

GIS and Remote Sensing Techniques for the Assessment of Land Use Changes Impact on Flood Hydrology: the Case Study of Yialias Basin in Cyprus

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Abstract

Flooding is one of the most common natural disasters worldwide, leading to economic losses and loss of human lives. This paper highlights the hydrological effects of multi-temporal land use changes in flood hazard within the Yialias catchment area, located in central Cyprus. A calibrated hydrological model was firstly developed to describe the hydrological processes and internal basin dynamics of the three major sub-basins, in order to study the diachronic effects of land use changes. For the implementation of the hydrological model, land use, soil and hydrometeorological data were incorporated. The climatic and stream flow data were derived from rain and flow gauge stations located in the wider area of the watershed basin. In addition, the land use and soil data were extracted after the application of object oriented nearest neighbor algorithms of ASTER satellite images. Subsequently, the Cellular Automata

1 (CA) -Markov chain analysis was implemented to predict the 2020 Land use / Land cover
2 (LULC) map and incorporate it to the hydrological impact assessment. The results denoted
3 the increase of runoff in the catchment area due to the recorded extensive urban sprawl
4 phenomenon of the last decade.

5

6 **1 Introduction**

7 Land use and floods are closely related; therefore, any changes in the land use, such as
8 urbanization across the catchment's area, may trigger-off a sequence of flood occurrences
9 (Hadjimitsis, 2010). The current and future development in water resources is very sensitive
10 to land use and intensification of human activities. It is expected that flood risk will continue
11 to rise, as a consequence of a combination of climate change (e.g. Kundzewicz et al., 2005;
12 Tsanis et al., 2011; Grillakis et al., 2011) and an increase in exposure vulnerability (e.g., due
13 to increasing flood plain occupancy), increase in endangered areas and changes in the
14 terrestrial system (e.g. land cover changes and river regulation; see Elmer et al., 2012).
15 Human transformation of the Earth's land surface seems to have multiple consequences for
16 biophysical systems at all scales (Roosmalen et al., 2009). During the past decades, airborne
17 and spaceborne remote sensing technologies along with Geographical Information Systems
18 (GIS) have widely used for flood monitoring, including flash floods (Taubenbock et al.,
19 2011).

20 Flash floods respond to the causative storms in a short period of time, with water levels in the
21 drainage network reaching peak levels within a few minutes or hours, allowing for a very
22 limited time-window for warnings to be prepared and issued (Koutroulis and Tsanis, 2010;
23 Grillakis et al., 2010). Modeling of floods has greatly improved in recent years, with the
24 advent of GIS, satellite remote sensing imagery, high-resolution digital elevation models
25 (DEMs), distributed hydrologic models, and development of real time flood forecasting and
26 delivery systems on the internet (Garrote and Bras, 1995; Bedient et al., 2003). Hydrological
27 and hydraulic simulation models are essential tools to evaluate potential consequences of
28 proposed strategies and to facilitate management decisions. Nowadays satellite remote
29 sensing has the potential to provide extensive coverage of key variables such as precipitation
30 and soil moisture as well as many of the parameters such as vegetation cover, vegetation
31 change and imperviousness that are important inputs to modern hydrological models (De
32 Fries and Eshelman, 2004). According to Mao and Cherkauer (2012), human activity is one of

1 the major driving forces leading to changes in land cover characteristics and subsequently
2 hydrologic processes. Land use influences the infiltration and soil water distribution process
3 because saturated hydraulic conductivity is influenced by plant roots and pores resulting from
4 the presence of soil fauna (Ragab and Cooper, 1993; Fohrer et al., 2000). A characteristic
5 example is the influence of buildup areas and roads on overland flow, flood frequency and
6 magnitude (Nejadhashemi et al., 2011). Therefore, land cover plays a key role in controlling
7 the hydrologic regime of a catchment area through a number of different parameters such as
8 leaf area index, evapotranspiration, soil moisture content and infiltration capacity, surface and
9 subsurface flow regimes including base-flow contributions to streams and recharge, surface
10 roughness, run off as well as soil erosion through complex interactions among vegetation,
11 soils, geology, terrain and climate processes.

12 Especially, urban areas are prone to flooding due to the large proportion of impermeable
13 surface cover such as concrete that increases the total volume of runoff and peak flows and
14 shortens the time that the floodwaters take to arrive at peak runoff (Hall, 1984, Knebl, 2005).
15 In various studies, historical and present land-use/cover patterns or extreme scenarios have
16 been used as input in hydrologic models to determine hydrologic responses to different
17 scenarios in a combined integrated approach (Moiwo et al., 2010; Hong et al., 2010). At
18 different watershed scales, several researchers (Savary et al., 2009; Schilling et al., 2010;
19 Turnbull et al., 2012) have developed various methods aiming at quantifying the hydrologic
20 alterations in relation to land-cover change.

21 VIDAncHqThis paper attempts to quantify the sensitivity of the distributed hydrological
22 model to the land use and soil parameterizations, in order to simulate runoff processes in a
23 catchment area in Cyprus, namely Yialias watershed. Specifically, the potential use of remote
24 sensing in providing hydrological models with adequate, reliable and updated land use data is
25 highlighted. The major flood event that occurred between 12-13 February 2003 was
26 successively simulated with the use of multi-temporal land use data of the specific period
27 (data of 2000) and data of 2010 (keeping the same meteorological parameters).

28 The aim of this approach was to assess the impact of land use changes (including conversions
29 between different land-use types and shifts in the geographic extent of those land-use types)
30 to the run off processes and hydrologic response. In the following, a CA -Markov chain
31 analysis was implemented to calculate and predict the area's LULC regime for 2020 and
32 incorporate it to the hydrological model for assesing watershed's basin response. The
33 hydrological model used is the HEC-HMS in distributed mode to utilize the modified Clark

1 (Clark, 1945) method of transforming the excess rainfall to runoff. Moreover, the USDA SCS
2 curve Number method (SCS, 1985) was used to account for the precipitation losses. The SCS
3 curve number method is amongst the more widely used methods of assessing the effect of
4 land-use change in the hydrological response (Defries and Eshleman, 2003).

5 **2 Study area and Resources**

6 Located in the central part of the island of Cyprus, the catchment area of the study is about
7 110 km² in size with an average slope value of 7.19 % (Fig. 1a). Specifically the study area is
8 situated between longitudes 33° 11' 24. 28'' and 33° 26' 31. 52'' and latitudes 34°54'36,.74''
9 and 35°2' 52.16'' (WGS' 84, 36°N). In the past few years, the specific catchment area has
10 been undergoing intensive land use change due to rapid economic growth and urbanization.
11 The island of Cyprus is located in the northeastern-most corner of the Mediterranean Sea and,
12 therefore, has a typical eastern Mediterranean climate: the combined temperature – rainfall
13 regime is characterized by cool-to-mild wet winters and warm-to-hot dry summers
14 (Michaelides et al., 2009).

15

16 **Figure 1.**

17

18 For the purposes of the study, the following satellite and digital spatial data were utilized: a)
19 Two ASTER Images with 10 year time interval in order to monitor the multi-temporal urban
20 sprawl phenomenon. For this study, the first three spectral bands were used (VNIR and
21 SWIR) with spatial resolution of 15 m. The exact acquisition dates of the images were:
22 12/05/2000 and 06/04/2010.

23 b) A Digital Elevation Model (DEM) of 10 m pixel created with the use of orthorectified
24 stereo-pairs of aerial photos (scale 1:5000) covering the study area.

25 The meteorological data were provided from the Meteorological Service of Cyprus. More
26 specifically, time-series rainfall data of 6 rain gauge stations for a period of 20 years (1990-
27 2010) was provided. Flow data from 3 stream gauges stations (Kotsiati, Nisou, Potamia) were
28 provided from the Water Development Department of Cyprus (Table 1). From the available
29 data, the most severe hydrological events were used to calibrate the hydrological model. The
30 spatial distribution of rain and stream flow gauge stations in the vicinity of the catchment area
31 is shown in Figure 1b.

1

2 **Table 1.**

3

4

5 **3 Methodology**

6 Initially, pre-processing techniques such as geometric, radiometric and atmospheric
7 corrections were applied to both satellite images. Sophisticated classification techniques, such
8 as object oriented analysis, were implemented and diachronic LULC maps of the study area
9 were developed (for the time period of 2000 – 2010). Using these LULC datasets, the CA-
10 Markov algorithm was applied and the LULC map of 2020 time period was predicted. In
11 addition, the area's soil map was developed in a GIS environment. In the following, LULC
12 maps, soil map, DEM, meteorological and flow data for different time periods were
13 incorporated in HEC – HMS (Hydrologic Engineering Center's – Hydrologic Modelling
14 System) hydrological software for implementing hydrological modelling in GIS environment.
15 Firstly, the model was calibrated for three precipitation events and then was validated for a
16 major flood event that occurred in 2003. Finally, the same precipitation data of 2003 were
17 once again incorporated to estimate the updated Curve Number map for 2010 and 2020 and
18 assess the watershed's hydrological response under different land cover conditions. The
19 overall proposed methodology is presented in the flowchart of Figure 2.

20

21 **Figure 2.**

22

23 **3.1. Pre-processing techniques**

24 Regarding the preprocessing of the images, geometric corrections were carried out using
25 standard techniques with several ground control points (GCP's) and a second order
26 polynomial fit. For this purpose, detail topographical maps (scale 1:5000 and 1:2000) were
27 used to track the position of GCP's in conjunction with the digital shoreline of Cyprus
28 extracted from detail topographic maps (scale 1:5000). At a next step, radiometric corrections
29 were applied to ASTER images. Radiometric corrections are essential for satellite images,
30 since illumination's changes (e.g., Earth to sun distance correction) and changes in viewing

1 geometry (e.g., sun elevation correction) should be minimized in multi-temporal analysis.
2 Thus, the DN (Digital Number) values were converted to reflectance values.

3 Atmospheric correction is considered to be one of the most difficult techniques since the
4 distributions and intensities of these effects are often inadequately known. Despite the variety
5 of techniques, used to estimate the atmospheric effect, atmospheric correction remains a hard
6 task in the pre-processing of image data. As it is shown by several studies (Hadjimitsis et al.,
7 2004; 2010; Agapiou et al., 2011), the darkest pixel (DP) atmospheric correction method can
8 be easily and accurate applied either by using dark and non-variant targets located in the
9 image or by conducting in situ measurements. In the present study, water dams were used as
10 dark targets and the darkest pixel correction was applied to both images.

11

12 **3.2. Object oriented classification**

13 According to Alexakis et al. (2012a), spectral mixing in satellite images between marl / chalk
14 geological formations and urban areas was widely observed in Yialias catchment area and
15 especially in its downwards part. This problem is clearly denoted in the spectral signature
16 diagram derived from the use of the handheld GER 1500 spectroradiometer. The GER 1500
17 spectroradiometer can record electromagnetic radiation between 350 nm up to 1050 nm. For
18 the purposes of this study, different targets (Fig. 3) from the Yialias watershed basin were
19 selected and their corresponding samples were collected (Soil [Marl / Chalk] A, B, C, - Roof
20 – Tile). Laboratory spectroradiometric measurements were consecutively carried out for each
21 different sample. A final mean measurement corresponding to ASTER bands was extracted
22 from the ten measurements and for this transformation the Relative Response Filters (RSR) of
23 ASTER satellite was used. RSR filters describe the relative sensitivity of the satellite sensor
24 to radiance at various parts of the electromagnetic spectrum (Wu et al., 2010) and their values
25 range from 0 to 1. Bandpass filters are used in the same way in spectroradiometers in order to
26 transmit a certain wavelength band and block others. Therefore, the broadband reflectance
27 from the spectroradiometer was calculated based on the wavelength of ASTER sensor and the
28 RSR filter as follows:

$$29 \quad R_{band} = \frac{\sum (R_i * RSR_i)}{\sum RSR_i} \quad (1)$$

30

- 1 where,
- 2 R_{band} = reflectance at a range of wavelength (e.g., Band 1)
- 3 R_i = reflectance at a specific wavelength (e.g., $i= 450$ nm)
- 4 RSR_i = Relative Response value at the specific wavelength

5

6 **Figure 3.**

7

8 According to the results (see Fig. 4), there is a spectral similarity between soil and urban
9 signatures. This fact clearly depicted the unavoidable need for the application of alternative
10 classification techniques such as object oriented classification.

11 Object based classification methodology begins with the construction of segmented objects at
12 multiple levels of scales as major units for image analysis, instead of using a per pixel basis of
13 single scale for image classification (Stow et al., 2007). Therefore, one of the main
14 advantages of using objects in classification process is that, in addition to spectral
15 information, objects have numerous geographical and geometrical features attributed to them,
16 including shape, length and topological entities, such as adjacency (Baatz et al., 2004). A
17 group of pixels having similar spectral and spatial properties is considered as an object in the
18 object-based classification prototype.

19 Initially, the object based approach involves the segmentation of image data into individual
20 objects. According to Willhauck et al. (2000) and Alexakis et al. (2012b), the images
21 segmentation is mainly influenced by the parameters of scale, color and form. The size of the
22 image object is determined according to a scale parameter which allows for more objects to be
23 merged and fused as values become larger. The form parameter is a combination between the
24 smoothness and the compactness of segment's borders. The weighting of these parameters
25 establishes the homogeneity criterion for the object patterns (Whiteside et al., 2011).

26 In this study, appropriate values were assigned to three key parameters: shape, compactness
27 and scale. The shape parameter, which adjusts spectral homogeneity compared to object's
28 shape, was set to 0.1 in order to give less weight to shape since urban and marl / chalk classes
29 did not have a specific shape. The compactness parameter balances compactness/smoothness
30 and determines the object shape between compact edges and smooth boundaries. It was set to
31 0.5 in order to balance equally the compactness and smoothness of the objects. However, the

1 most crucial factor of segmentation process is the adjustment of scale which controls the
2 object size. Thus, the higher the value of scale parameter, the larger the extracted segmented
3 objects. Following, the evaluation of several different scale parameters, a value of 10 was
4 selected. Thus, the images were initially segmented (Fig. 4a) into object primitives or
5 segments using the multi-resolution algorithm which according to Baatz et al. (2003) follows
6 the fractal net evolution algorithm.

7 The classification process identified and implemented seven major different classes
8 (Agriculture Generic [general unidentified croplands], Agriculture Close Grown [dense
9 cultivated croplands (usually wheat)], Herbaceous [mixture of grass, weeds, and low-growing
10 brush, with brush the minor element], Forest Mixed, Olive Trees, Urban fabric, Water) by
11 using the nearest neighbour classification algorithm (Fig. 4b ; 4c) The main advantage of the
12 nearest neighbour classification algorithm is that it allows unlimited applicability of the
13 classification process to other areas and requires only the additional selection of new training
14 samples until a satisfactory result is obtained.

15 At the end, with the specific classification approach, the *Kappa* coefficient values were
16 increased from the initial values of lower to 0.6 for both 2000 and 2010 images to 0.78 and
17 0.80, accordingly.

18

19 **Figure 4.**

20

21 **3.3. Soil Map**

22 The soil map was constructed in GIS environment according to local hydrogeological maps
23 regime, local soil data and HEC-HMS soil classes. The final map was a three-class
24 generalized soil map of the area (Fig. 5). Specifically, Vergennes is a very deep, moderately
25 well drained soil of sandy loam composition concerning the specific area. Windsor consists
26 of very deep, excessively drained soil which for the specific area is of coarse sandy loam
27 composition. Covington consists of very deep, poorly drained soil that is formed in calcareous
28 glaciolacustrine and estuarine clays mainly found in the northeastern part of the basin.

29

30 **Figure 5.**

1

2 **4 Prediction of Urban Sprawl phenomenon**

3 The Stochastic Markov chain Model was implemented to test whether urban expansion could
4 be predicted for 2020 using the ASTER data of both 2000 and 2010. According to Ahmed and
5 Ahmed (2012), this kind of predictive land cover change modeling is appropriate when the
6 past trend of land cover is known.

7 Urban growth modeling has evolved over recent years to capture increasingly well the details
8 of urban morphology and structure at a qualitative as well as a quantitative level (Rimal,
9 2005). Land use change transition probability in Markov analysis indicates the probability of
10 making a transition from one land use class to another within two discrete time periods. The
11 Markov chain equation was constructed using the land cover distributions at the beginning
12 (M_t) and at the end (M_{t+1}) of a discrete time period, as well as a transition matrix (MLC)
13 representing the land cover changes that occurred during that period. In a Markov chain the
14 probability of the next state is only dependent upon the current state. This is called Markov
15 property as shown in the equation 2 (Ahmed and Ahmed, 2012):

$$16 \quad P(\xi_{t+1} = X_{i_{t+1}} | \xi_1 = X_{i_1}, \dots, \xi_t = X_{i_t}) = P(\xi_{t+1} = X_{i_{t+1}} | \xi_t = X_{i_t}) \quad (2)$$

17 where, the probability Markov chain ξ_1, ξ_2, \dots can be calculated as:

$$18 \quad P(\xi_1 = X_{i_1}, \dots, \xi_t = X_{i_t}) = P(\xi_1 = X_{i_1}) * P(\xi_2 = X_{i_2} | \xi_1 = X_{i_1}) * P(\xi_t = X_{i_t}) * P(\xi_{t-1} = X_{i_{t-1}}) \\ 19 \quad (3)$$

20 Under the assumption that the sample is representative of the region, these proportional
21 changes become probabilities of land cover change over the entire sample area and form the
22 transition matrices. However, the model is not spatially explicit and does not provide
23 explanation the processes leading to changes and overlooks the spatial distribution of land
24 cover in predicting land cover (Lambin et al., 1994; Adhikari et al., 2012).

25 The transition probability matrix explains the probability that each land cover category will
26 change into another category. Specifically, it refers to the number of pixels that are expected
27 to change from each land cover type to every other type over the specified number of time
28 units (Kityuttachai et al., 2013). CA- Markov methodology underlies dynamics of the change
29 events based on proximity concept so that the regions closer to existing areas of the same
30 class are more probable to change to a different class (Memarian et al., 2012). A combined

1 Markov and Cellular Automata (CA-Markov) was used to predict the area's land cover
2 regime for the year 2020. The CA-Markov analysis was run to test a pair of land cover images
3 (2000 and 2010) and output the transition probability matrix (Table 2). As it is indicated in
4 Table 2, the Forest Mixed and Olive Trees classes have significant possibility to change to
5 urban land cover in the near future.

6

7 **Table 2.**

8

9 After the implementation of CA Markov model, the land use area statistics were thoroughly
10 examined (Fig. 6a). The results indicated a steady increase of urban land cover within the
11 catchment area which is expected to range in a percentage of around 100 % until 2020 as well
12 as a respective increase of agricultural generic and olive trees classes. In addition, significant
13 decrease of agricultural close grown land cover is recorded for 2010 and is predicted for 2020.
14 Those characteristic changes are also presented in the relative differences (%) diagram (Fig.
15 6b).

16

17 **Figure 6.**

18

19 **5 Hydrological Modeling**

20 **5.1. The hydrological model HEC-HMS**

21 The Hydrologic Modeling System (HEC-HMS) is designed to simulate the precipitation-
22 runoff processes of dendritic watershed systems. It is developed to be applicable in a wide
23 range of geographic areas for solving the widest possible range of problems. This includes
24 large river basin water supply and flood hydrology and small urban or natural watershed
25 runoff (HEC-HMS User's Manual, 2001).

26 The basic rainfall runoff processes than need to be simulated in HEC - HMS for flood flow
27 estimation using rainfall data as input are the rainfall losses and the transformation of excess
28 rainfall to runoff. For calculating rainfall losses the SCS Curve Number method was used and
29 for the transformation of excess rainfall to runoff the Mod Clark method was used both
30 applied in GIS environment.

1

2 **5.2. The Mod Clark method**

3 The modified Clark (ModClark) model in HEC-HMS is a distributed parameter model in
4 which spatial variability of characteristics and processes are considered explicitly (Kull and
5 Feldman, 1998; Peters and Easton, 1996). This model accounts explicitly for variations in
6 travel time to the watershed outlet from all regions of a watershed. The ModClark algorithm
7 is a version of the Clark unit hydrograph transformation modified to accommodate spatially
8 distributed precipitation (Clark, 1945). Runoff computations with the ModClark model
9 explicitly account for translation and storage. Storage is accounted for within the same linear
10 reservoir model incorporated in the Clark model. Translation is accounted for within a grid-
11 based travel-time model $t_{cell}=t_c \cdot (d_{cell}/d_{max})$ (HEC, 2000), where t_c is the time of
12 concentration for the subwatershed and is a function of basin's length and slope, d_{cell} is the
13 travel distance from the cell to the outlet, and d_{max} is the travel distance from the cell
14 furthest from the outlet. The method requires an input coefficient for storage, R , where R
15 accounts for both translation and attenuation of excess precipitation as it moves over the basin
16 toward the outlet. Storage coefficient R is estimated as the discharge at the inflection point on
17 the recession limb of the hydrograph divided by the slope at the inflection point. The
18 translation hydrograph is routed using the equation:

$$19 \quad Q(t)=\left[\frac{\Delta t}{R+0.5\Delta t} I(t) \right] + \left[1 - \frac{\Delta t}{R+0.5\Delta t} Q(t-1) \right] \quad (4)$$

20 where, $Q(t)$ is the outflow from storage at time t , Δt is the time increment, R is the storage
21 coefficient, $I(t)$ is the average inflow to storage at time t and $Q(t-1)$ is the outflow from
22 storage at previous time $(t-1)$.

23

24 **5.3. SCS Curve number loss method**

25 The SCS (Soil Conservation Service) curve number loss method is a simple, widely used and
26 efficient method for computing excess rainfall (direct runoff) from a rainfall event in a
27 particular area. The curve number is based on the area's hydrologic soil group, land use,
28 treatment and hydrologic condition, with the first two having the greatest importance. The
29 SCS Runoff Curve Number (CN) method is described in detail in NEH (National Engineering
30 Handbook) - 4 (SCS 1985). The SCS runoff equation is:

$$Q = \frac{(P - IA)^2}{(P - IA) + S} \quad (5)$$

where Q is the runoff volume, P the precipitation volume, IA is the initial abstraction and S field capacity.

A linear relationship between IA and S was suggested by SCS (1985), as shown in Eq. 6.

$$IA = \lambda \times S \quad (6)$$

where, λ = initial abstraction ratio. With $\lambda = 0.2$ in Eq. 3, Eq. 2 is transformed into the following equation:

$$Q = \frac{(P - 0,2S)^2}{P + 0,8S} \quad (7)$$

For convenience in practical applications, S is mapped into a dimensionless parameter CN (i.e., the curve number) which varies in the more appealing range between 0 and 100. The chosen mapping equation is presented as follows, for SI units.

$$S = \frac{25400 - 254CN}{CN} \quad (8)$$

5.4. Performance estimators

Nash-Sutcliffe efficiency E

The efficiency E proposed by Nash and Sutcliffe (1970) is defined as one minus the sum of the absolute squared differences between the predicted and observed values normalized by the variance of the observed values during the period under investigation. It is estimated by equation:

$$E = 1 - \frac{\sum_{i=1}^n (O_i - P_i)^2}{\sum_{i=1}^n (O_i - \bar{O})^2} \quad (9)$$

where, O indicates observed and P predicted values; bars indicate mean values. The normalization of the variance of the observation series results in relatively higher values of E in catchments with higher dynamics and lower values of E in catchments with lower dynamics. To obtain comparable values of E in a catchment with lower dynamics, the prediction has to be better than in a basin with high dynamics. The range of E lies between 1.0 (perfect fit) and $-\infty$. A result lower than zero indicates that the mean value of the observed time series would have been a better predictor than the model.

1 Phase error (PE):

2 Phase error is defined as the difference in hours between the peak of the observed and the
3 simulated flow.

4 Peak discharge error (PD_{err}):

5 Peak discharge error is defined as the percent difference between the observed and the
6 simulated peak discharges:

7
$$PD_{err} = \frac{\max Q_{sim} - \max Q_{obs}}{\max Q_{obs}} \times 100 \quad (10)$$

8

9

10 **6. Case study**

11 **6.1. Model Set Up**

12 The HEC-HMS model was setup in distributed mode, enabling the utilization of the spatial
13 information of the land use via the Curve Number coefficient. The rainfall losses component
14 was based solely on the SCS curve number method (USDA SCS, 1972). This method assumes
15 an initial abstraction before ponding that is related to curve number. Curve numbers in this
16 study were determined from USDA National Engineering Handbook (USDA-SCS, 1972).
17 The curve number method in HEC-HMS relates runoff to soil type, land use management and
18 antecedent soil moisture conditions. The transformation method used was the modified Clark
19 that considers the spatial variability of characteristics and processes explicitly. The Curve
20 number was estimated using a 10m resolution Digital Elevation Model, land use classification
21 for 2000 and soil classification of the area.

22 Yialias basin was modeled using a three sub-basin setup following the available flow gauge
23 locations within the basin. The outlets of the sub-basins were set at Kotsiatis (75.15km²),
24 Nisou (21.71km²) and Potamia (16.29Km²).

25

26

27

28 **6.2 Hydrological Data**

1 The HEC-HMS model was calibrated using three available rainfall – runoff events (2000,
2 2001, 2004), while was validated using a recorded flood event. A list of the rainfall runoff
3 events is given in Table 3. Four precipitation events were selected for the calibration –
4 validation of HEC – HMS hydrological model. The calibration events were the most intense
5 that could be found in the recorded data. Three events were selected, to calibrate the model
6 for the flood of 2003, which served as validation event. The specific event occurred in the
7 watershed’s urban area (downstream) between 12-13th (peak time) of February of 2003.
8 During this event, a driver of a school bus was deadly injured and severe damages were
9 caused all over the catchment area.

10 The hydrological characteristic of each event is presented in Table 3. The three events (dated
11 2000, 2001 and 2004) served for the calibration of the hydrological model. The calibrated
12 model was then evaluated for its performance on the fourth event of 2003 that was a major
13 flood event of the basin. The total precipitation depths (as estimated by the areal interpolation
14 of the available rain gauge data for the entire period of the rainfall events) are also given in
15 Table 3, along with the total duration of the event. It can be observed that the flood event of
16 2003 had the greatest precipitation height comparing to the rest of the calibration events. To
17 identify the driving forces of the flood event, the return period of each maximum hourly
18 rainfall rate was estimated for each rainfall station and event (Table 3). It can be observed that
19 the flood event distinguishes from the rest of the rainfall – runoff events mainly due to the
20 relative high return period that it was occurred simultaneously in two stations (Leukara and
21 Analiontas), comparing to the rest of the events.

22

23

24

25 **Table 3.**

26

27 **7. Result - Discussion**

28 In this study the multi-temporal land use regime of Yialias watershed in Cyprus was
29 thoroughly searched with the use of object oriented classification technique and application of
30 CA- Markov model. The specific model appears to have certain advantages as well as specific
31 disadvantages in its application. Initially, it does not require deep insight into the mechanisms

1 of dynamic change, but it can help to indicate areas where such insight would be valuable and
2 hence act as both a guide and stimulant to further research. On the other hand, Markov
3 analysis ignores the forces and processes that produced the initial land use patterns and also it
4 assumes that changes will continue to do so in the future by sometimes ignoring social,
5 human and economic dynamics. However, in order to give a spatial dimension to the Markov
6 model we applied CA Markov model. Through the 2000 – 2010 decade's analysis, results
7 denote an increase in Agricultural Generic, Olive tree cultivation and herbaceous areas,
8 putting stress into the Close Growth Agricultural Land which is the main decreasing land use
9 category. The forested is shown to roughly occupy the same land portion. The same tendency
10 seems to be for the next decade affecting the potential hydrological response of the basin.
11 Specifically, the simultaneous increase of residential areas and the decrease of agricultural
12 close grown cover throughout the basin is expected to enhance the potential devastating
13 surface run off processes.
14 Regarding the hydrological modeling, the calibration of the model was performed using the
15 Nash Sutcliffe estimator (E), with respect to the correct representation of the peak discharge
16 and the correct timing of it. The calibration and validation results are shown in Table 4.

17 **Table 4.**

18

19 The calibration and validation hydrographs are presented in Fig. 7. The results of the
20 calibration show that the distributed setup of HEC-HMS model adequately describes the
21 timing and the peak discharge of Yialias basin. E ranged from 0.9 to 0.46 between the
22 calibration events and the three sub basins. For the validation event, the E ranged between
23 0.45 and 0.62. The phase error ranged between 0 and 1 hour, except for Event 2 & 3 (Table 3)
24 simulation at Potamia that the phase error was two hours. Finally, the peak discharge error
25 was kept under 17.6%, in all sub basins and calibration events, while for the validation event,
26 it ranged between 0% and 6%.

27

28 **Figure 7.**

29

1 Having calibrated and validated the HEC-HMS model, the land use map of 2010 and the
2 projected 2020 were used to estimate the changed curve number map for 2010 and 2020,
3 respectively (Fig. 8).

4

5 **Figure 8.**

6

7 The changes between the 2000 curve number and the ones of 2010 and 2020 are also
8 demonstrated in Fig. 9. The changes indicate that between 2000 and 2010, 2020, the area
9 weighted curve number for all the land use categories except the urban areas, retains a
10 relatively constant value around 53. (From CN = 52.9 for year 2000, to 52.7 and 53.3 for
11 2010s and 2020s respectively). In contrast, the areal weighted CN for all the land use
12 categories retain a more robust increasing trend from 53.8 to 55 and then to 56.2. It is shown
13 here that the increase in the urban land use in 2010 (from 1.85% to 5% of area) outweighs the
14 slight decrease in the CN in the rest of the basins' land use classes. Accordingly, the 2020
15 projected land use shows that the CN is projected to increase from 55.0 in 2010 to 56.2. This
16 increase by 1.2 units is both attributed to the change to non-urban land uses and the further
17 urbanization of the basin (from 5% to 6.5%).

18 All the events that were used to calibrate and validate the hydrological model were then run
19 under changed land use / curve number conditions. The results are shown in Table 5.

20

21 **Table 5.**

22

23 The results show an increase in the peak discharge. The magnitude of the increase in peak
24 flow is different for the four simulated events and for each sub-basin in the catchment.

25

26 **Figure 9.**

27

28 Results for the validation event (which consisted a flood event in 2003), indicate an increase
29 in the runoff response under the changed land use conditions of 2010. The changes were

1 estimated to be 10.2%, 7% and 11.1% (Table 4), for the three sub-basins Kotsiatis, Nisou and
2 Potamia, respectively, in comparison to those of 2000. The outcome indicates that the runoff
3 dynamics of the basin are changing due to the land use transition among different categories.
4 Next, the CA-Markov chain predicted 2020 land use was used to simulate the 2003 event
5 under future land use conditions. The results show a noteworthy increase in the peak
6 discharge that reached 22.4% 14.6% and 19.9% compared to the 2000 land use runs for the
7 above three sub-basins, respectively . The simulated changes in the runoff are presented in
8 Fig. 7. The changes in the simulated peak discharges can be explained by the overall increase
9 in the curve number of the basin for both 2010 and 2020 simulations. Moreover the pattern of
10 the CN increase between the urban and non-urban land use classes can stand as a positive
11 proof that the change in 2010 peak discharge is wholly attributed to the urban areas increase,
12 while the 2020 further increase is merely attributed to urban areas increase but also in the
13 trade off of non-urban land uses. It has to be noted that the above rationale explains in
14 general the mechanism of the land use change effect on the peak runoff, but it does not
15 account neither for the spatial distribution of the land use changes, nor the distribution of the
16 precipitation.

17

18 **8 Conclusions**

19 This study presented an integrated methodology for searching and forecasting a catchment's
20 area hydrologic response with the use of HEC HMS model and satellite remote sensing
21 techniques. The preliminary results denoted the crucial role of urban sprawl phenomenon as
22 well as the significant change of land cover regime in the increase of runoff rate within the
23 spatial limits of a catchment area and highlighted the importance of searching land use regime
24 with the use of satellite remote sensing imageries. It was proved that the incorporation of
25 multi-temporal remote sensing data in hydrological models can effectively support decision
26 making in the areas of risk and vulnerability assessment, sustainable development and general
27 management before and after flood events. In addition, the implementation of CA-Markov
28 provided indication of the potential impact of land use change on flood vulnerability in the
29 near future.

30 The comparison of observed flow results concerning the flood event of 2003 with the
31 simulated flow results (with the use of different land use data concerning 2000, 2010 and
32 2020 land use regimes) proved that in the case of "2010" and "2020" model, the runoff rates

1 were steadily higher due to the expanded urban area cover that increased the phenomenon of
2 surface run off. This tendency was verified after incorporating the land use data for the 2020
3 time period. Knowing from past events that the area between the Nisou and Potamia is highly
4 prone to flooding, the already increased dynamics of the surface runoff indicate higher
5 flooding hazard for the area. Moreover, the projected changes in land use that is simulated to
6 increase the peak discharge by 14.6% and 19.9% until 2020 for the Nisou and Potamia,
7 dictate actions have to be taken to mitigate the flood hazard.

8 The results of this study can be used as a road map for taking specific actions in land use
9 management changes to achieve sustainable water resources goals in the near future. The
10 research team will continue to study the hydrological response of the catchment area with
11 more updated meteorological and stream data as well as satellite images of higher spatial
12 resolution.

13

14 **Acknowledgements**

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16 project “SATFLOOD” (ΠΡΟΣΕΛΚΥΣΗ/ΝΕΟΣ/0609). Also, thanks are given to the Remote
17 Sensing and Geo Environment Laboratory of the Department of Civil Engineering &
18 Geomatics at the Cyprus University of Technology for supporting this project
19 (<http://www.cut.ac.cy/>).

20

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9

10 Table 1. Characteristics of the study area’s rain and flow gauge stations.

	Stations	Longitude Easting	Latitude Northing	Elevation (m)	Distance from the coast (km)	Length of records (year)
	<i>Rain gauges</i>					
1	Mantra tou Kampiou	520682	3867871	640	21.818	20
2	Analiontas	526562	3874143	360	27.124	20
3	Lithrodontas	527420	3867428	420	20.926	20
4	Leukara	526783	3861720	420	16.28	20
5	Kionia	518269	3863820	1200	13.97	20
6	Pera Chorio	535407	3874471	250.38	24.02	20
7	Mathiatis	530615	3869030	373.78	25.23	20
	<i>Flow gauges</i>					
1	Kotsiati	539779	3878282	195.43	27.75	34
2	Nisou	535960	3875415	239.99	24.45	46
3	Potamia	530639	3872576	298.91	22.05	14

11

12

13 **Table 2.** Transition probability matrix for each land cover class using the Markov chain
14 equation.

	Agricultural – Close Grown	Agricultural – Generic	Herba ceous	Forest Mixed	Urban	Olive Trees	Water

1	Agricultural – Close Grown	0.8157	0.0340	0.0500	0.0237	0.0158	0.0606	0.00
2	Agricultural – Generic	0.0004	0.8070	0.1551	0.0007	0.0001	0.0367	0
3	Herbaceous	0.0721	0.0986	0.6058	0.0767	0.0296	0.1171	0.0001
4	Forest Mixed	0.2963	0.1509	0.1329	0.3222	0.0568	0.0409	0
5	Urban	0.1925	0.0995	0.1747	0.0485	0.3433	0.1398	0.0017
6	Olive Trees	0.0983	0.1370	0.2084	0.1556	0.0549	0.3458	0
7	Water	0	0	0.4222	0	0.0889	0.0667	0.4222

1
2

3 **Table 3:** List of calibration and validation events. The precipitation represents the average
4 precipitation of the entire watershed. The return period for each rain gauge for each event is
5 also provided.

		Start date	End date	Total event P [mm]	Return Period [yrs]				
					Lithrodontas	Mantra tou Kampiou	Leukara	Analiiontas	Kionia
Calibration	Event 1	07 Dec 2000	18 Dec 2000	102.5	0.96	3.03	1.04	1.28	3.74
	Event 2	06 Dec 2001	11 Dec 2001	82.2	0.91	3.96	1.33	4.25	21.64
	Event 3	09 Jan 2004	15 Jan 2004	122.3	-	3.50	4.80	12.48	0.89
Validation	Event 4	10 Feb 2003	17 Feb 2003	157.8	-	1.15	0.72	1.16	1.01

6
7
8

1 **Table 4.** Calibration and Validation results of HEC-HMS. The Nash Sutcliffe (E), Phase
 2 Error (PE) and Peak Discharge Error (PDE) are presented. Negative values of phase error
 3 (PE) indicate simulated peak before the observed event.

4

		Kotsiatis			Nisou			Potamia		
		E	PE [h]	PD E [%]	E	PE [h]	PD E [%]	E	PE [h]	PDE [%]
	Event 1	0.78	0	3.3	0.87	1	-0.6	0.46	1	5.6
Calibration	Event 2	0.61	0	0.0	0.66	1	4.7	0.86	2	4.6
	Event 3	0.67	0	-1.2	0.70	1	17.6	0.90	2	4.8
Validation	Event 4	0.45	0	0.0	0.50	1	2.5	0.62	0	6.0

5

6

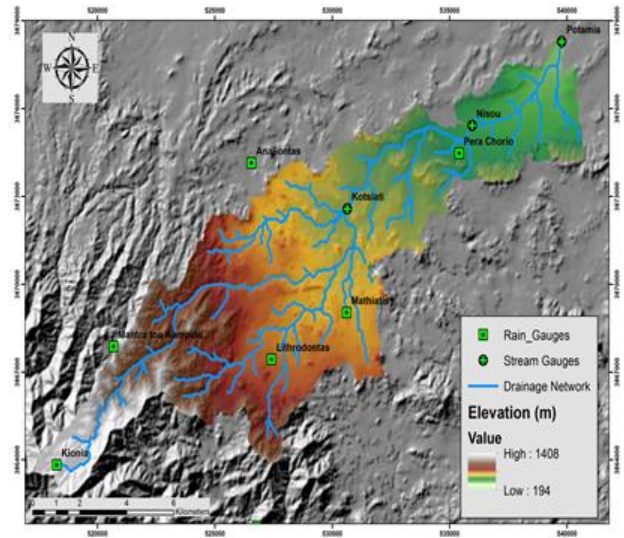
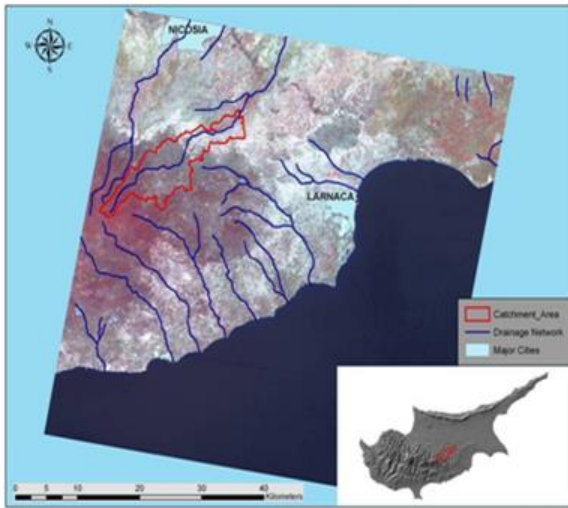
7 **Table 5.** Changes in Yialias simulated peak discharge due to land cover change in 2010 and
 8 2020 comparing to the 2000 land use.

	Kotsiatis		Nisou		Potamia	
	2010	2020	2010	2020	2010	2020
Event 1	39.4%	59.4%	32.1%	49.1%	56.6%	88.2%
Event 2	1.9%	4.5%	1.5%	3.7%	1.5%	4.4%
Event 3	11.1%	20.2%	7.1%	12.3%	7.7%	12.7%
Event 4	10.2%	22.4%	7.0%	14.6%	11.1%	19.9%

9

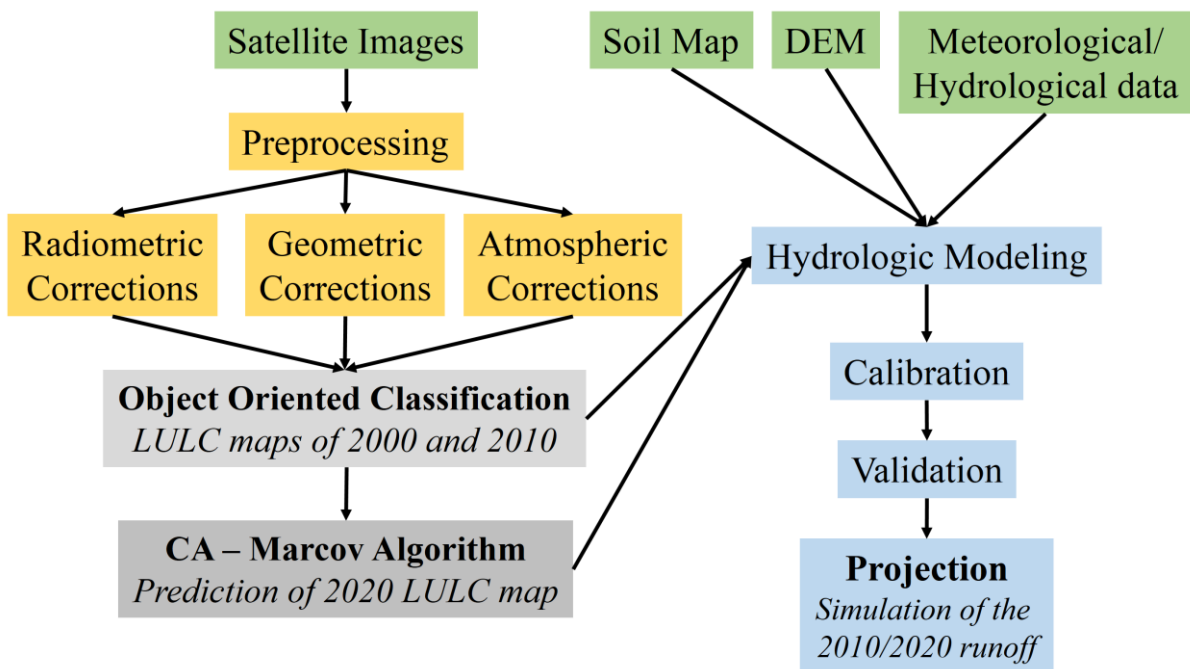
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1
 2 Figure 1. (a) Study Area as indicated in the RGB- 321 of ASTER image; (b) Location of rain
 3 and stream gauges stations.

4



5
 6 Figure 2. Flow chart of the proposed methodology.

7

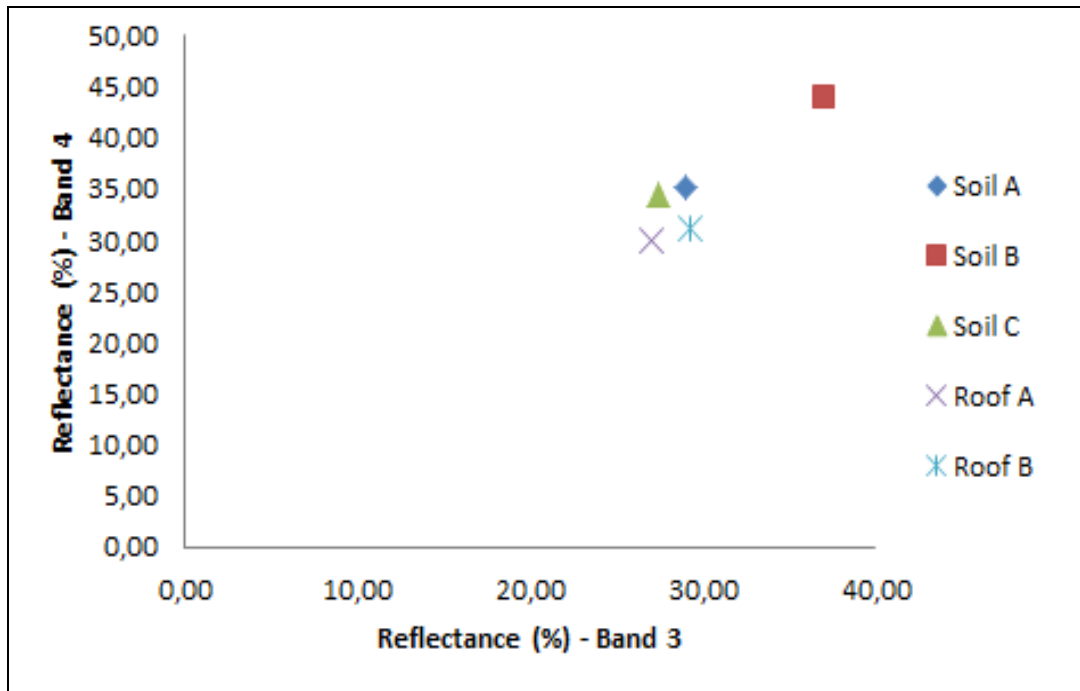
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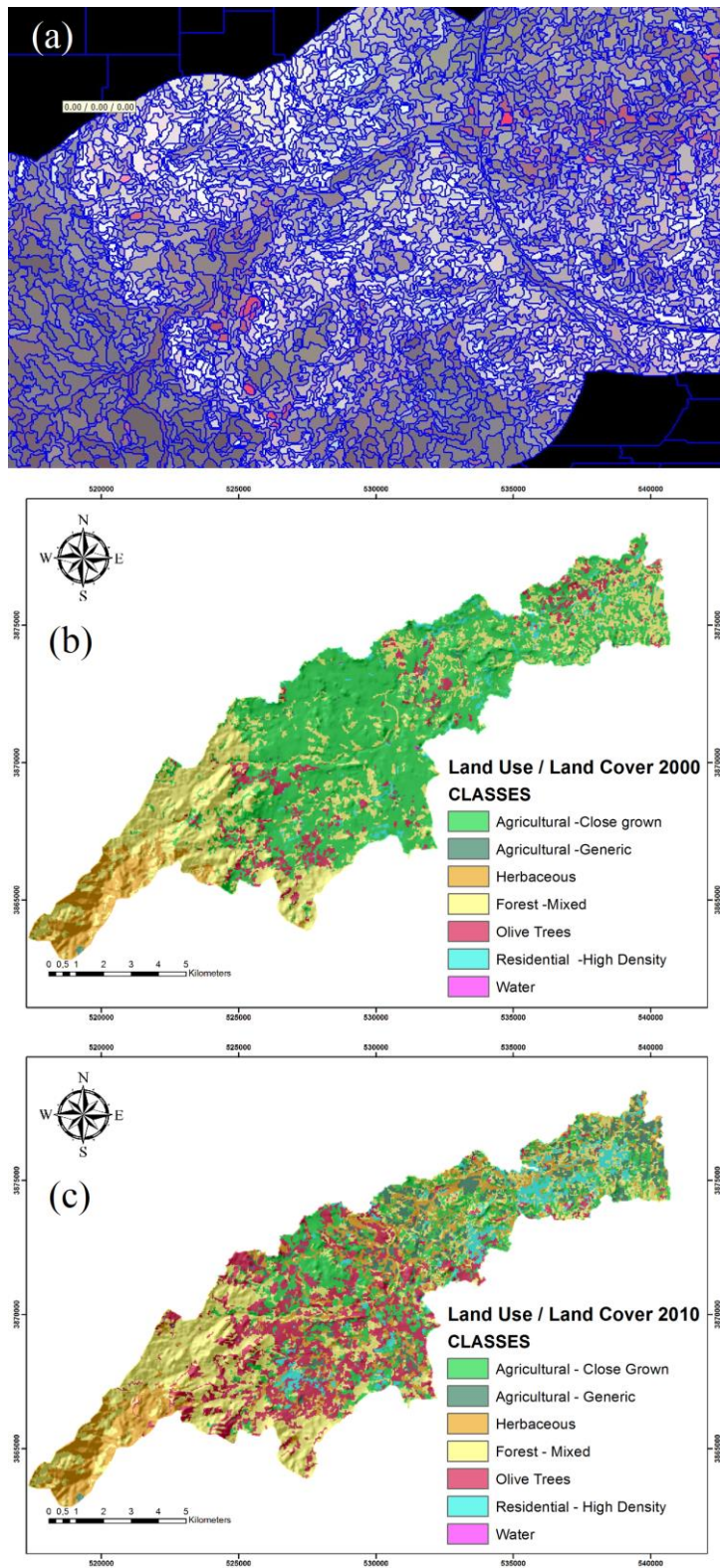
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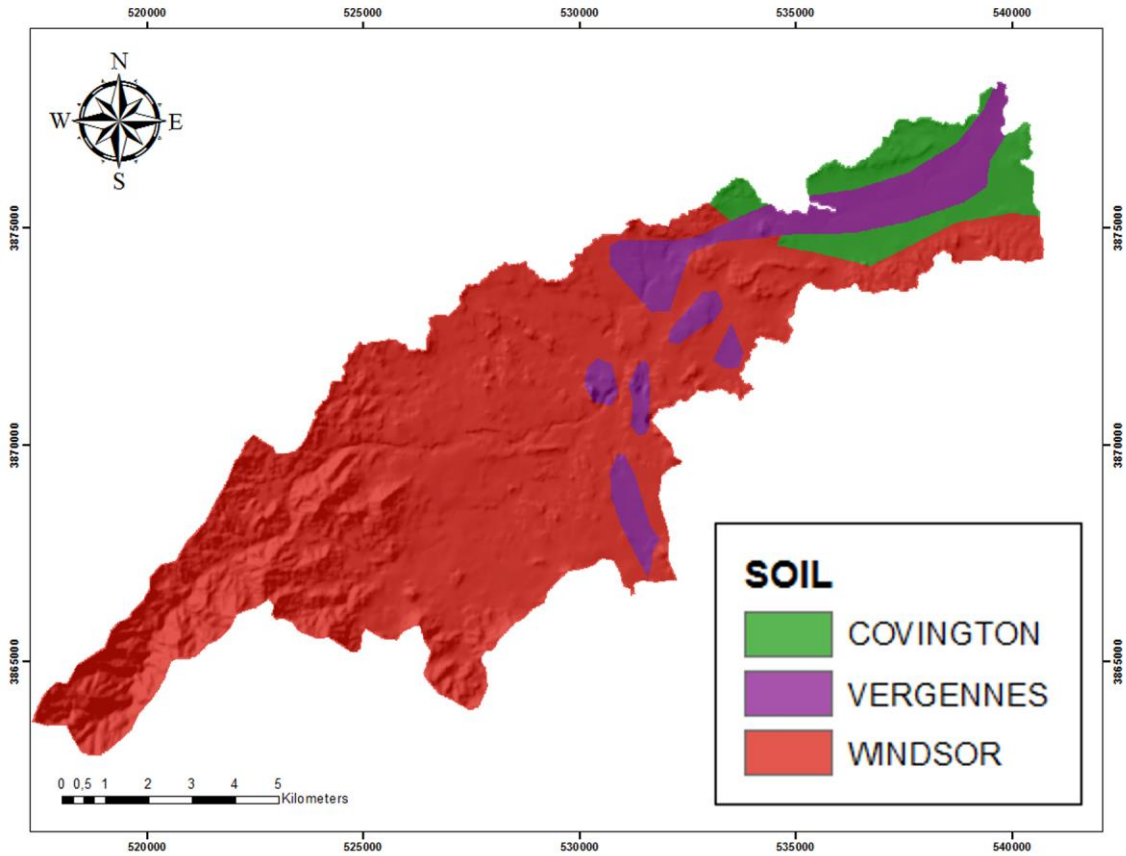
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Figure 3. Scatter plot for the different targets for bands 3-4.



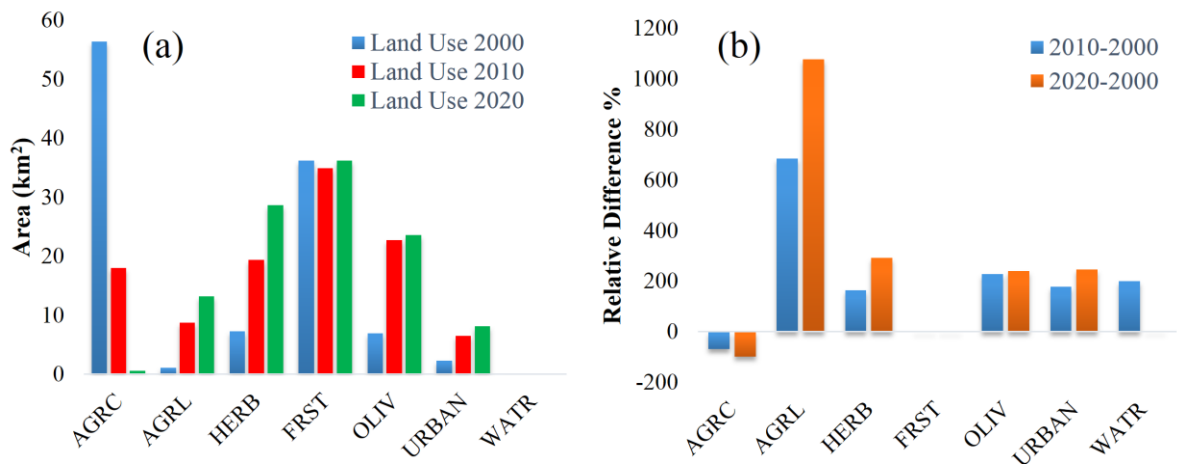
1 Figure 4. (a) Image segmentation of ASTER 2010 image; (b) LULC map of the study area
 2 for 2000; and (c) LULC map of the study area for 2010.

3



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2 Figure 5. Soil Map of the study area.

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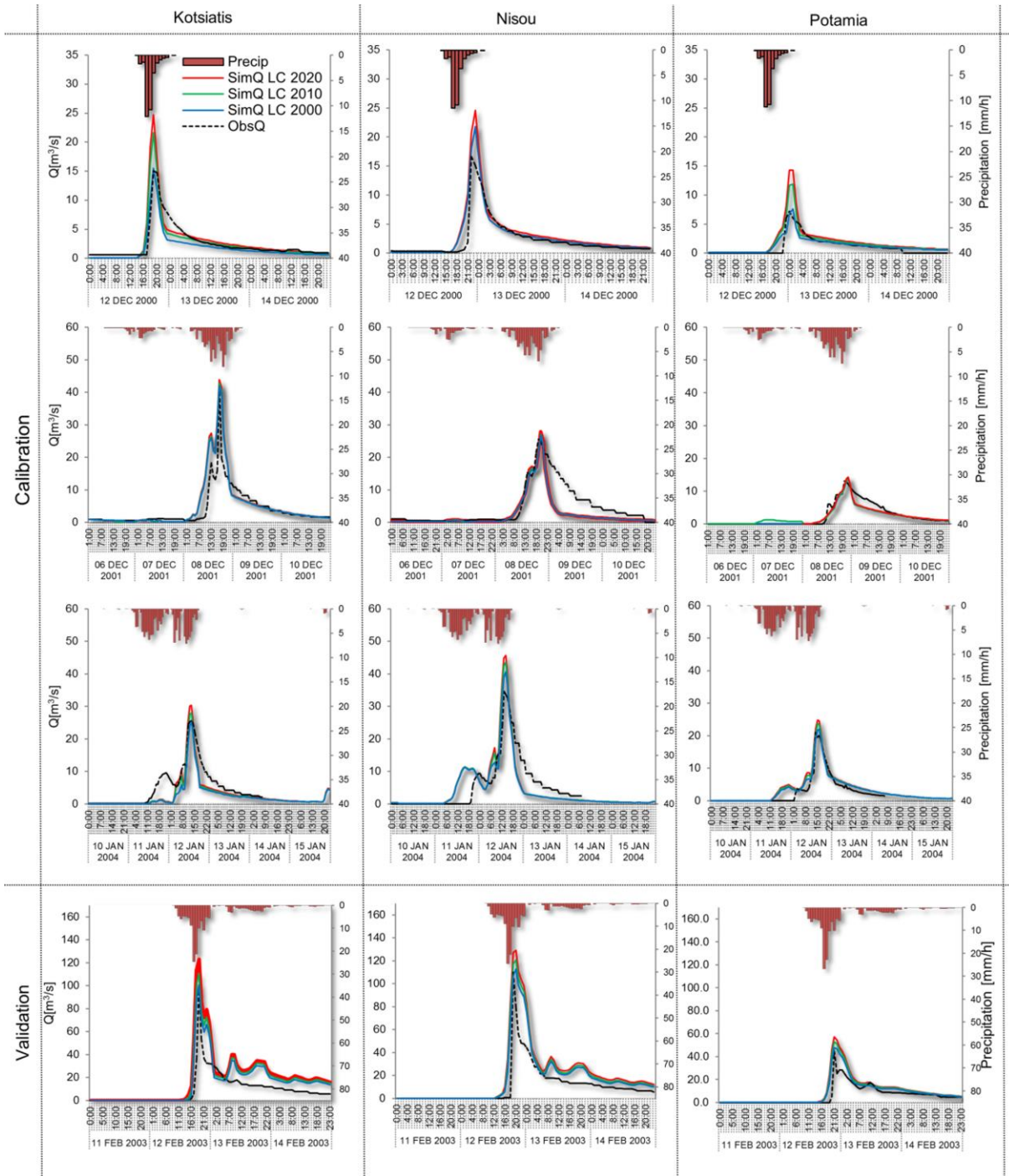


5
6 Figure 6. (a) Land use statistics (AGRC = Agricultural Close Grown, AGRL = Agricultural
7 Generic, HERB = Herbaceous, FRST = Forest Mixed, OLIV = Olive Trees, URBAN = Urban
8 Fabric, WATR = Water). (b) Relative (%) difference diagram of land uses cover.

9

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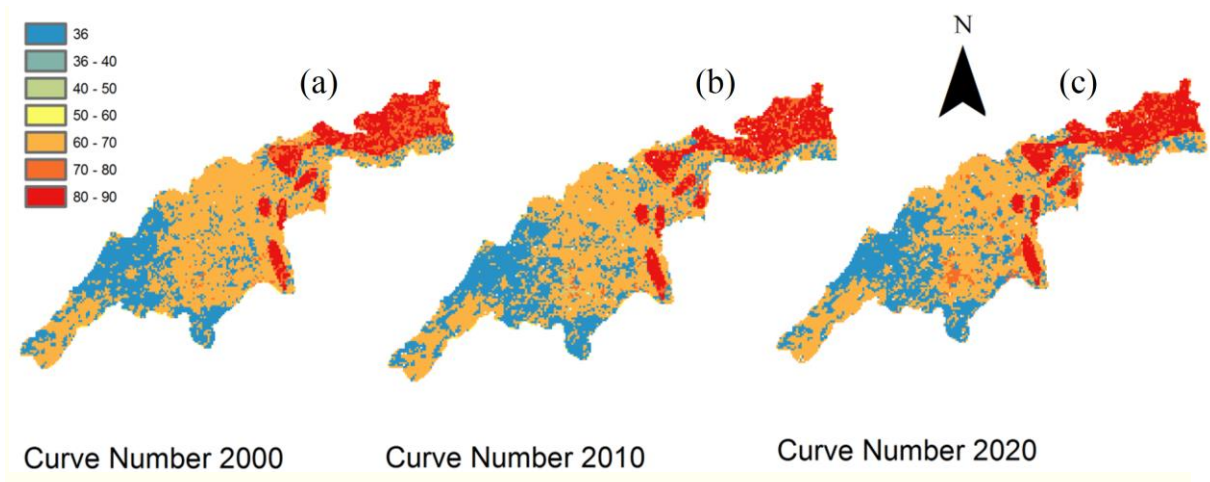
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4 Figure 7. Calibration and validation hydrographs for the observed and simulated flows. The
5 Land use 2010 (green lines) and 2020 (red lines) hydrological simulations are also presented.

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7

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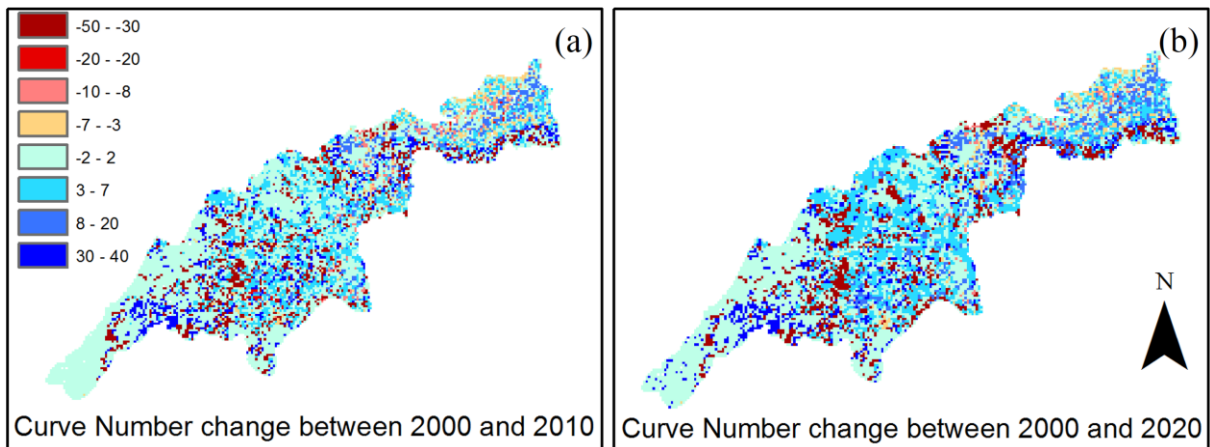


2

3 Figure 8. Curve number estimated for different land uses.

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5



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7 Figure 9. Changes between curve number of 2000 – 2010 (a) and 2000 – 2020 (b).

8

9