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Effective 3-D surface modeling for geographic information systems

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storage resources. Consequently, modelling and resource management have become an important aspect for an effective GIS application system. The use of GIS in municipal services such as infrastructure and lighting based on city modeling and related layering approach has increased dramatically (Glander and Döllner, 2009).

Given the growing use of Light Detection and Ranging (LIDAR) technology, the 3-D city modeling and analysis processing have triggered off a new era. In recent years, the research on methods using the LIDAR technologies has exponentially increased (Tao and Hu, 2001). The main purpose of such approaches is to correctly identify the terrain and the objects on the terrain. Several techniques for precisely differentiating the terrain and the objects on the terrain have been recently proposed (Yoon and Shan, 2002). Such methods have also contributed evolving new software and hardware architectures. For instance in Dollner and Hinrichs (2000), Saha et al. (2011), and McKinney and Cai (2002), the objects and terrain are represented as object-oriented data structure concept and each building is assigned to an object. Among the properties of the building include roof type, roof polygons, height, roof surface and LIDAR point sequence. Another approach used interpolation for graphics library and smoothing (Zhou et al., 2004). Many topological models for 3-D spatial objects have been already reported in the literature to describe relationships between spatial objects. As compared to 2-D approaches, such relationships have become more complex in 3-D methods (Zlatanova et al., 2004).

In 3-D GIS modeling, type and size of data have led databases to include special add-ons in order to store and process them. Besides the classic text-based queries, geometry-based queries have become a necessity, which leads emergence of structures known as spatial databases. This feature is then added by many vendor database systems. In recent years, the structures for the storage as well as query of GIS data have reached a promising level (Kothuri et al., 2007). The increase of precision and quality in satellite and aerial imagery has brought about the tendency to use GIS applications. The need for saving and processing huge image information in databases has enabled not only spatial database extensions but also multimedia database extensions

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to be used in current database systems (Ramakrishnan and Gehrke, 2003). More widespread use in the field of telemedicine and the media, this feature, in fact, has potential initiative for GIS field.

There is a significant trend in re-modeling of systems in 3-D space. Much work has been done on 3-D processing of terrain and objects on terrain in GIS applications (Arens et al., 2005) based on computer graphics methods (Arens et al., 2005). Delaunay Triangulation is widely used in spatial object and terrain representations (Goias and Dutton, 1997). A recent study proposed using polyhedrons as base structures in spatial object representation (Chandra and Govardhan, 2008). On the other hand, recent advances in game engines utilize realistic representations and models such as light, and sound effects (Noh et al., 2006).

Initially, two-tier architectures were used in GIS applications. In these systems, clients operate applications in order to receive services through the network from the database server (Coors, 2003). Storing the data on the server and sections processed on the client are important in the effectiveness of the architecture. Resource needs and the client/server layout in 3-D structures have gained increasing importance. Software complexity and user expectations are crucial in interactive GIS applications. Production of high-quality satellite and aerial images, getting ground elevation and location information accurately with Global Positioning System (GPS) have contributed to the development of realistic 3-D GIS applications.

The development of GIS applications that require high-speed data and image transmission does not grow parallel with the computer technology. This has led to a search for other means to overcome the bottleneck in terms of computing environments. In other words, a search for new opportunities has emerged to employ high-quality 3-D GIS applications in computers with limited memory resources and processing power. In Guttman (1984), the modeled terrain is entirely processed, but details of only a specific terrain area is presented during representation instead of providing all the details.

With the spread of Internet use, research of web-based GIS solutions has initially started on 2-D (Huang and Lin, 1999). Recently, 2-D GIS research replaced with 3-D

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et al., 2007; Pribyl, 2002). The processes of surface modeling described in this section are performed only once. If the surface is reconstructed when any data of the surface is modified, the surface modeling process must be repeated from the beginning. The duration of this process depends on the quantity and size of the data. In other words, the number of Geo-Node data elements storing the system information as discrete data is unique. Figure 1 shows the basic structure of Geo-Nodes. The information stored in Geo-Nodes include text, graphics and spatial data.

The database connectivity physically associated with Geo-Nodes is determined by data model. Relational scheme emerged from our data model including tables and their relationships is depicted in Fig. 2.

In addition to the relational model generated from data modeling, the system also has INIT table containing packages of system parameters. It eliminates the dependence of the system with the application and achieves the business logic part of the application on server side. The data retrieved from plain text file in UTM format is converted to SDO_GEOMETRY data type and stored in POINTS table. Figure 3 shows a PL/SQL example inserting spatial data to the POINTS table.

Graphic elements generating geometric representation of surface are stored in POLYHEDRONS table. Separating points set in POINTS table into blocks, those graphic elements is closed geometries with multi-surface and referred to as polyhedron. In Fig. 4, a PL/SQL statement is given that generates closed geometries with multi-surface and inserts to the POLYHEDRONS table.

Since spatial querying is time consuming process, IDs of points in every polyhedron are stored in POINT_POLYHEDRON table. Therefore, relationships of polyhedrons and points are identified by spatial queries only one time, and then stored in POINT_POLYHEDRON table. In order to perform these queries, R-Tree spatial index must be included in SDO_GEOMETRY data fields. Figure 5 presents a code block for relationships between polyhedrons and points and inserting them to the POINT_POLYHEDRON table.

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set, the minimum bounding multi-surface geometric solid (polyhedron) is constructed that fully encloses the set of points (Fig. 8). The minimum bounding polyhedron containing point set in 3-dimensional space is then decomposed into surfaces according to the X_PART and Z_PART variables of INIT table in spatial database (Fig. 9). These closed surfaces are saved in POLYHEDRONS table. SHAPE field of the table stores the geometries using SDO_GEOMETRY data type. It makes use of the R-Tree spatial index which supports topological queries.

Interior points of each polyhedron, in other words intersection points, can be determined via spatial queries using R-Tree spatial index. For two geometries as input variables, spatial boolean SDO_ANYINTERACT query returns true when they have an intersection relation. The duration of this process depends on the number of points and polyhedrons. Figure 10 shows a query for determination of intersection points with polyhedron. Although R-Tree indexing is the most efficient spatial access method, it is not as fast as a standard SQL query on a database table using B-Tree index structure (Ramakrishnan and Gehrke, 2003).

Since determination of intersection points in a polyhedron via topological query is very time consuming, this will be a drawback in real-time surface representation. One possible way of saving computational effort is to store intersection points in a table, namely POINT_POLYHEDRON. B-Tree index is stored in POLYHEDRON_ID field of the table. As a result, significant performance differences can be achieved in accessing to the intersection points. Figure 11 shows an example of topological query using a B-Tree index.

Using Delaunay triangulation method, a surface can be generated from the points within polyhedrons that are stored in the POLYHEDRONS table. Thus, a triangular network is formed from each polyhedron. Triangles of the network are stored in the TRIANGLES table. All polyhedrons together comprise a triangular surface. Neighbors of the polyhedrons are produced using doubly linked list and the final surface representation is obtained by combining surfaces of polyhedrons with its neighbors.

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Problems arise when the surface model is formed by partitioning the polyhedrons into triangular elements. Merging the triangular surfaces of each polyhedron with its neighboring surfaces may result in surface overlap, shared sharp edges of surfaces or surface gap. Figure 12 shows surfaces of polyhedrons each of which four squares is projection of a polyhedron. These problems are tackled by introducing artificial points (marked by cross-x) on the vertices of the polyhedrons (Fig. 13). Artificial points may not be among spatial dataset forming the surface. Therefore, closed attention should be directed toward the surface characteristics while adding artificial points in order to preserve the original surface shape. “Y” height values of the artificial points added to the polyhedron vertices must be accurately computed to preserve the surface characteristics. Since polyhedrons are stored in POLYHEDRONS table of spatial database using SDO_GEOMETRY data type, in horizontal plane, the “X” and “Z” values of the points located on polyhedron vertices can be found easily. In order to determine the heights of new vertices, intersection of each new vertex with other four polyhedrons are identified. If a new vertex added to the polyhedron lies on the corner of the surface formed by other polyhedrons, then it will be in intersection with only its own geometry. If it lies on the edge of the entire surface, then it will be intersecting two polyhedrons, else it will be in intersection with four polyhedrons. After the characterization of intersection state, the closest point to each new vertex is determined. In calculation of height values of new points that lie on X–Z axis, if any points already exist in X–Z axis, the height of existing points is used. Otherwise, the height and proximity of the closest points are taken into account. Thus, the height of an artificial point can be greatly influenced by the height of its closest point. To compute the height of an artificial point, first, height ratio, of the point is calculated as:

$$pR_i = 1 - (pD_i + sD) \quad i = 1..4 \quad (1)$$

where pD_i is distance of the point i to the artificial point and sD is the sum of distances of all points to the artificial point. Applying Eq. (1) to all other points, height of the new

segment is stored in IMAGE field of IMAGES multimedia database table in binary format. The unique identity number in POLYHEDRON_ID field determines which image belongs to which polyhedron. Figure 16 shows the effect of seamless texturing between surfaces.

5 Proposed surface modeling technique provides 3-D representation of topographic ground surface and many types of ground and non-ground objects such as buildings, houses and infrastructure (e.g. roads and bridges including noise barriers, lamp posts and sign boards as well as buried objects such as drums and pipes). The system allows representation of any object on terrain. An object is associated with a 3-D geometry model together with a texture image and integrated to the model with its world coordinates. In order to facilitate the storage and indexing of 3-D objects represented on the surface model, two database tables have been created: (i) OBJECT_TYPES, and (ii) OBJECTS. OBJECT_TYPES table is used to incorporate different types of objects with the terrain surface. OBJECTS table contains location information and terrain conditions for placing an object referenced in OBJECT_TYPES table. After model construction, the object is inserted into the OBJECT field of OBJECT_TYPES table in binary format. Then, the object model is scaled to the desired size, rotated to the desired orientation and ultimately translated to the final destination on surface. This allows to use multiple references (instancing). That is, once the object model is abstracted, re-instancing it into several representations could be possible. Once the position of the object model is identified, the polyhedron that bounds the object is determined from spatial database using topological queries. An R-Tree index structure is built during the process of unfolding polyhedrons using topological queries on LOCATION column of OBJECTS spatial table. The polyhedron is then assigned a unique identification number in POLYHEDRON_ID field of OBJECTS table.

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3.2 Data structure

A Geo-Node, as a stand-alone element, has no meaning itself. Its relations with other Geo-Nodes must be known. Figure 17 depicts proposed eight-connected double-linked list, in which N denotes the objects stored in linked lists.

Each Geo-node in eight-connected double-linked list stores geometry entities including triangles that form multi-surface geometry, satellite image segments that drape over surface and 3-D objects represented on terrain.

The main use of the proposed dynamic data structure is that it manages the movement of persistent Geo-Node data on secondary storage and buffer during interactive display of surface model by the user. In this context, linked list corresponds to a grid structure that accessing one element provides traversing through all elements in the linked list. Figure 18 illustrates the eight-connected linked list structure composed of Geo-Nodes. The right side of the Fig. 18 shows all Geo-Nodes allocated in the memory at a specific time, and red frame indicates subset of Geo-Nodes available to the user at that time.

RECTANGLES table of the spatial database consists of TOP, LEFT, RIGHT, BOTTOM, RIGHT_TOP, RIGHT_BOTTOM, LEFT_BOTTOM, LEFT_TOP, LEFT_BOTTOM columns of numeric data with rows. The data contains numeric values defining 3-D multi-surface geometry stored in the same row with all neighboring geometries in eight-connected double-linked list. The motion at the client side via any I/O device triggers the buffer manager based on Directional Replacement Policy (DRP). This module provides smooth and continuous retrieval of data by utilizing effective connectivity periods when the user's view is moving. A simple mechanism of the DRP algorithm is given in Fig. 19. P denotes the Geo-Node to be fetched using pre-fetching and, X denotes the Geo-Node to be replaced using the replacement policy in the movement of the user's view.

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3.3 Dynamic representation of the surface model

Proposed multi-layer system offers friendly user interface easy to understand and provides interactive visualization. The position and orientation of the user's view on the surface are continuously updated. When current view of the user is within a polyhedron that is on the corner and edge vertices of the surface, new surface segments (plane surfaces) are identified to be visualized. These are the planes in neighboring polyhedrons of the current polyhedron. Polyhedrons together with data of corresponding triangular planes, satellite images and CAD objects in the database are prepared for visualization. The surface of each polyhedron can then be reconstructed from this data. Figure 20 shows the reconstruction of the surface model when reaching the boundary of the display.

The future viewing direction of the user on the surface can be estimated based on the path of the navigation, and hence new surface segments to be visualized can be incorporated into the buffer pool in the memory before reaching a boundary region. Whenever the position of the user within a polyhedron is placed upon another polyhedron, neighboring polyhedrons of the current polyhedron is identified using the eight-connected double-linked list, and corresponding planes and objects of this polyhedron are sent to the buffer. In query processing, when the database needs to access a data item of interest, it first requests on the buffer manager. If the desired surface in the polyhedron is already in the buffer, the buffer manager simply returns it. If it does not, the buffer manager brings desired polyhedron and corresponding information (triangles, objects and satellite image) from the database to the memory. This process is repeated for any displacement on the surface until the view of the user reaches a boundary. Before displaying an edge surface on the current polyhedron, surface segment to be rendered is reconstructed. In dynamic representation mechanism, buffer manager is first called to fetch the data needed for reconstruction. If the buffer manager has not already cached a requested block, the surface to be visualized is reconstructed reading the corresponding block from the database to the buffer pool. After surface reconstruction,

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are eliminated. Furthermore, a game engine was used in rendering pipeline in order to improve the realism of visualization. The experimental results show that visualization of urban scene is successful with high performance. The proposed platform can offer new capabilities to build 3-D GIS applications in two tier or n -tier (client/server) architectures.

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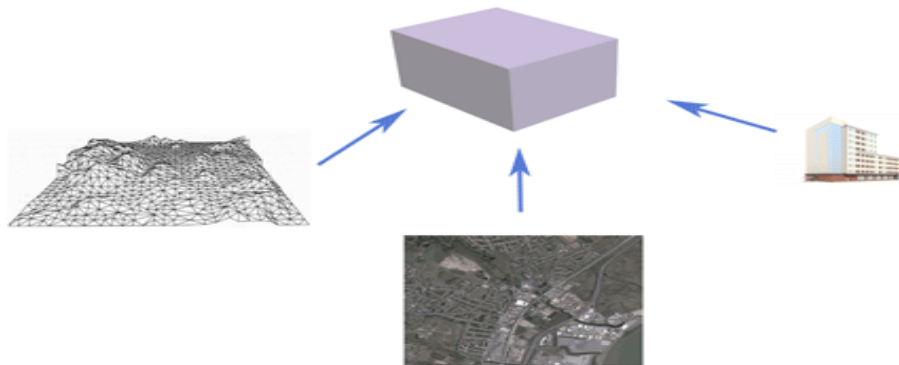


Fig. 1. Geo-Node Structure.

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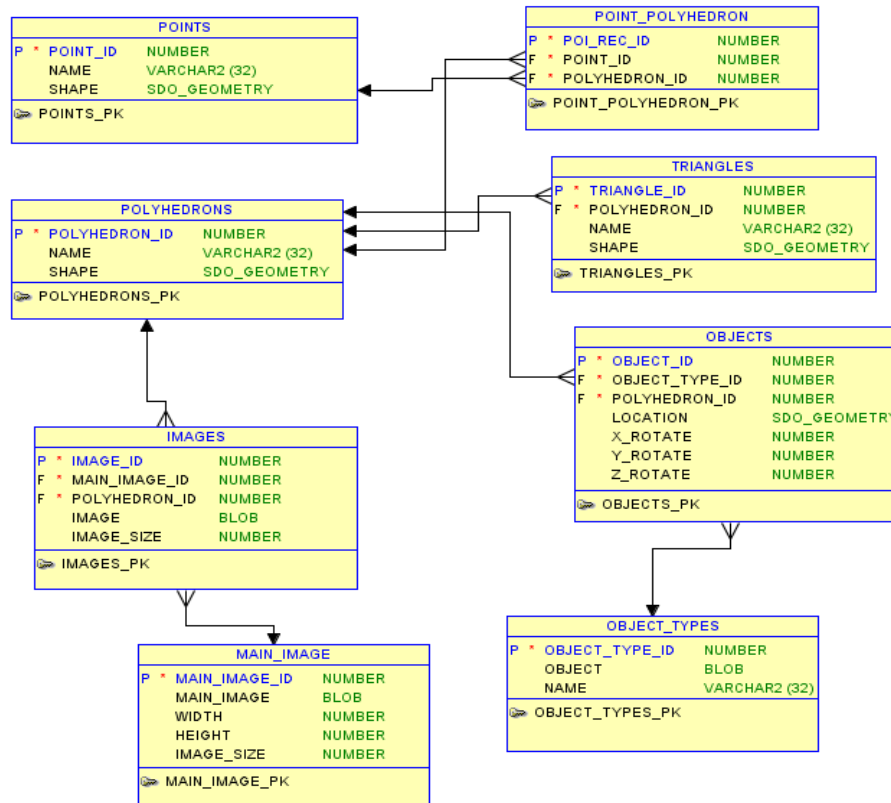


Fig. 2. ER diagram of the data stored in tables.

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```
INSERT INTO POINTS (SHAPE) VALUES (  
SDO_GEOMETRY (3001, NULL, SDO_POINT_TYPE (Px, Py, Pz), NULL, NULL) );
```

Fig. 3. PL/SQL statement inserting point geometry to the POINTS table.

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```
INSERT INTO POLYHEDRONS (SHAPE) VALUES (SDO_GEOMETRY(3008, NULL, NULL,  
SDO_ELEM_INFO_ARRAY(1, 1007, 3),  
SDO_ORDINATE_ARRAY(X_min, Y_min, Z_min, X_max, Y_max, Z_max)));
```

Fig. 4. PL/SQL statement generating closed geometries with multi-surface and inserting to the POLYHEDRONS table.

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```
...
CURSOR crsPolyhedrons
IS SELECT * FROM POLYHEDRONS ORDER BY POLYHEDRON_ID ASC;
rowPolyhedron crsPolyhedrons%ROWTYPE;

CURSOR crsPoints(polyhedronShape SDO_GEOMETRY)
IS SELECT P.* FROM POINTS P WHERE
SDO_ANYINTERACT(P.SHAPE, polyhedronShape) LIKE '%TRUE%';
rowPoint crsPoints%ROWTYPE;
BEGIN
  OPEN crsPolyhedrons;
  LOOP
    FETCH crsPolyhedrons INTO rowPolyhedron;
    EXIT WHEN crsPolyhedrons%NOTFOUND;

    OPEN crsPoints(rowPolyhedron.Shape);
    LOOP
      FETCH crsPoints INTO rowPoint;
      EXIT WHEN crsPoints%NOTFOUND;

      INSERT INTO POINT_POLYHEDRON (POLYHEDRON_ID, POINT_ID)
        VALUES (rowPolyhedron.Polyhedron_Id, rowPoint.POINT_ID);
    END LOOP;
    CLOSE crsPoints;
  END LOOP;
  CLOSE crsPolyhedrons;
END;
```

Fig. 5. PL/SQL code block identifying the relationships between polyhedrons and points, then inserting to the POINT_POLYHEDRON table.

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Fig. 7. A sample of point set.

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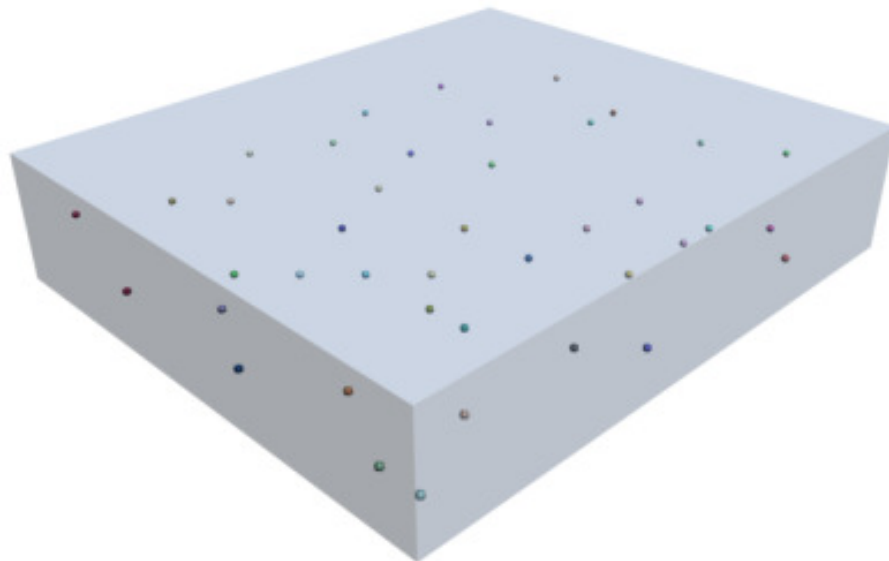


Fig. 8. Multi-surface closed geometry containing point set.

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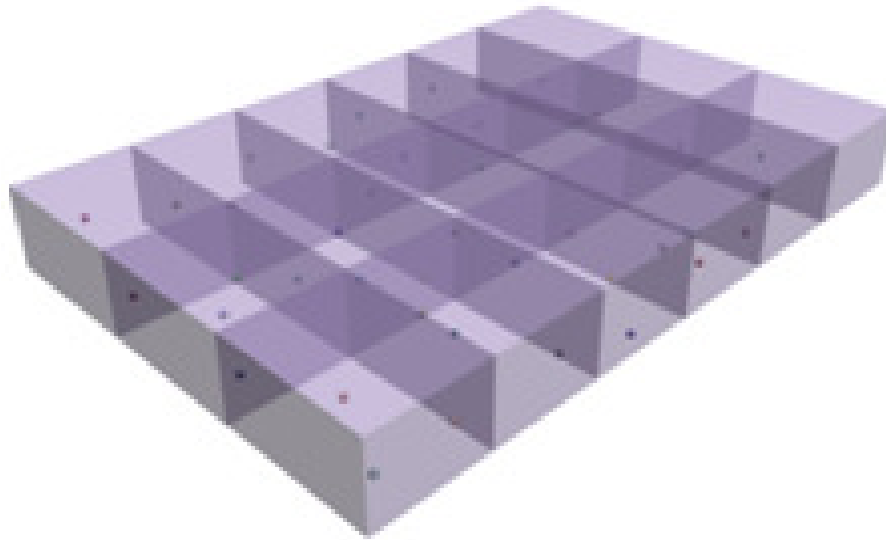


Fig. 9. Decomposed geometry containing point set.

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```
SELECT P.* FROM POINTS P WHERE SDO_ANYINTERACT(P.SHAPE, (SELECT R.SHAPE FROM POLYHEDRONS R WHERE R.POLYHEDRON_ID=10)) = 'TRUE';
```

Fig. 10. Query determining intersection points with a polyhedron.

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```
SELECT P.* FROM POINTS P INNER JOIN POINT_POLYHEDRON R ON  
P.POINT_ID=R.POINT_ID WHERE R.POLYHEDRON_ID=10;
```

Fig. 11. A topological query with B-Tree index.

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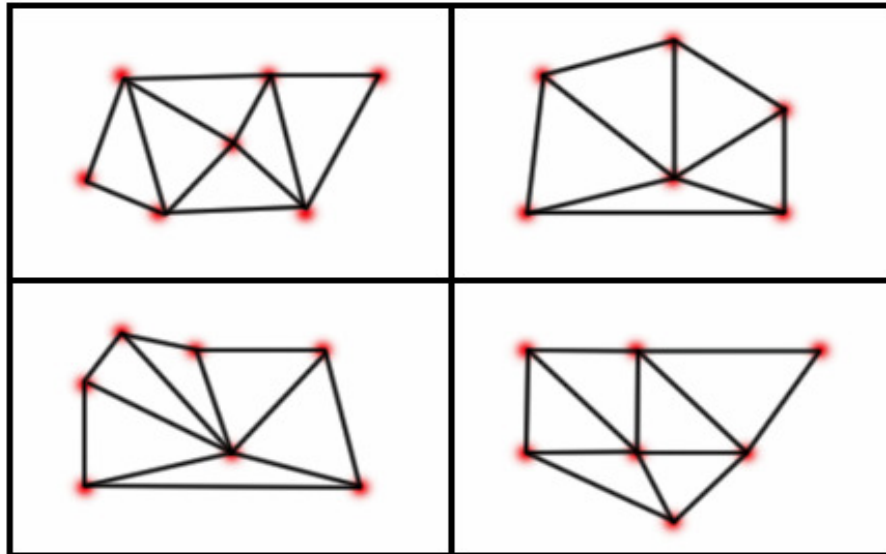


Fig. 12. Surfaces of polyhedrons.

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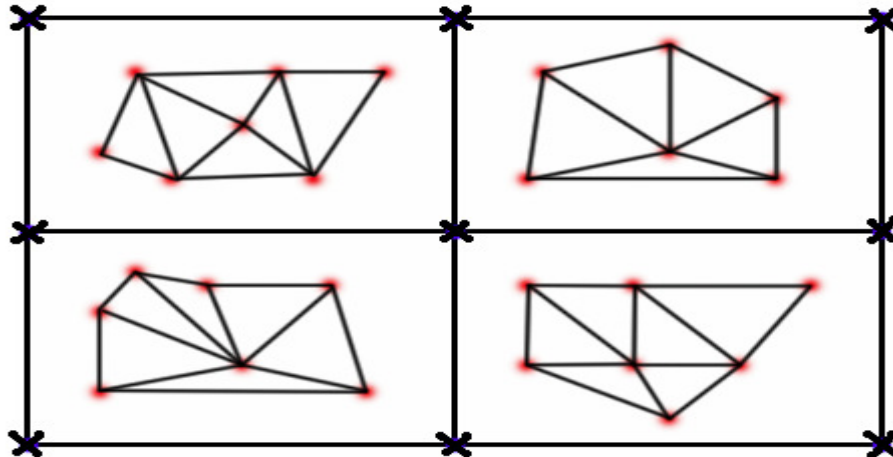


Fig. 13. Artificial points, shown by cross (x), added to merge the surface.

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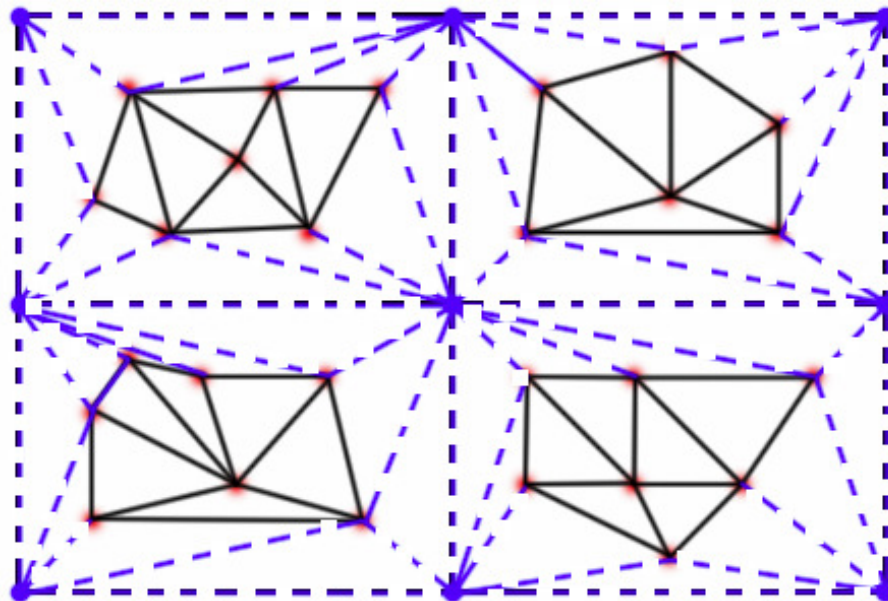


Fig. 14. A whole surface model merged with new dotted triangles.

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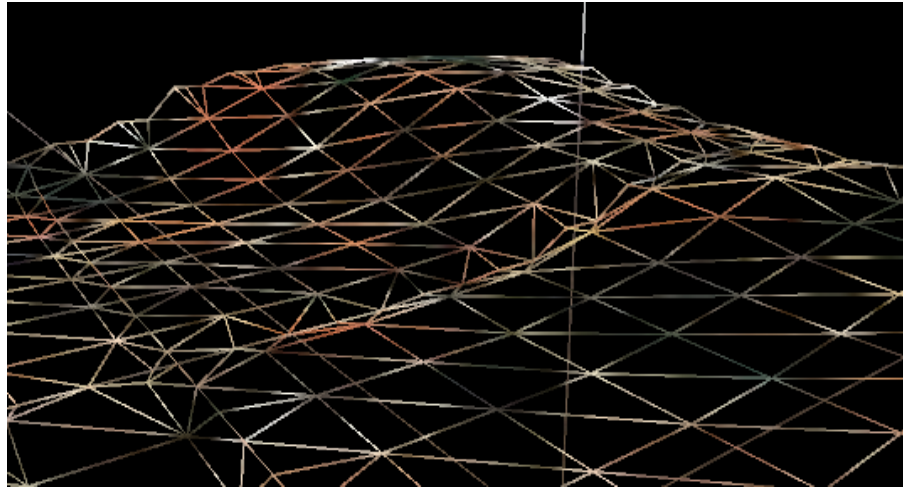


Fig. 15. Smooth view of whole surface model.

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Fig. 16. Textured model with continuous smooth transitions (upper) and without continuous smooth transitions (bottom) between surfaces.

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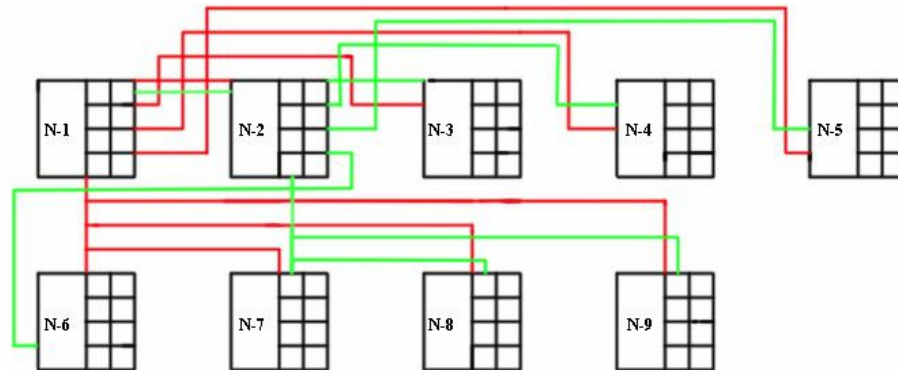


Fig. 17. Eight-Connected Linked List.

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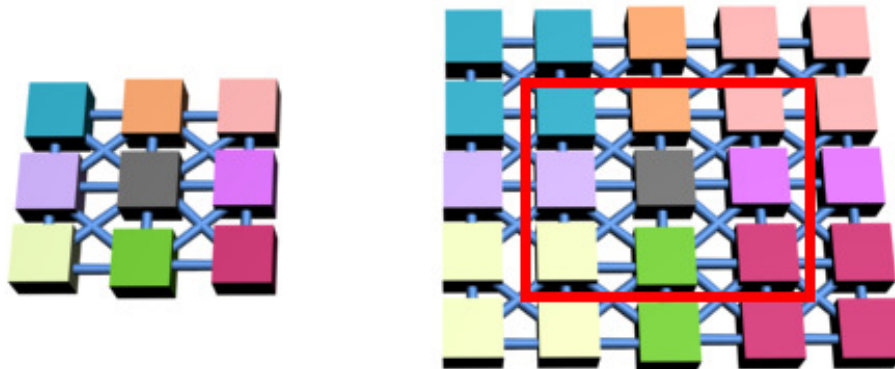


Fig. 18. Illustration of eight-connected linked list composed of Geo-Nodes.

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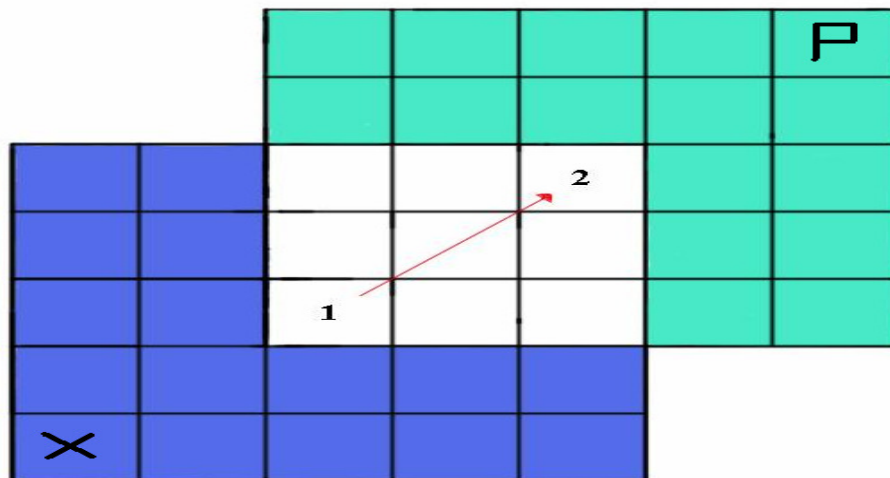
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**Fig. 19.** The DRP mechanism.[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[◀](#)[▶](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Printer-friendly Version](#)[Interactive Discussion](#)

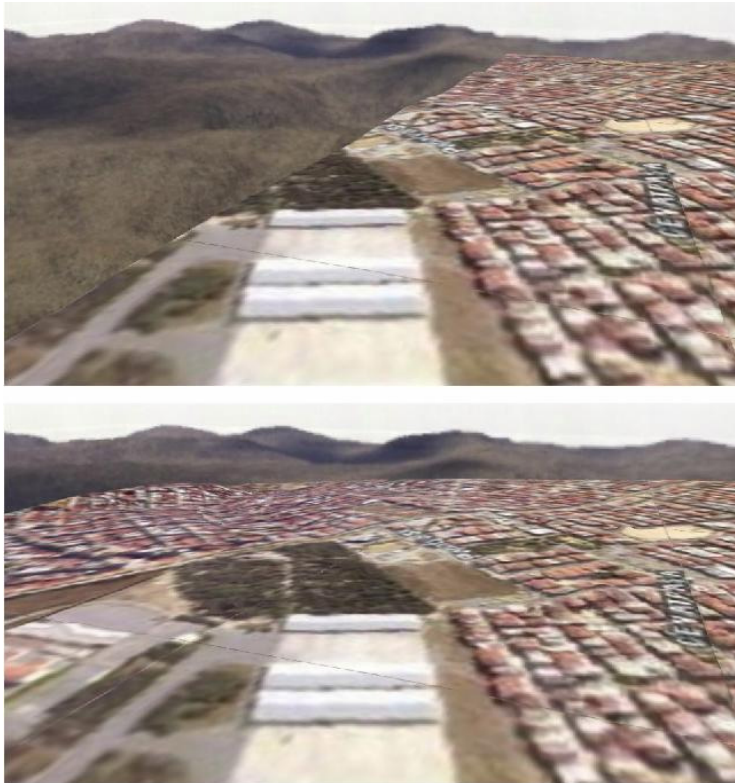


Fig. 20. Reconstruction of the model in the direction of the movement upon reaching the boundary of the surface at a specific time.

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The Number of Points	The Number of Polyhedron	Neighbourhood	The Size of the Satellite Image	FPS
10.000	25	2	1 MB	75–69
10.000	25	2	170 MB	75–63
10.000	100	2	1 MB	75–72
10.000	100	2	170 MB	75–66
10.000	100	3	1 MB	75–72
10.000	100	3	170 MB	75–64
100.000	25	2	1 MB	75–54
100.000	25	2	170 MB	75–39
100.000	100	2	1 MB	75–65
100.000	100	2	170 MB	75–43
100.000	100	3	1 MB	75–64
100.000	100	3	170 MB	75–61

Fig. 21. Performance results.

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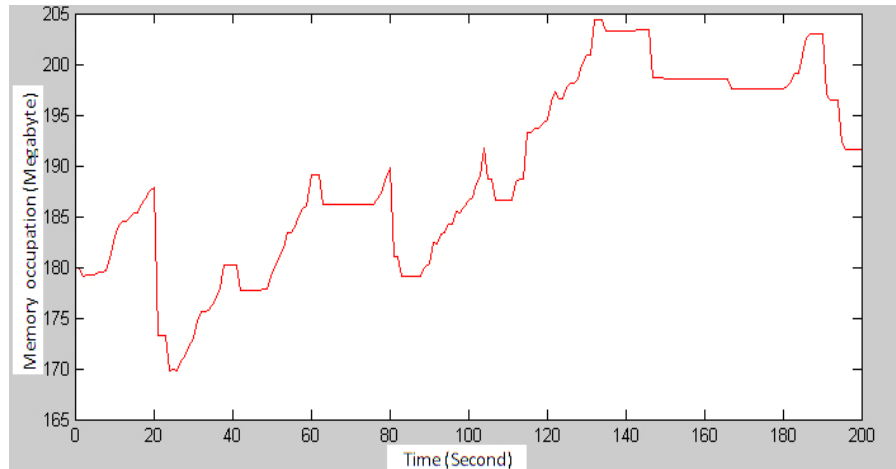
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**Fig. 22.** Memory usage (MB) vs. scene time (sec).[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[⏪](#)[⏩](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Printer-friendly Version](#)[Interactive Discussion](#)