addition, the contrast between land and sea lightning becomes evident when looking at the CG flash density of negative flashes with estimated peak currents larger
25 than 75 and 100 kA, plotted in Fig. 8a and b, respectively. It is striking that flashes with higher peak currents primarily occur in greater numbers over sea than on land.

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4 Summary

Due to the variable nature of lightning occurrence from year to year, reliable insights into the lightning activity and parameters can only be achieved when based on large amounts of data. In this work, a total of 32 million CG flashes recorded in between 2006 and 2014 are used to analyze the spatial and temporal characteristics within the EUCLID domain.

It is found that the lightning activity primarily takes place between May and September, accounting for about 85 % of the total observed lightning activity. The thunderstorm season reaches its peaks in July. As regards the diurnal flash counts, those are the lowest during the morning hours, followed by a continuous increase from 10:00 UTC up to 15:00 UTC.

In addition, the observed peak current distribution displays a discrepancy between land and sea, favoring higher peak current flashes over sea than over land.

Acknowledgements. The authors are grateful to the support from all the EUCLID members.

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Table 1. Peak current cumulative statistical distribution values.

| Peak current [kA] | Percentage exceeding tabulated value | | |
|----------------------|--------------------------------------|------|-----|
| | 95 % | 50 % | 5 % |
| First neg. strokes | 4 | 15 | 57 |
| Subseq. neg. strokes | 5 | 14 | 35 |
| First pos. strokes | 10 | 22 | 96 |

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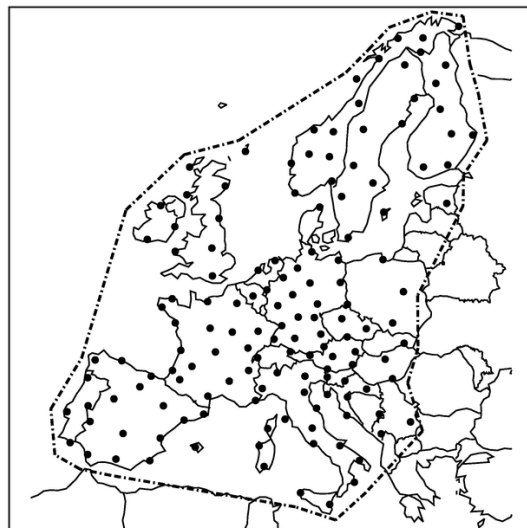


Figure 1. Sensor locations within the EUCLID network. Note that only data within the polygon (dash-dotted line) is used for quantitative analysis in this work.

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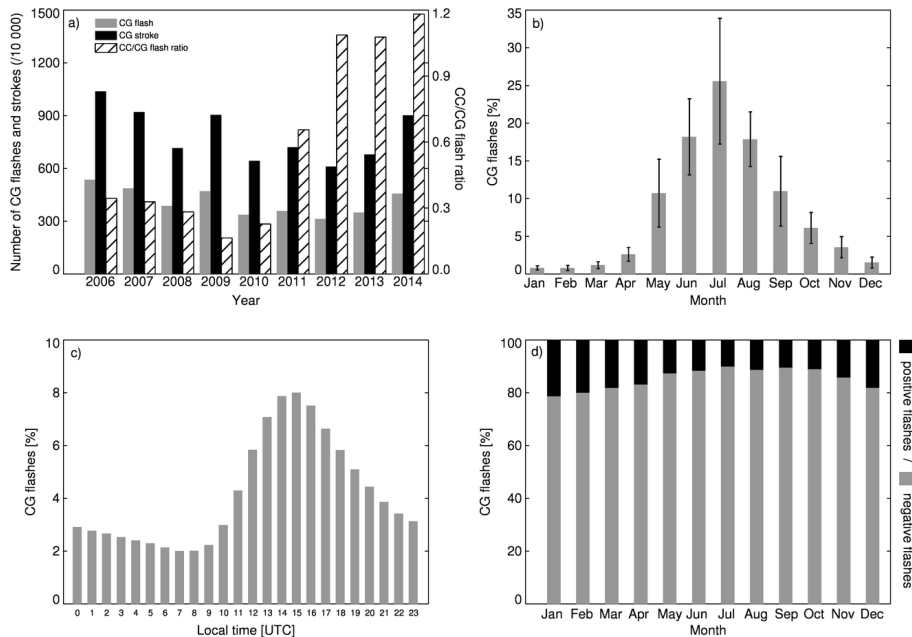


Figure 2. (a) Variation of the annual CG stroke and flash counts, as well as the CC/CG flash ratio, (b) mean monthly flash counts with bars representing the ± 1 SD (standard deviation), (c) mean diurnal flash counts and (d) mean monthly polarity distribution, based on 2006–2014 EUCLID data.

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The European lightning location system EUCLID – Part 2

D. R. Poelman et al.

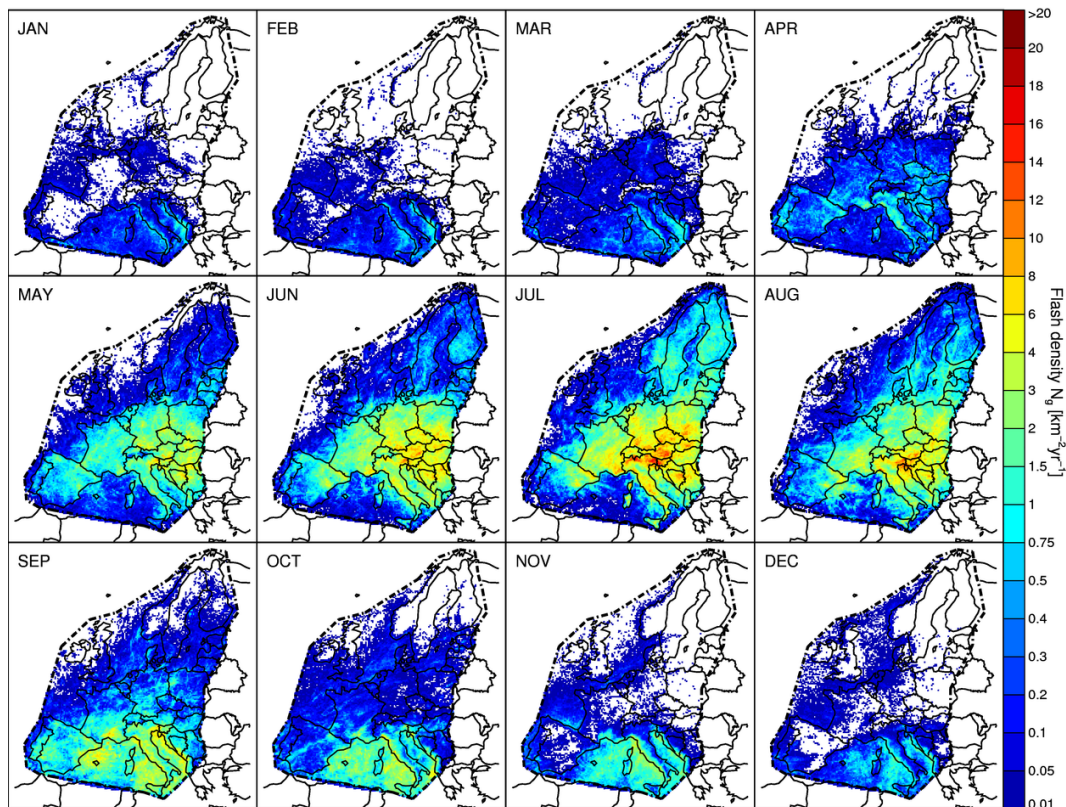


Figure 4. Monthly variability of flash density N_g [$\text{km}^{-2} \text{yr}^{-1}$], based on 2006–2014 EUCLID data and adopting a spatial resolution of $20 \text{ km}^2 \times 20 \text{ km}^2$.

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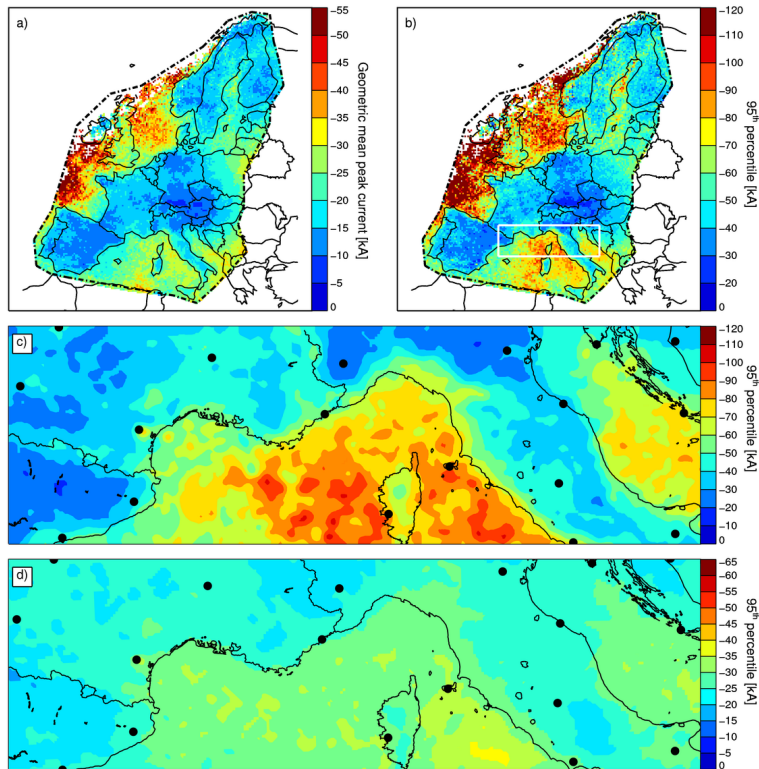


Figure 7. Distribution of **(a)** geometric mean, and **(b)** 95th percentile of the peak current [kA] from first strokes in negative flashes, based on 2006–2014 EUCLID data and adopting a spatial resolution of $20 \text{ km}^2 \times 20 \text{ km}^2$. **(c)** Zoom-in as outlined by the white box in **(b)**, smoothed by a Gaussian filter for clarity. **(d)** Same as **(c)**, but for subsequent strokes. In addition, the sensor locations are indicated in **(c)** and **(d)**.

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